



AGH UNIVERSITY OF SCIENCE
AND TECHNOLOGY

Part I: ADC fundamentals

Part II: SAR ADC design and tests

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Part I: ADC fundamentals

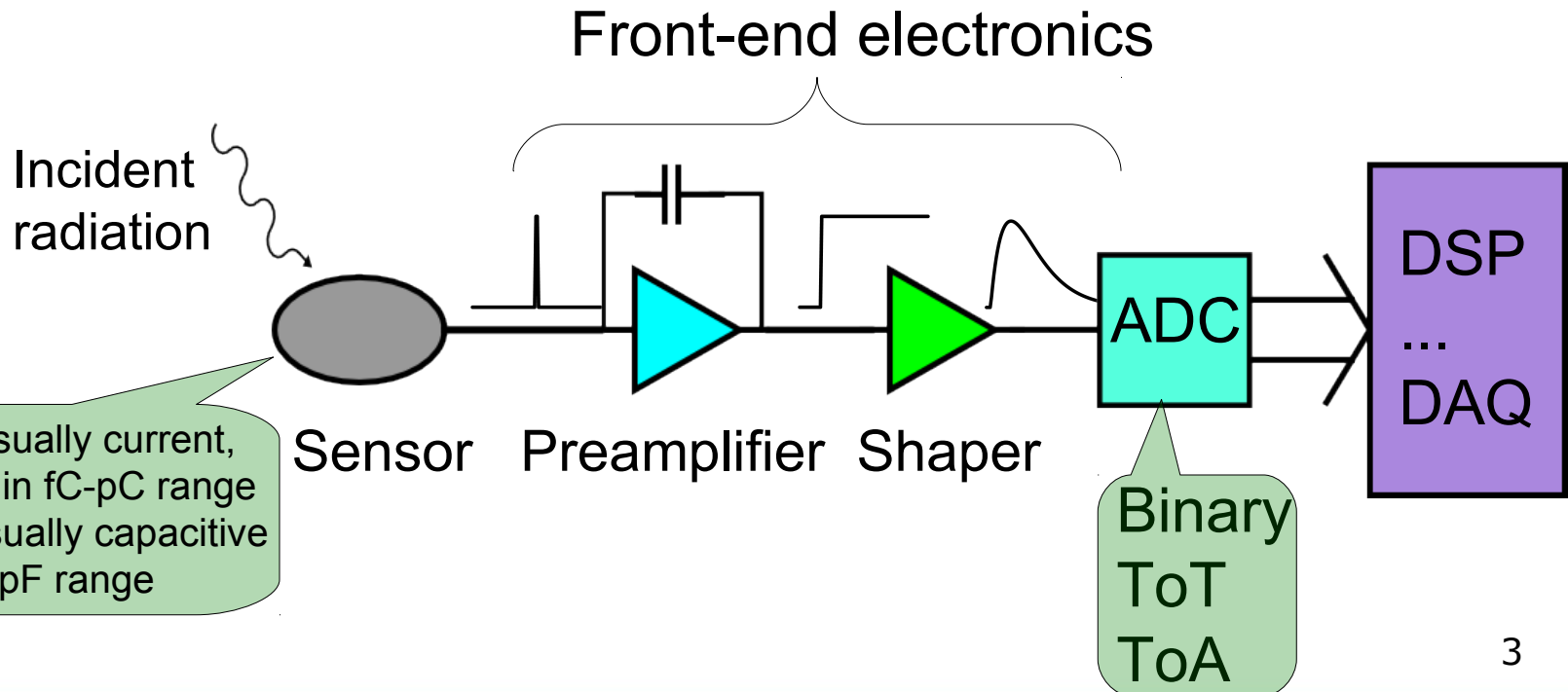
- Introduction
 - ADC fundamentals of operation
 - ADC errors
 - ADC testing
 - ADC architectures
 - ADC State of Art
 - Examples of multichannel ADC in HEP and commercial
- Many references to source articles are given throughout the presentation

Introduction

Readout electronics in HEP experiments

Readout electronics processes signals from sensors to measure:

- energy released by radiation ► amplitude measurements
- time of signal occurrence ► timing measurements
- position where the radiation hits the sensor ► tracking, imaging



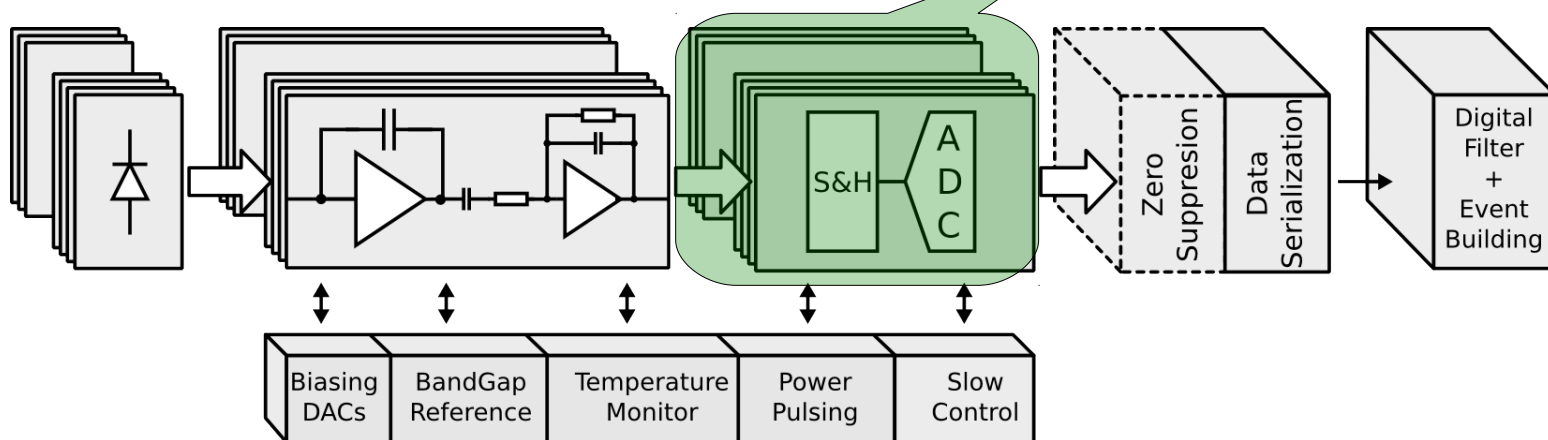
- Signal - usually current, its integral in fC-pC range
- Sensor usually capacitive in 0.1-100 pF range

Introduction

Motivation for low power ADC design

In older detector readout systems analog signals were sent out from the front-end ASIC and conversion was done externally by commercial ADC. This was because ADC power consumption was too high to place ADC in each readout channel. Of course the system performance was limited.

Main challenge – ADC power consumption!

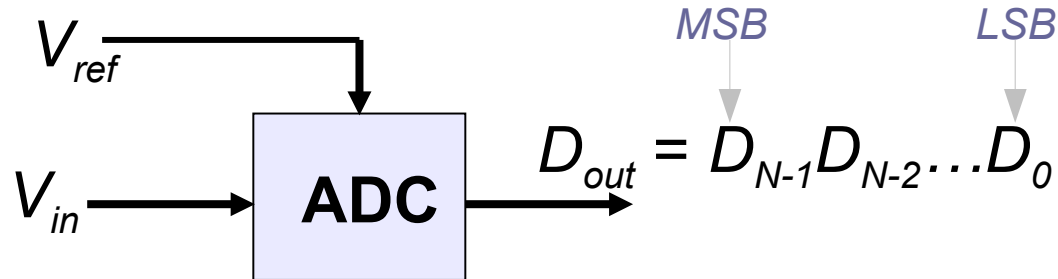


Multichannel readout system(ASIC) with efficient(DIGITAL) signal processing needs fast low-power ADC in each channel

Part I: ADC fundamentals

- Introduction
- **ADC fundamentals of operation**
- ADC errors
- ADC testing
- ADC architectures
- ADC State of Art
- Examples of multichannel ADC in HEP and commercial

ADC fundamentals



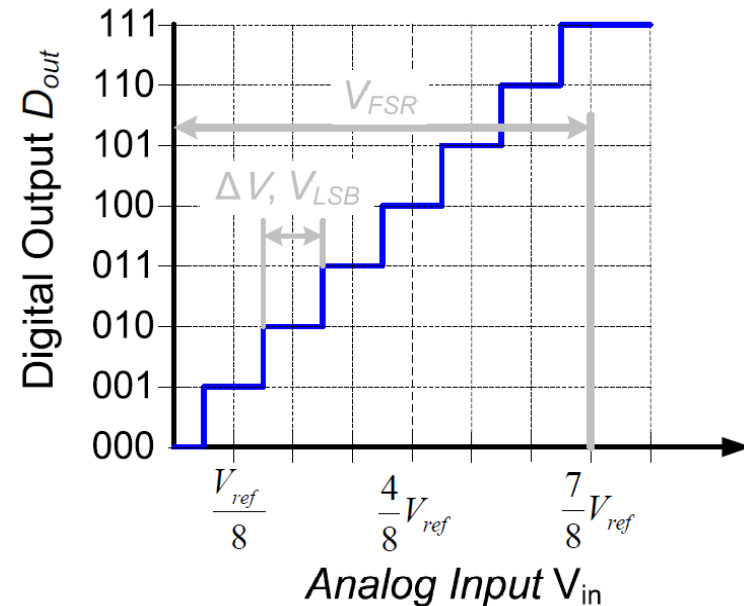
• **Resolution N:** number of bits used to represent in discrete way an analog signal

- 6 Bit = $2^6 = 64$ quantization levels,
- 10 Bit = $2^{10} = 1024$ quantization levels

• **Reference voltage V_{ref} :** Sets the input range. Analog input signal V_{in} is related to digital output signal D_{out} through V_{ref} with:

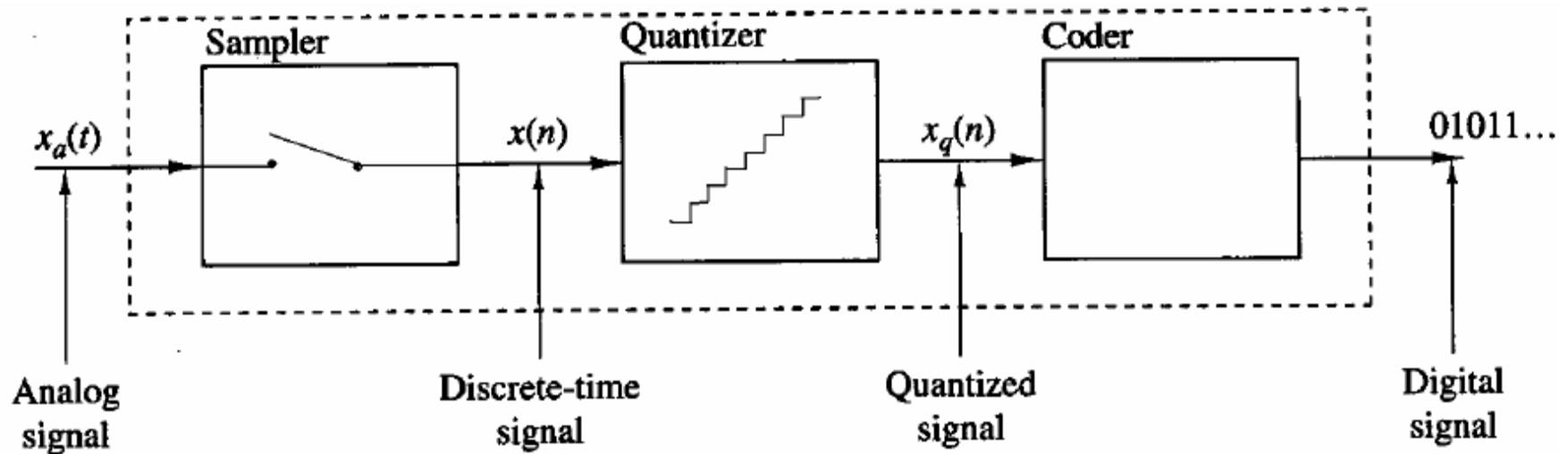
$$V_{in} = V_{ref} \cdot (D_{N-1} 2^{-1} + D_{N-2} 2^{-2} + \dots + D_0 2^{-N})$$

- Example: $N = 3$ Bit, $V_{ref} = 1V$, $D_{out} = '011'$
 $\Rightarrow V_{in} = 1V \cdot (2^{-2} + 2^{-3}) = 1V \cdot (0.25 + 0.125) = 0.375V$



ADC blocks&operations

- Sampler – samples the analog signal at discrete time intervals
- Quantizer approximates the sampled analog voltage to one of 2^N discrete levels
- Encoder – encodes the measurement in a convenient format



ADC operation fundamentals

Time discretization

Shannon Sampling Theorem: The sampling frequency should be at least twice the maximum frequency of the signal. If a continuous-time signal contains no frequencies higher than:

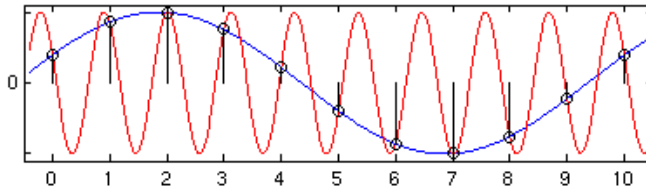
$$f_{max} < f_{sample} / 2 \quad (f_{sample} / 2: \text{Nyquist frequency})$$

,it can be completely determined by collected discrete samples.

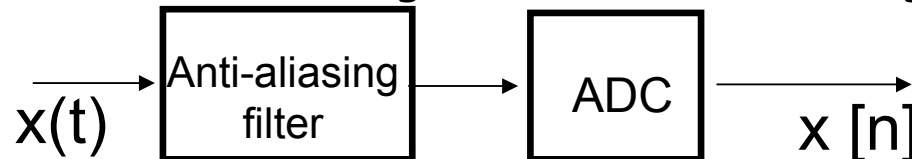
Example: Humans hear audio signals 20 Hz – 20 KHz. Audio CDs sample at 44.1 KHz

Aliasing: spurious low frequencies introduced by low sampling.

- Signals beyond $f_{sample} / 2$ are aliased to below $f_{sample} / 2$



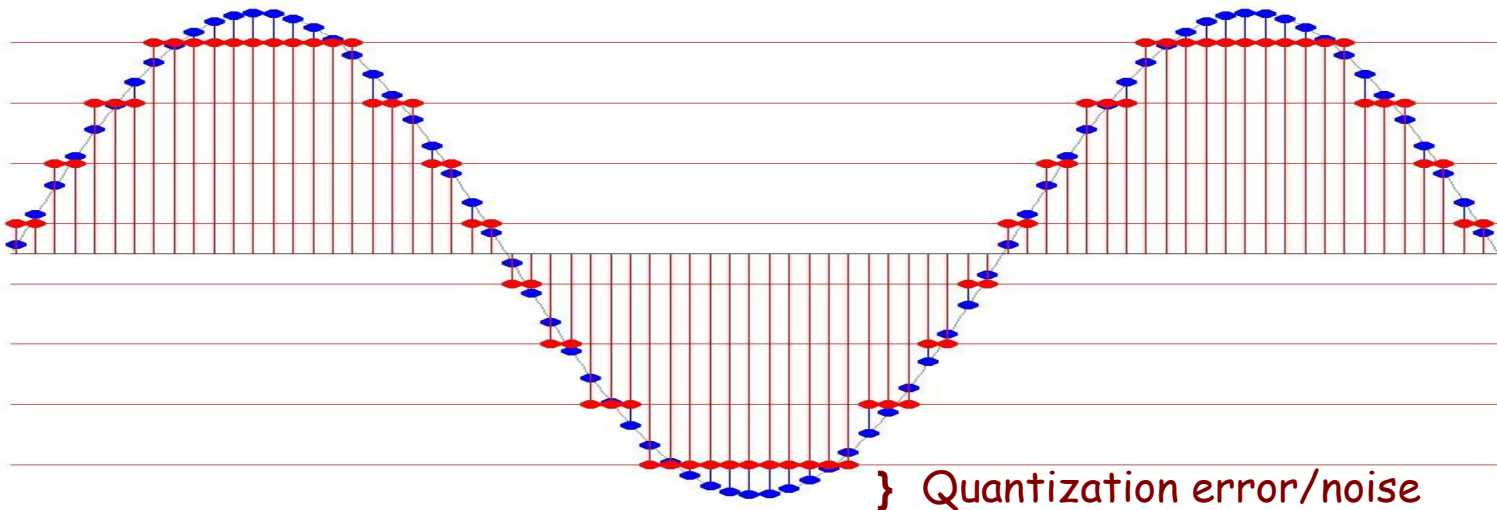
- Use anti-aliasing filter to avoid aliasing effects



ADC operation fundamentals

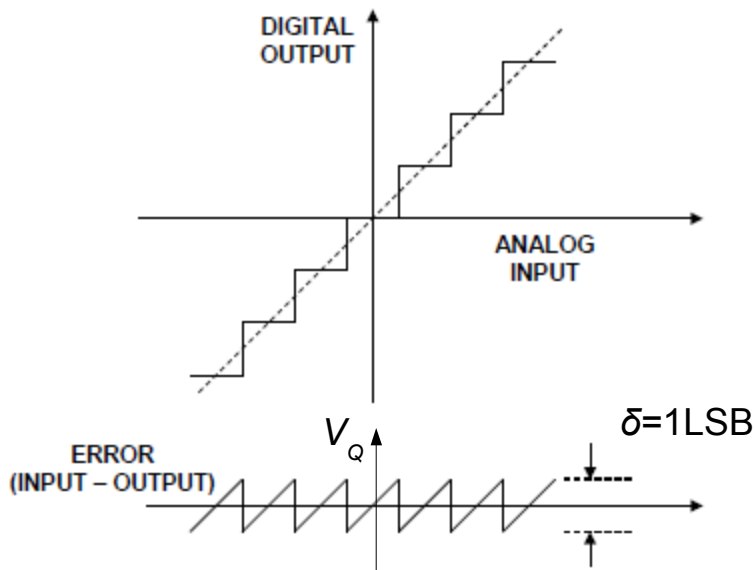
Amplitude discretization

- 1 bit → 2 possible values (comparator in binary systems)
- 8 bits → 256 possible values
- 10 bits → 1024 possible values
- N bits → 2^N possible values



Amplitude discretization for ideal ADC

Quantization error/noise



For N-bit converter $\delta = V_{FSR} / 2^N$

- Noise energy:

$$V_{Q(RMS)} = \sqrt{\frac{1}{\delta} \int_{-\delta/2}^{\delta/2} V_Q^2 dV_Q} = \sqrt{\frac{\delta^2}{12}}$$

- Signal energy:

$$V_{in(RMS)} = \frac{\delta \cdot 2^N}{2\sqrt{2}}$$

- SNR for ideal ADC:

$$SNR = 20 \log\left(\frac{V_{in(RMS)}}{V_{Q(RMS)}}\right)$$

$$SNR = 20 \log\left(2^N \cdot \sqrt{\frac{3}{2}}\right)$$

$$SNR = 6.02 \times N + 1.76 [dB]$$

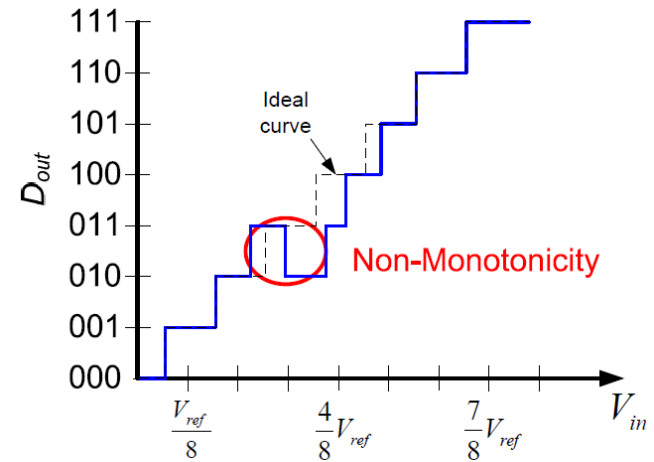
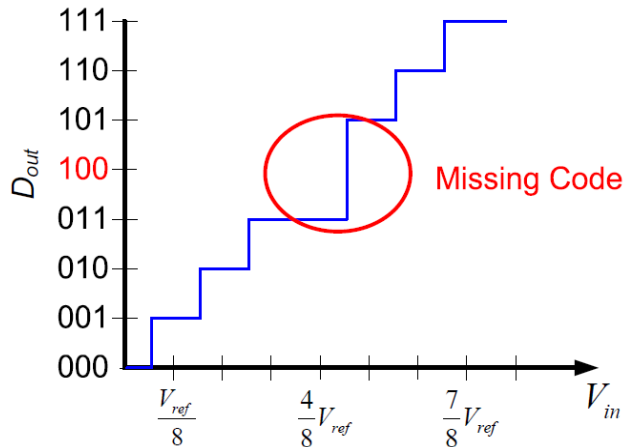
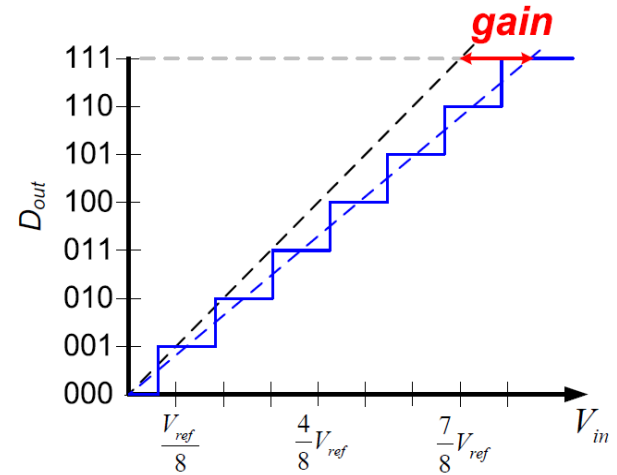
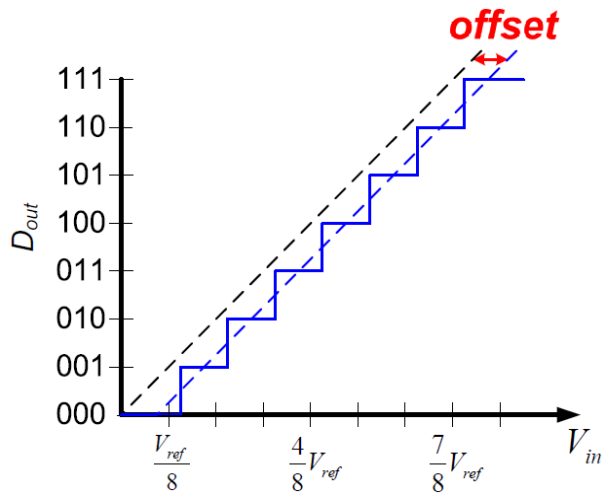
or

$$N = \frac{SNR [dB] - 1.76}{6.02}$$

Part I: ADC fundamentals

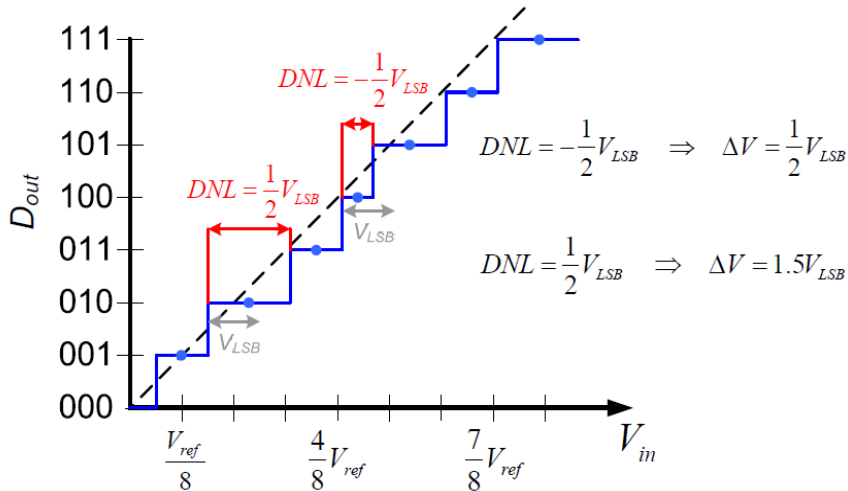
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ADC errors

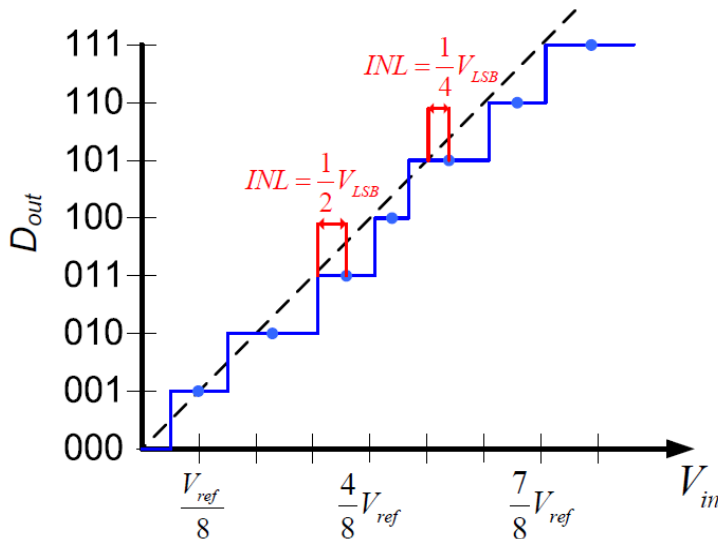


ADC errors

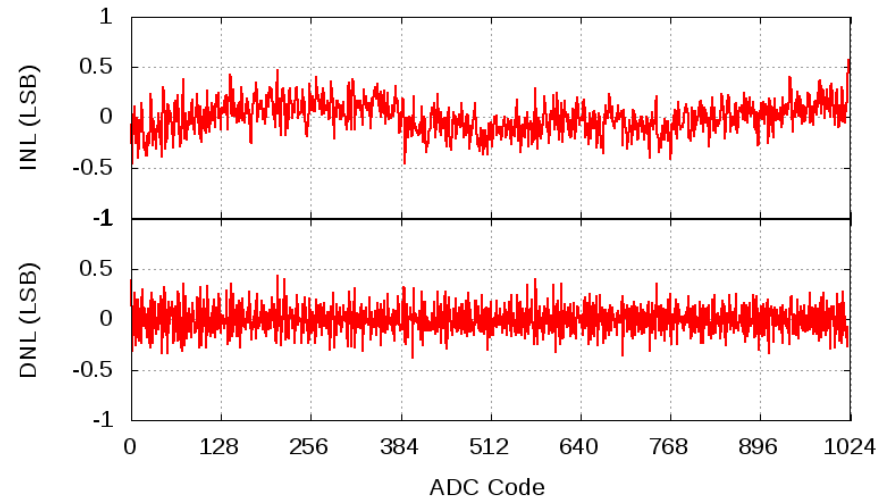
Static NonLinearity errors



- **DNL** - Differential NonLinearity - the difference between an actual step width and the ideal step width
- **INL** - Integral NonLinearity - deviation of an actual transfer function from a straight line (integrated DNL)

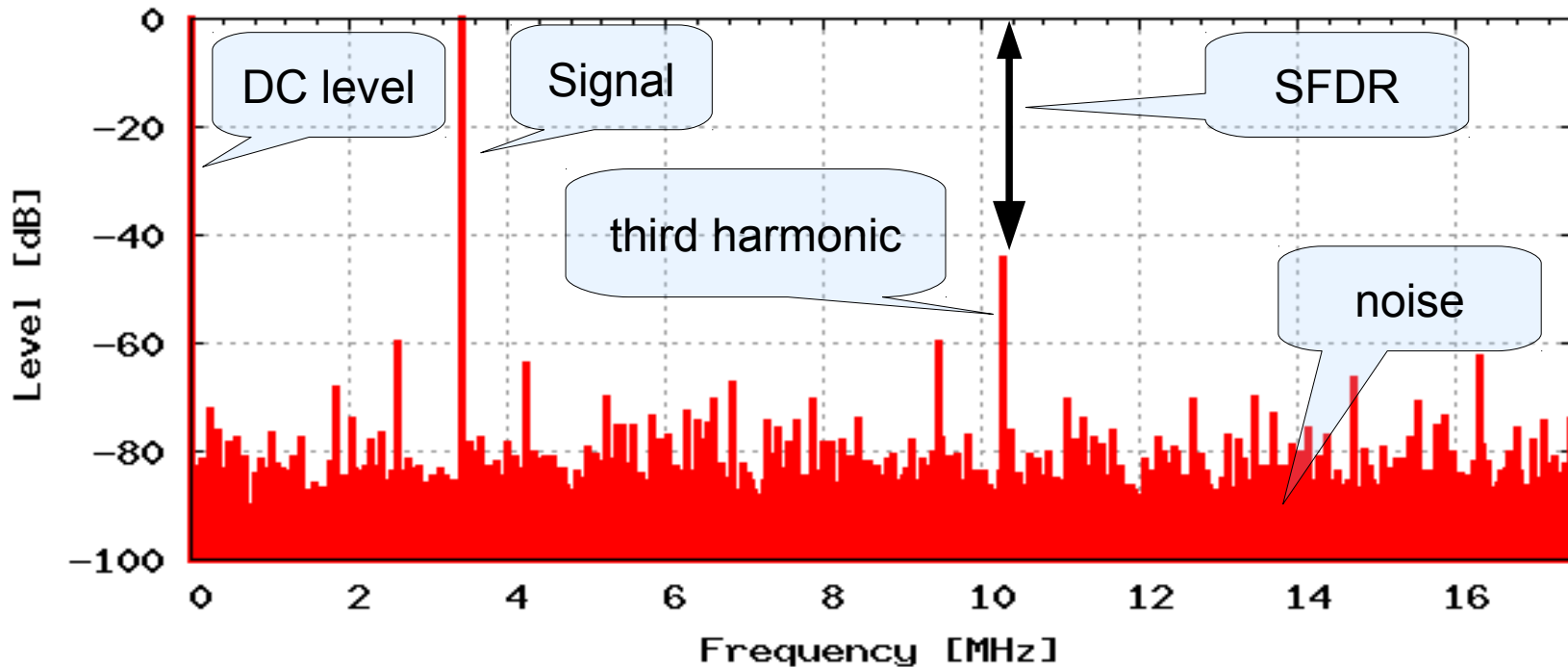


Example of INL/DNL for 10-bit ADC



ADC dynamic Dynamic errors

- Single tone, full scale sine wave applied to input of the ADC
- Fourier Transform computed from the collected digital samples



- **SNHR** – Signal to Non Harmonic Ratio
- **THD** – Total Harmonic Distortions

- **SFDR** – Spurious Free Dynamic Range
- **SINAD/SNDR** – Signal to Noise and Distortions

ADC errors

Calculation of dynamic errors

From DFT histogram collected with single tone sine input all dynamic parameters (usually expressed in dB) can be calculated:

$$SNHR = 20 \log_{10} \sqrt{\frac{X_{sine}^2}{\sum_{k=1, k \neq sine, k \neq harmonics}^{N/2} X_k^2}}$$

$$-THD = 20 \log_{10} \sqrt{\frac{X_{sine}^2}{\sum_{k=harmonics}^{10} X_k^2}}$$

$$SINAD/SNDR = 20 \log_{10} \sqrt{\frac{X_{sine}^2}{\sum_{k=1, k \neq sine}^{N/2} X_k^2}}$$

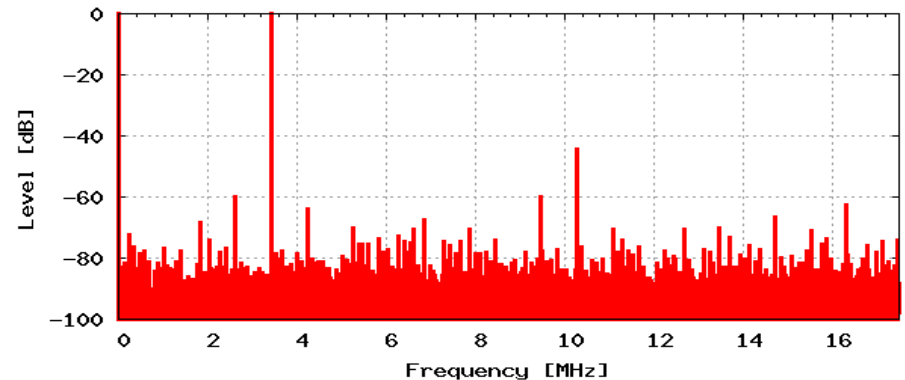
$$SFDR = 20 \log_{10} \sqrt{\frac{X_{sine}^2}{X_{highest\ spur}^2}}$$

For ideal ADC with NO harmonic distortion and NO noise only quantization error/noise exists and so its resolution:

$$N = \frac{SNR [dB] - 1.76}{6.02}$$

For realistic ADC the Effective Number Of Bits – ENOB – can be measured/calculated

$$ENOB = \frac{SINAD [dB] - 1.76}{6.02}$$



Aperture jitter

Resolution vs aperture jitter error

$$V_{IN}(t) = V_A \times \sin(2\pi \times f_{IN} \times t)$$

$$\frac{dV_{IN}(t)}{dt} = 2\pi \times f_{IN} \times V_A \times \cos(2\pi \times f_{IN} \times t)$$

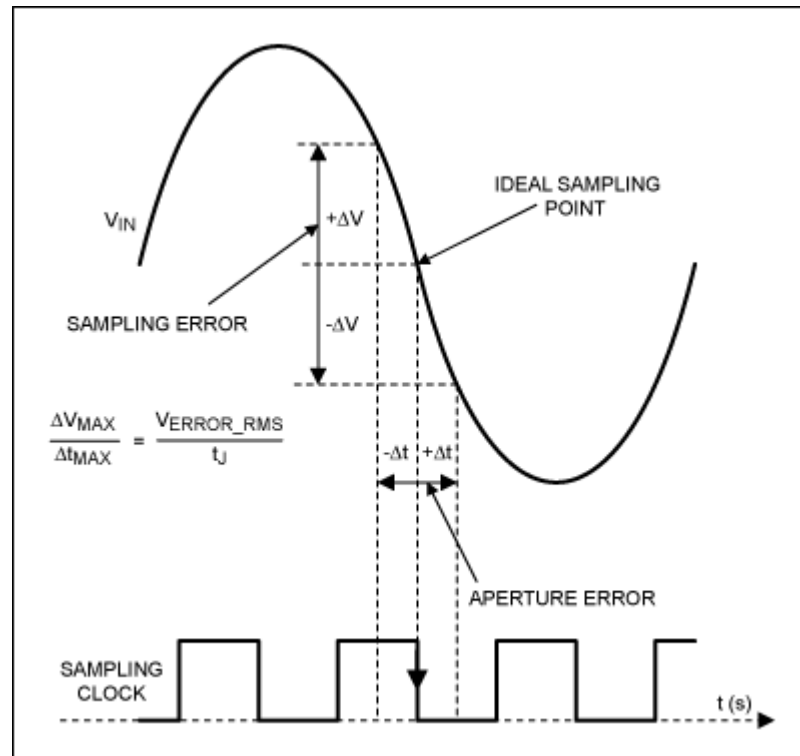
$$\left. \frac{dV_{IN}(t)}{dt} \right|_{RMS} = \frac{2\pi \times f_{IN} \times V_A}{\sqrt{2}}$$

$$\frac{V_{ERROR_RMS}}{t_J} = \frac{2\pi \times f_{IN} \times V_A}{\sqrt{2}}$$

t_J -time jitter

$$V_{ERROR_RMS} = \frac{2\pi \times f_{IN} \times V_A \times t_J}{\sqrt{2}}$$

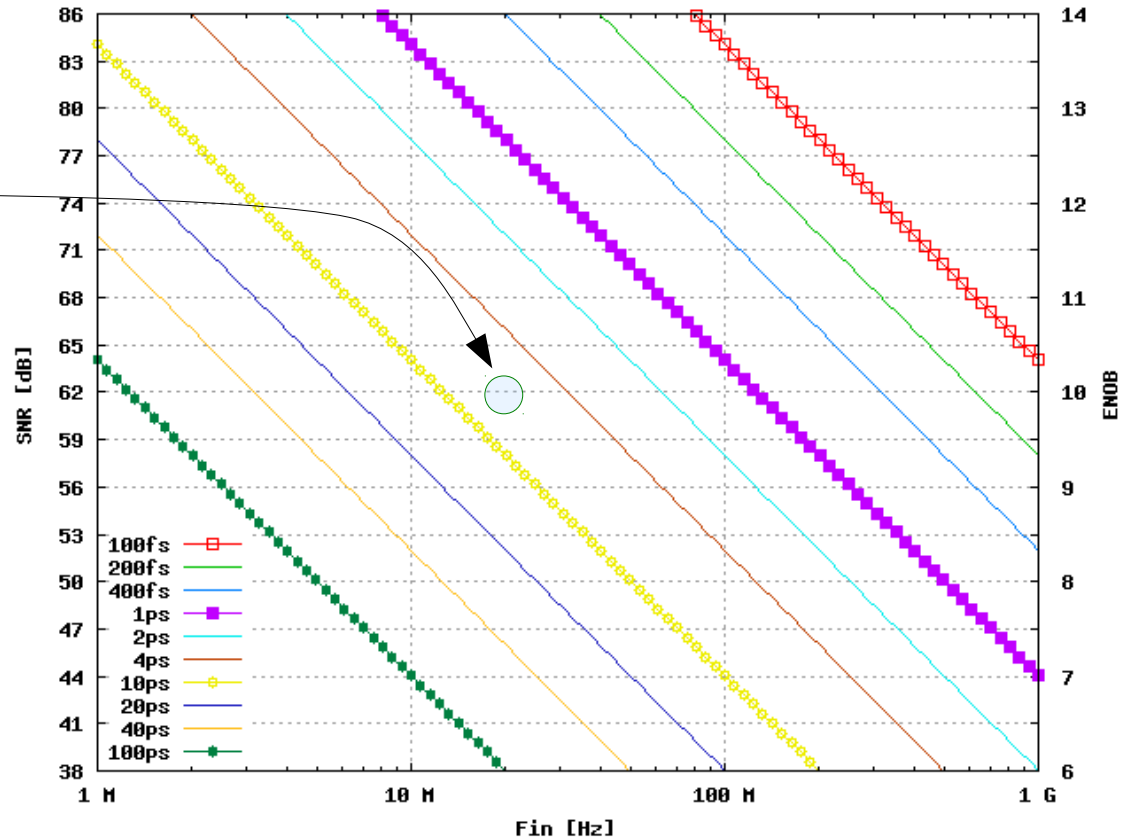
$$SNR = 20 \log_{10} \left[\frac{V_{IN_RMS}}{V_{ERROR_RMS}} \right] = 20 \log_{10} \left[\frac{V_A / \sqrt{2}}{2\pi \times f_{IN} \times V_A \times t_J / \sqrt{2}} \right]$$



Aperture jitter

Resolution vs aperture jitter error

For 10-bit ADC sampling at 40 MHz a Nyquist rate (20MHz) signal the aperture jitter error should be significantly less than 10ps to obtain full 10-bit resolution



Aperture jitter worsens the ENOB and so need to be minimized according to the required resolution.

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ADC testing

If you have any doubt on
ADC test procedure or
formula needed, please
consult
The IEEE Standard 1241

IEEE STANDARDS ASSOCIATION



IEEE Standard for Terminology and Test Methods for Analog-to-Digital Converters

IEEE Instrumentation & Measurement Society

Sponsored by the
Waveform Generation Measurement and Analysis Technical Committee

IEEE
3 Park Avenue
New York, NY 10016-5997
USA

IEEE Std 1241™-2010
(Revision of
IEEE Std 1241-2000)

14 January 2011

ADC testing

Static linearity errors DNL/INL

Linearity errors measurements are usually done using histogram (code density) method. In this method a well defined input signal with uniform probability density function (like ramp) is applied to the ADC input and the histogram with number of occurrences $h(k)$ of each ADC code is done.

From this histogram the DNL is calculated for all codes (except the first and last):

$$DNL(k) = \frac{h(k)_{ACTUAL}}{h(k)_{THEORETICAL}} - 1$$

INL is simply the integral of DNL values

$$DNL(n) = \sum_{k=1}^n DNL(k)$$

ADC testing

Theory of dynamic measurements



Input signal
 S_i

ADC transfer function
 T_{ADC}

Output data
 $O_D = S_i \cdot T_{ADC}$

Discrete Fourier Transform (DFT) of output data

$$F(x_n): X_k = \sum_{i=0}^N x_n \exp\left(\frac{-i2\pi kn}{N}\right)$$

$$f_{base} = \frac{f_{sample}}{N}$$

$$F(O_D) = F(S_i \cdot T_{ADC}) = F(S_i) \otimes F(T_{ADC})$$

$$S_i = \sin(kf_{base}) \Rightarrow F(\sin(kf_{base})) = \delta_k$$

$$F(S_i) \otimes F(T_{ADC}) = \delta_k \otimes F(T_{ADC}) = F(T_{ADC})$$

If input signal is pure sine wave with frequency equal to the one of DFT fundamental frequencies, deconvolution is straightforward since DFT of input signal is Kronecker delta 22

Very important !
(otherwise a leak to whole spectrum appears)

ADC testing

Theory of dynamic measurements

DFT of ADC transfer function → spectrum for given sampling frequency and input sine frequency

$$F(T_{ADC}) = f(f_{sample}, f_{sine})$$

Sampling Rate = 40.0 MHz
 Input Freq = 3.916 MHz
 Harmonics = 10

SINAD = 57.0 dB
 THD = -69.6 dB
 SNHR = 57.3 dB
 SFDR = 74.6 dB

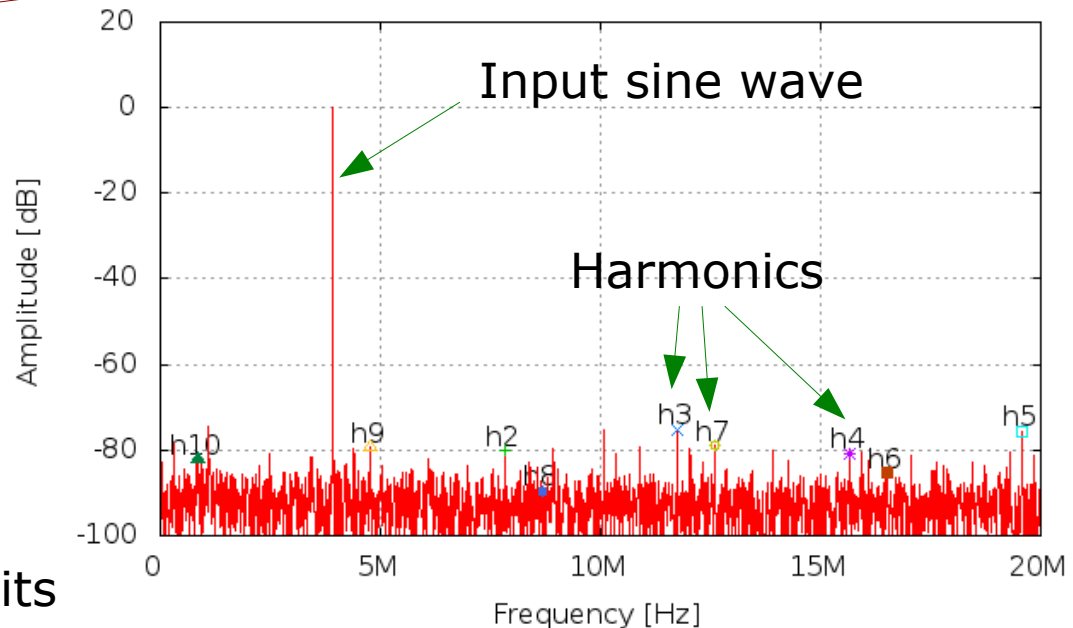
Dynamic metrics calculated from obtained DFT, i.e.:

- **SINAD** – signal to noise and distortion (harmonics) ratio

$$SINAD = 20 \log_{10} \sqrt{\frac{X_{sine}^2}{\sum_{k=1, k \neq sine}^{N/2} X_k^2}}$$

- **ENOB** – effective number of bits

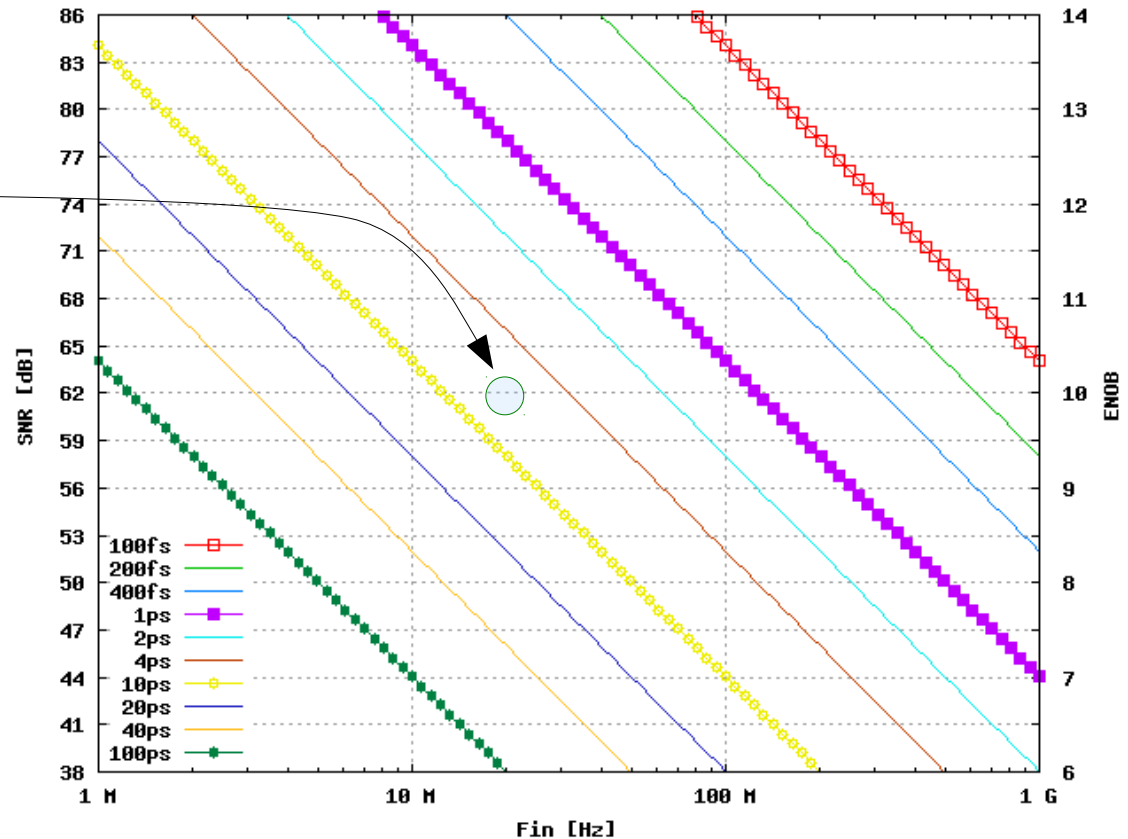
$$ENOB = \frac{SINAD - 1.76}{6.02}$$



ADC testing

Resolution vs sampling clock jitter

For 10-bit ADC sampling at 40 MHz a Nyquist rate (20MHz) signal the phase jitter of sampling clock should be significantly less than 10ps to obtain full 10-bit resolution



Phase jitter of sampling clock affects the ADC resolution in the same way as ADC aperture jitter. A low jitter generator is needed for ADC testing.

ADC testing Measurements setup

DFT and data analysis –
custom software

Differential function
generator – Agilent 81160A



Power supply



Input
sine

Sample
clock

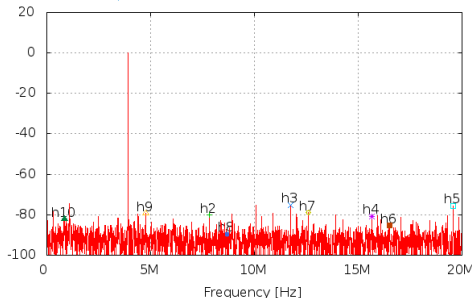
Results

Sampled data
(low bitrate)

Sampled data
(high bitrate)

Sampling Rate = 40.0 MHz
Input Freq = 3.916 MHz
Harmonics = 10

SINAD = 57.0 dB
THD = -69.6 dB
SNR = 57.3 dB
SFDR = 74.6 dB



DAQ – receive fast transmission from ADC (up to 500Mb/s), store the assumed amount of data (ie. 4096 samples) and sends to PC via Ethernet for offline analysis.

ADC testing Measurement setup – main board

DAQ (VIRTEX-5 FPGA)

ADC bias and power supply

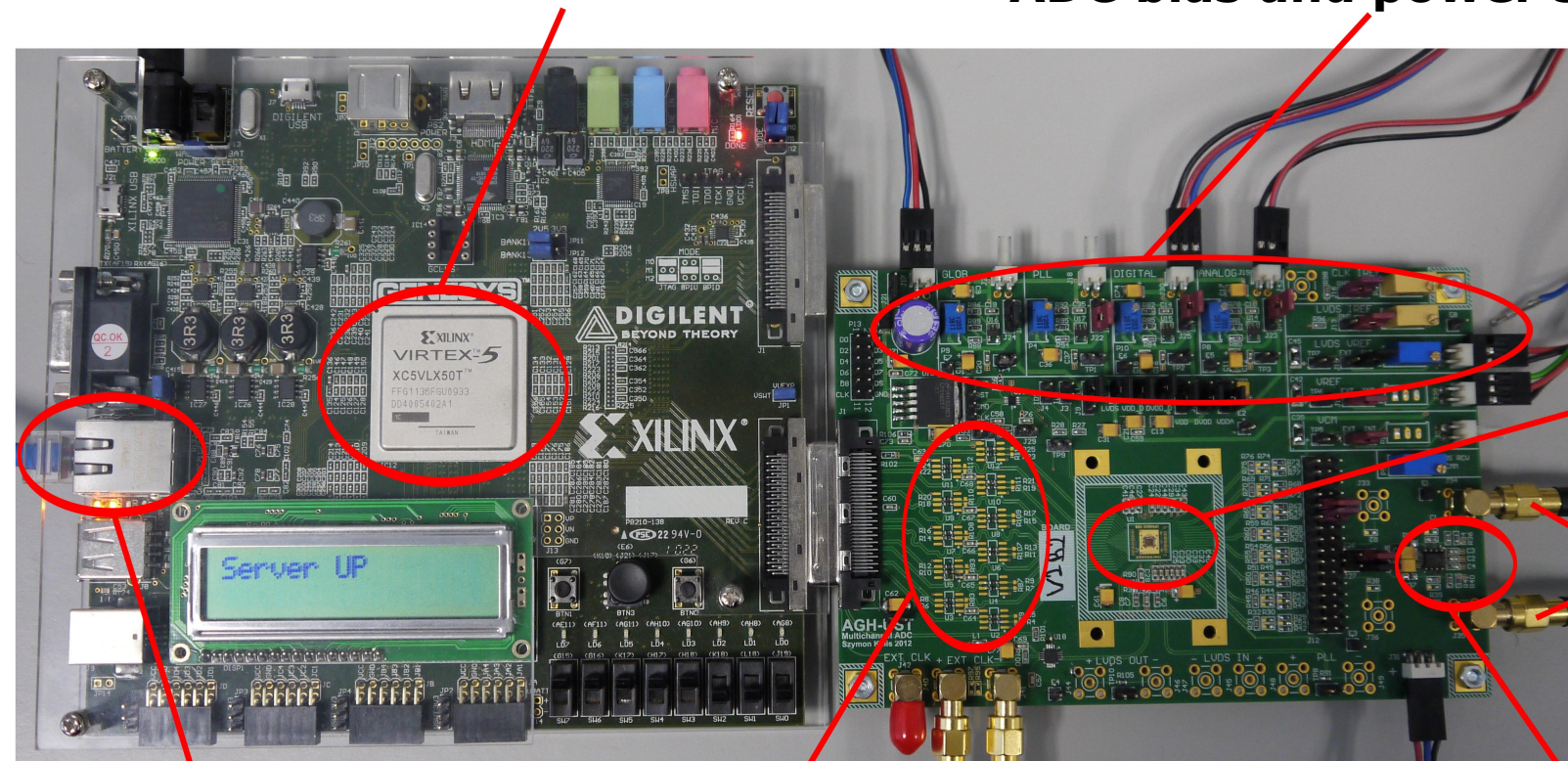
**10b SAR
ADC**

**Input
sine**

**PC data link
(Ethernet)**

**ADC output data -
parallel or serial (SLVS)**

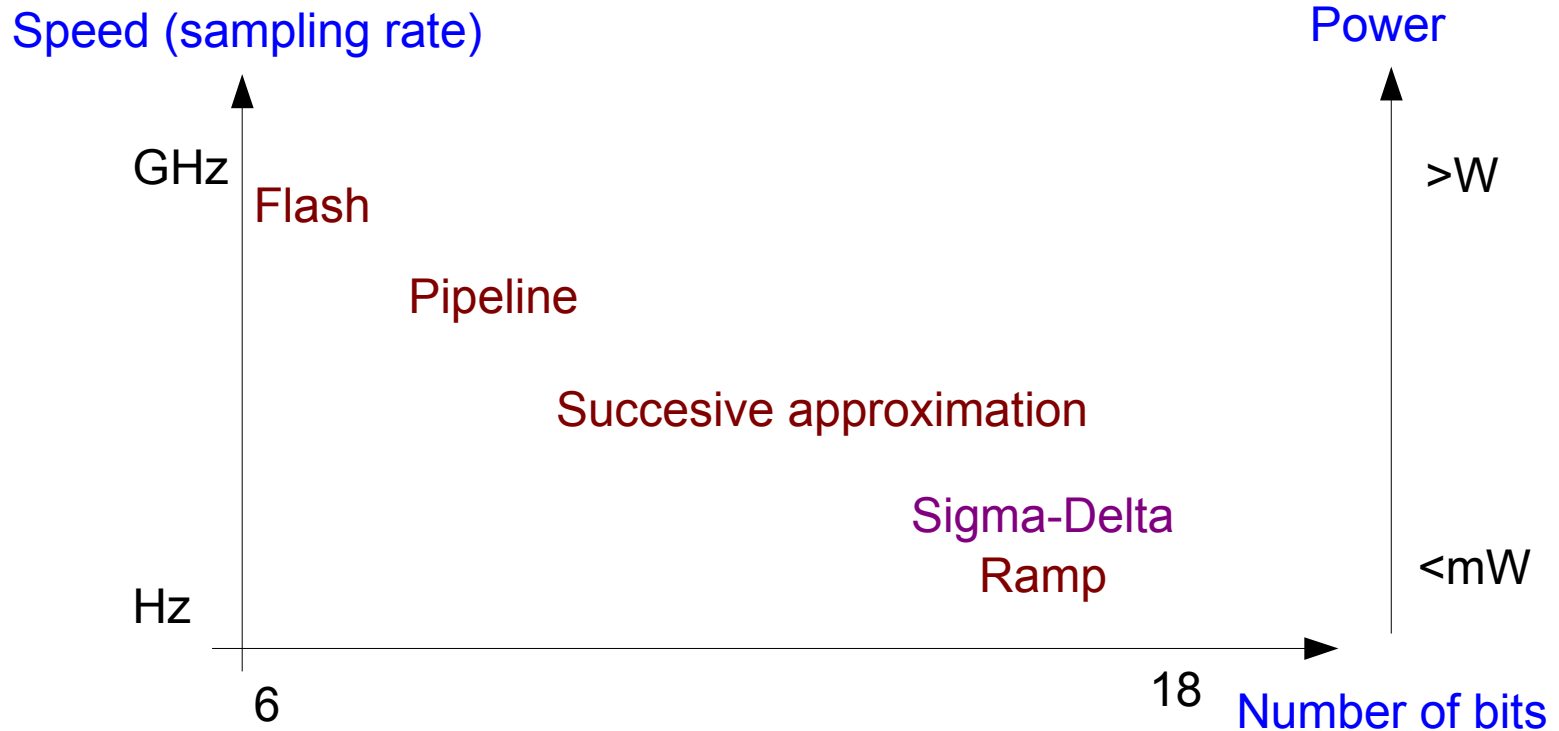
**Input differential
low pass filter**



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ADC architectures

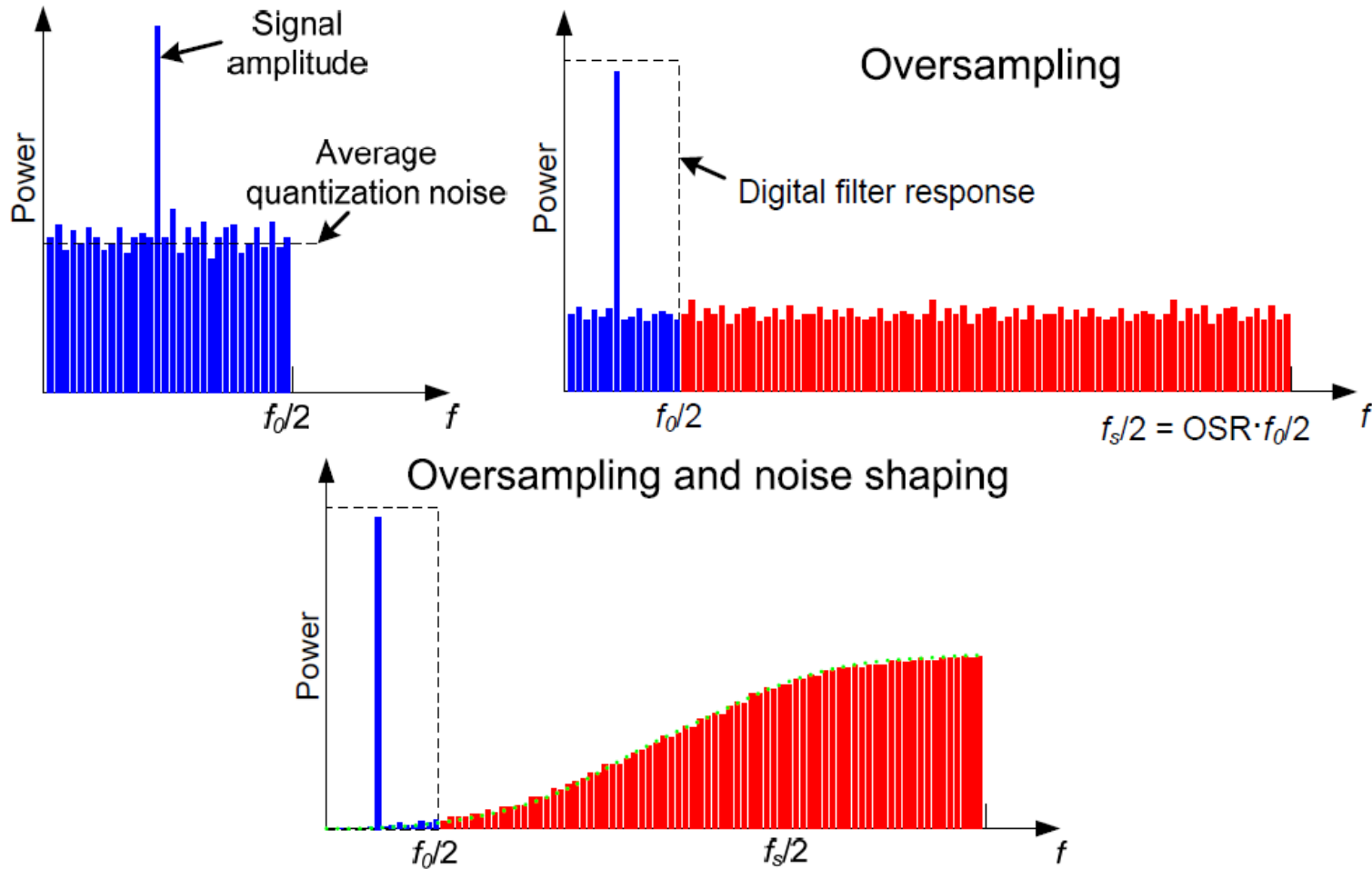


Nyquist rate ADCs ($f_{\text{signal}}^{\text{max}} \sim 0.5 f_{\text{sample}}$): Flash, Pipeline, SAR, Ramp, etc...

Oversampling ADCs ($f_{\text{signal}}^{\text{max}} \ll 0.5 f_{\text{sample}}$): Sigma-Delta

ADC architectures

Sigma-Delta



Thanks to Oversampling and Noise Shaping lowest noise (highest resolution >20-bit) can be obtained in Sigma-Delta converters

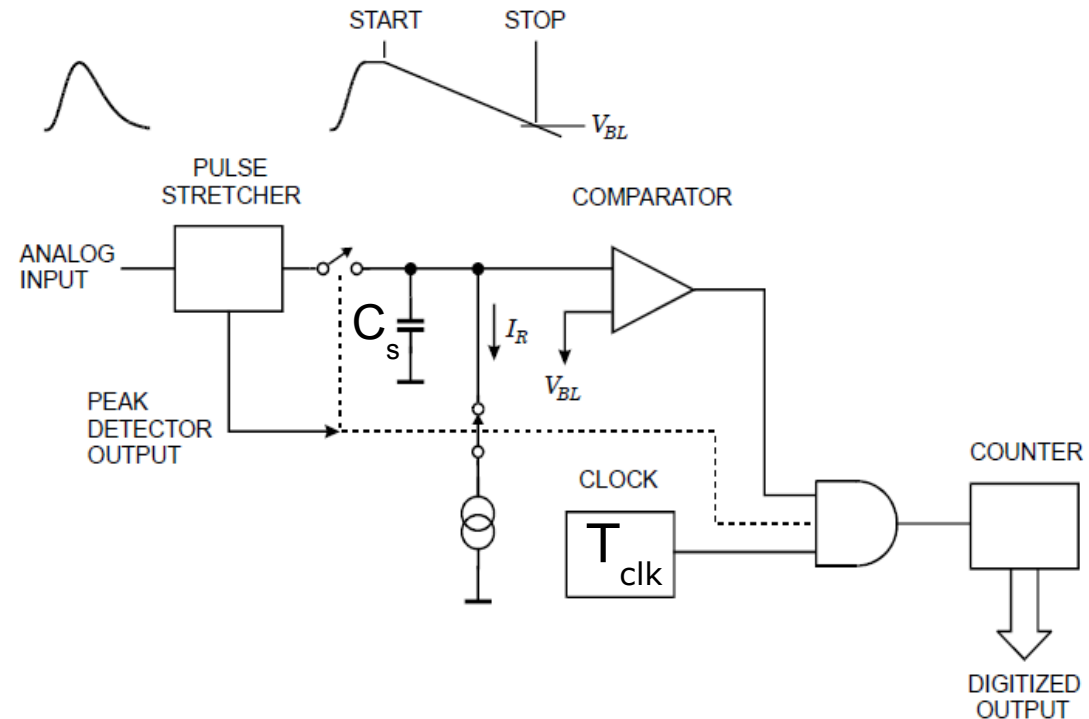
ADC architectures

Slow (ramp) Wilkinson ADC

Wilkinson ADC is often used in detector readout

When sampling capacitance C_s is charged:

- Stretcher disconnected
- Current source switched on and counter started
- Constant current discharging
- Counter stopped when comparator indicates that voltage on the capacitor reached the baseline

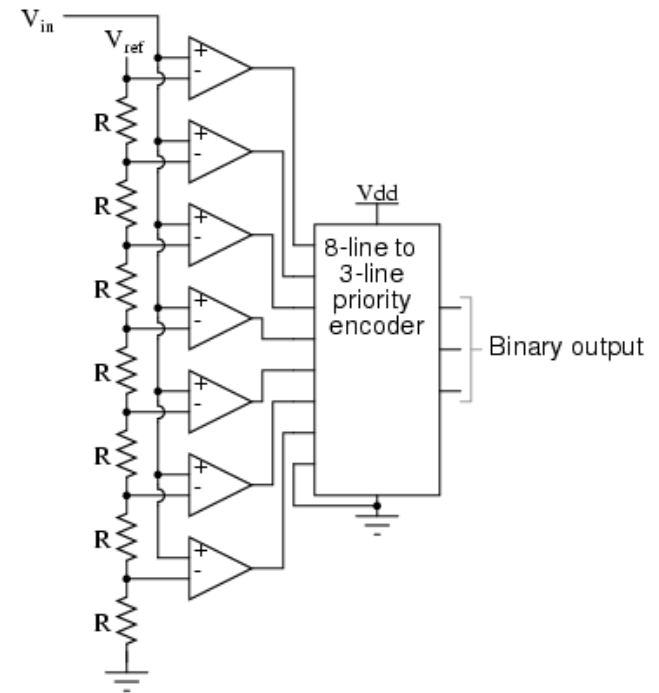


Advantages: high resolution, linearity, low power

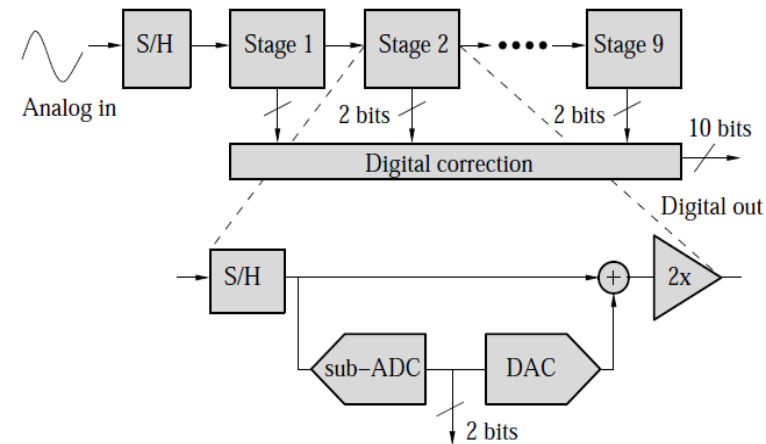
Drawback: slow conversion $T_{conv} \sim T_{clk} * 2^{N-bit}$

- Flash Architecture
 - Output rate = Clock rate
 - For N-bits need $\sim 2^N$ comparators&resistors
 - High power consumption
 - Large area
 - Good for low resolution systems ($< \sim 6$ bit)

3-bit Flash ADC example

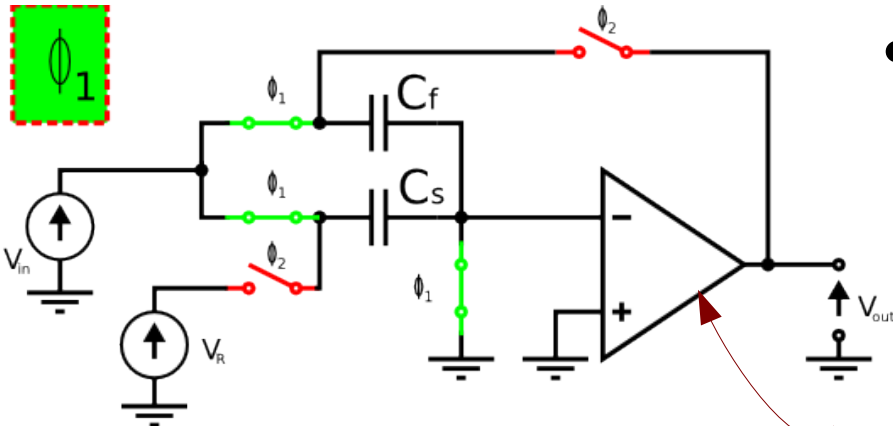


- Pipeline architecture
 - Output rate = Clock rate (latency time)
 - For N-bit resolution $\sim N$ same pipeline stages (often more than 1-bit per stage is converted) are working concurrently
 - Medium power consumption
 - Medium size
 - Usually up to ~ 12 -bits resolution
 - Very popular architecture (also in HEP detector readouts)



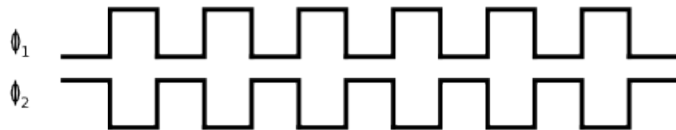
ADC architectures

Fast ADC – Pipeline stage operation



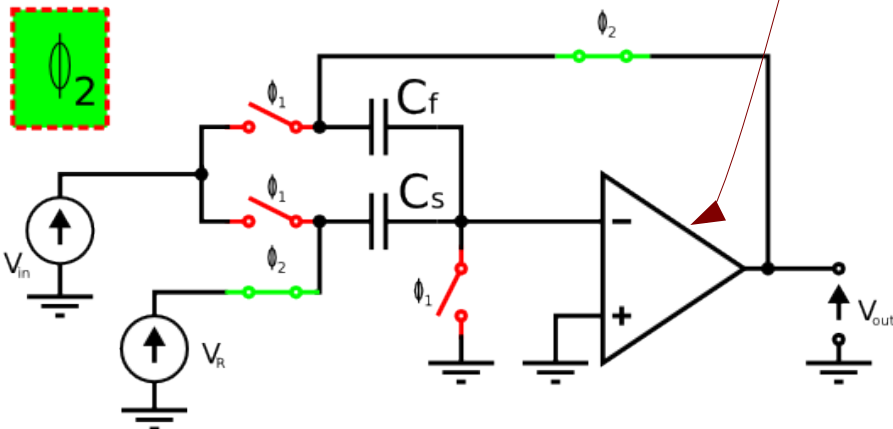
- phase ϕ_1 : sample & hold

$$V_{cf} = V_{cs} = V_{in}$$



OpAmp- Main power

- phase ϕ_2 : add & multiply

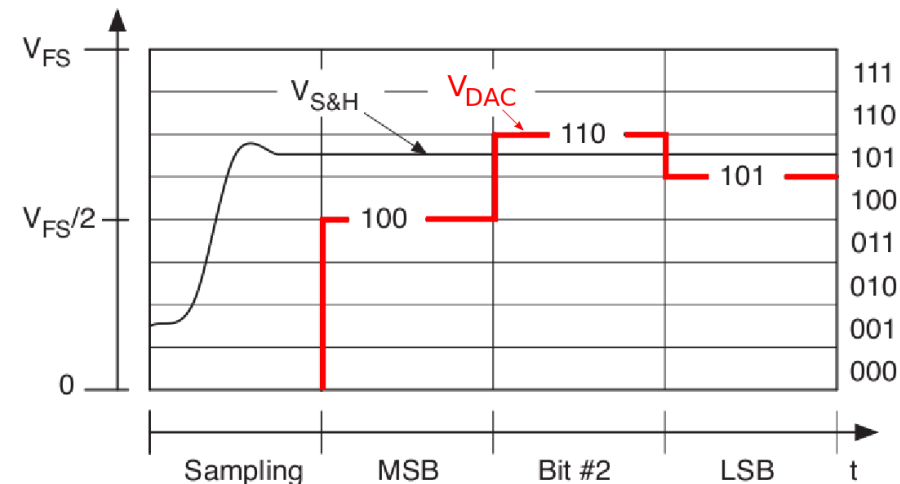
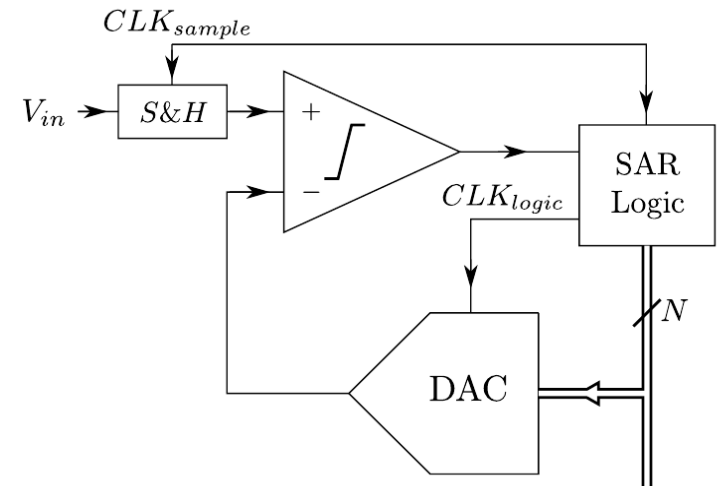


$$V_{out} \simeq V_{in} \left(1 + \frac{C_s}{C_f} \right) - V_R \left(\frac{C_s}{C_f} \right)$$

ADC architectures

Medium speed ADC – SAR (Successive Approximation Register) ADC

- SAR architecture
 - Output rate \sim Clock rate/N
 - For N-bits only one stage
 - Very low power
 - Very small area
 - Usually up to \sim 12-bits
 - In modern CMOS $< 200\text{nm}$
 - $f_{\text{sample}} \sim 100\text{MS/s}$ possible
 - ultra low power, like $\sim 1\text{mW}$ at 50MS/s for 10-bit ADC possible



Will be discussed in next lecture...

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How to compare ADC performance ? “Classic” Walden FOM

- Various features/parameters are important in ADC design/applications: effective resolution (ENOB), power, sampling frequency, area, etc... and can be used to create the “Figure Of Merit” (FOM) for ADC
- The first and most commonly used in various publications is the so called Walden FOM:

$$FOM = \frac{Power}{f_{sample} * 2^{ENOB}} [J / conv.]$$

- Since it is not “perfect” (does not account for all features), there are also other FOMs, but this one is most commonly used

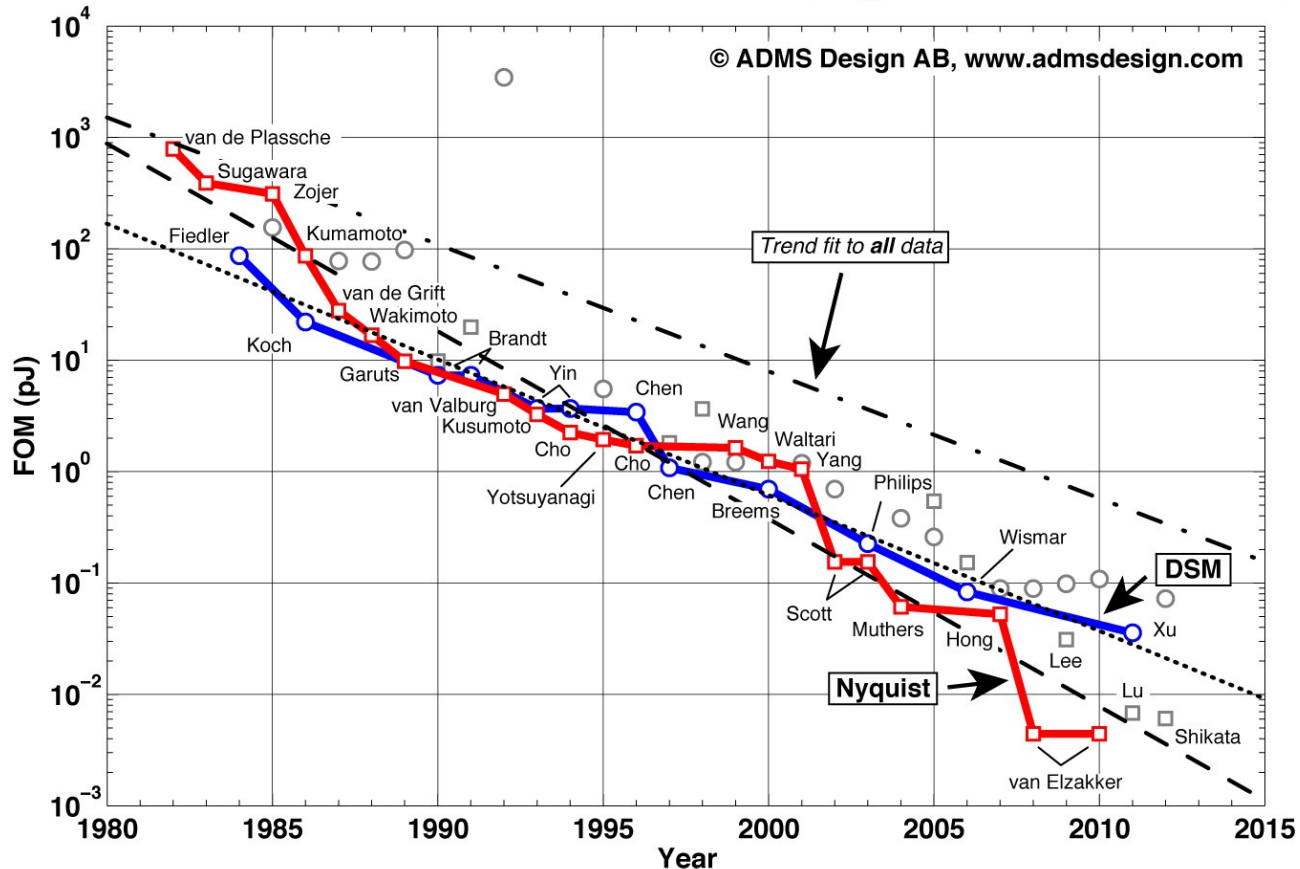
R. H. Walden, “Analog-to-digital converter technology comparison,” in Proc. of GaAs IC Symp., pp. 228–231, Oct., 1994.

R. H. Walden, “Analog-to-digital converter survey and analysis,” IEEE J. Selected Areas in Communications, no. 4, pp. 539–550, Apr. 1999.

ADC State of Art

Walden FOM evolution in time

$$FOM = \frac{Power}{f_{sample} * 2^{ENOB}} [J/conv.]$$

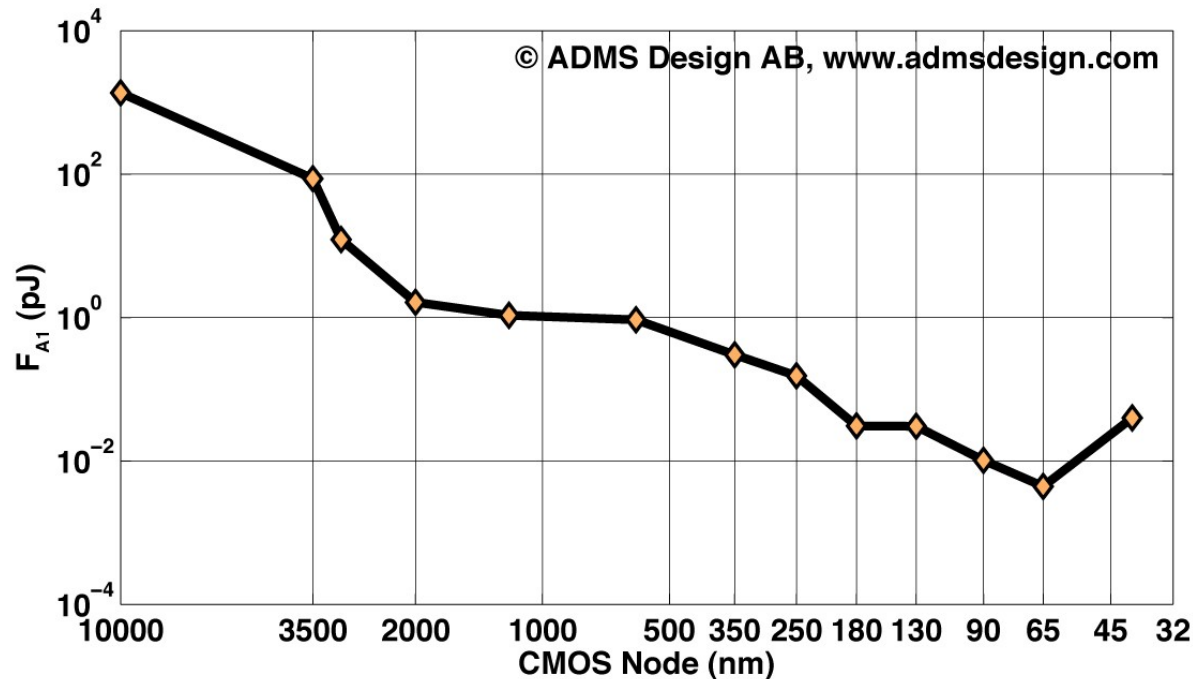


Nyquist ADCs improve roughly 2 times every 1.8 year. From ~2000 Nyquist rate ADCs broke away from the trend and improve faster...

ADC State of Art

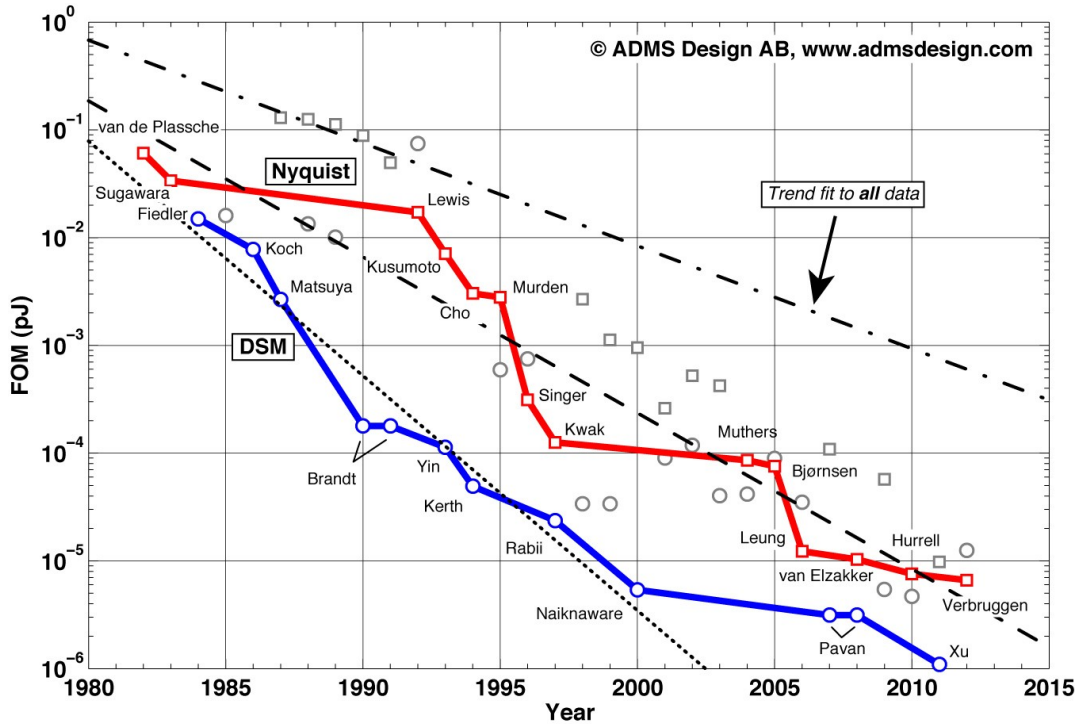
Walden FOM vs CMOS scaling

$$FOM = \frac{Power}{f_{sample} * 2^{ENOB}} [J/conv.]$$



FOM improves by roughly 100 time with a tenfold CMOS scaling.
Main factor – decreasing power supply.

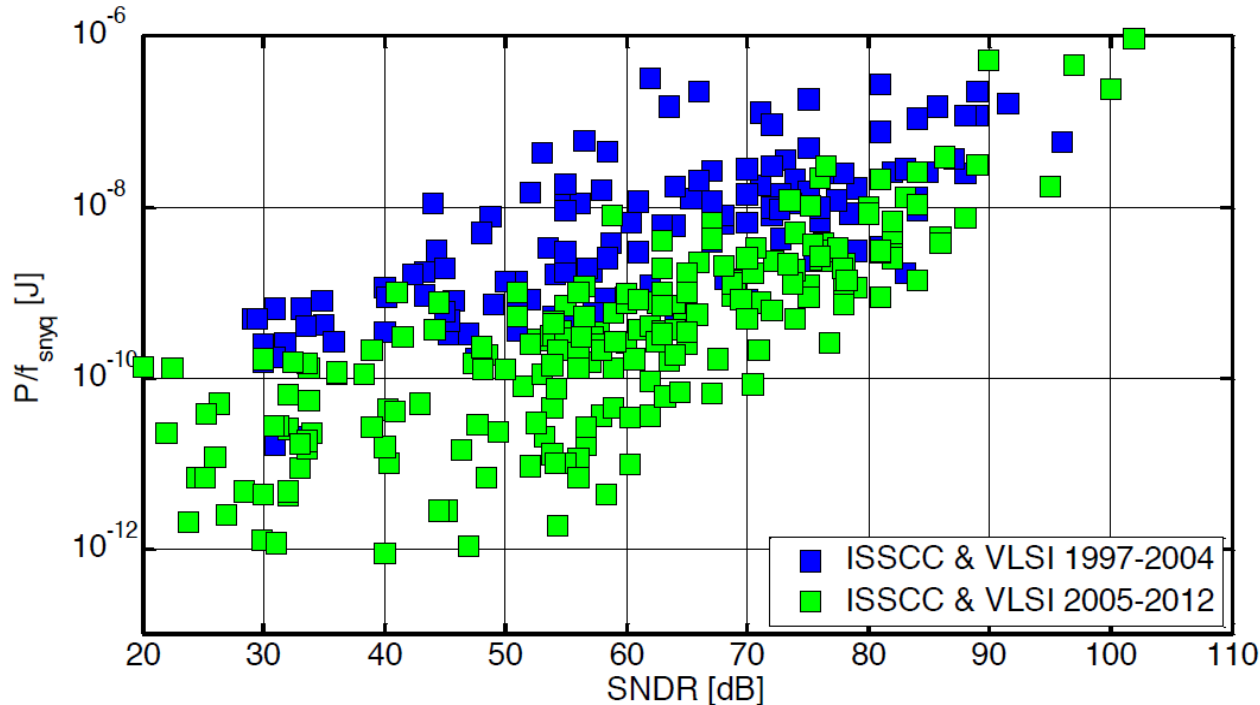
“Thermal FOM”



For high resolution ADCs, whose resolution is limited by thermal noise, the “Thermal” FOM_{Th} is used for comparison:

$$FOM_{Th} = \frac{Power}{f_{sample} * 2^{2 * ENOB}} [J/conv.]$$

ADC State of Art Murmunn Figure of Merit



Since there is no theoretical reason to have power exactly doubled at each additional bit of resolution Murmann prefers to show the plot of of Power/ f_{sample} versus “resolution” (SNDR)

$$ENOB = \frac{SNDR [dB] - 1.76}{6.02}$$

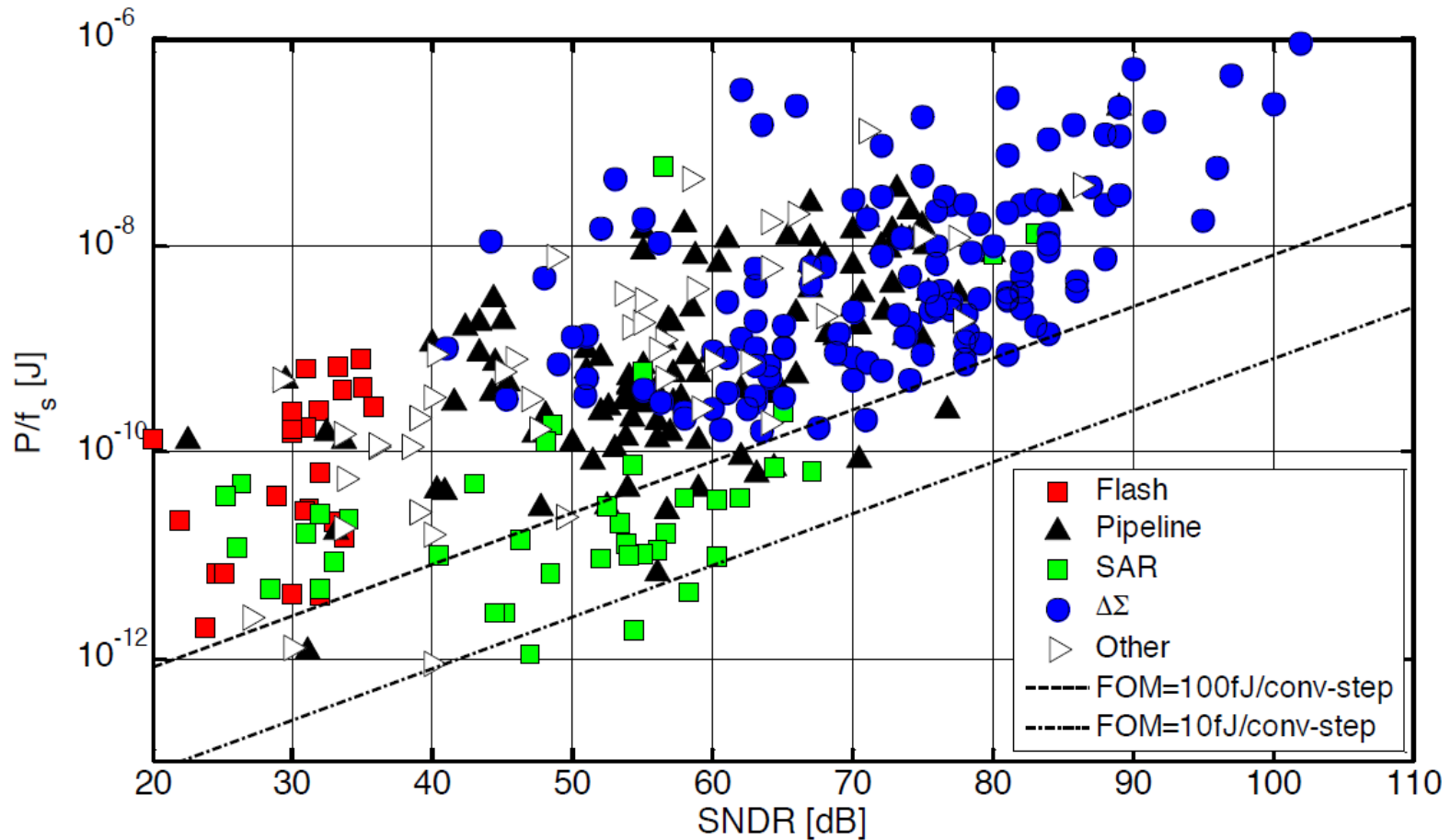
A huge performance improvement has been obtained in the last ~10 years.

A nice feature of Murmann ADC survey is the fact that it is constantly updated on his webpage:

B. Murmann, “ADC Performance Survey 1997-2013”, <http://www.stanford.edu/~murmunn/adcsurvey.html>

ADC State of Art

Murmann Figure of Merit - architectures



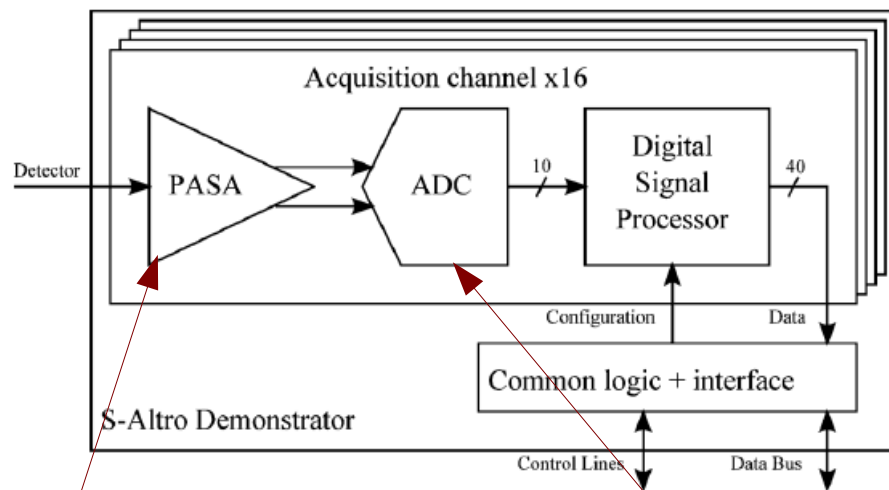
Most of the best ADCs ($FOM < 100fJ/conv.$) are SARs designed within last 10 years

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- ADC State of Art
- **Examples of multichannel ADC in HEP and commercial**

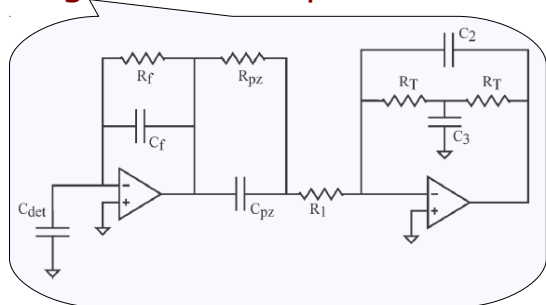
S-ALTRO Demonstrator ASIC

Project at CERN in 130 nm CMOS

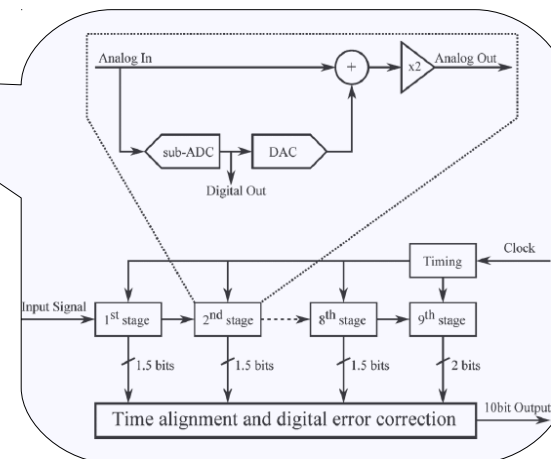


Supply voltage	1.5 V core, 2.5 V pads
Programmable gain	12, 15, 19 or 27 mV/fC
Programmable peaking time	30, 60, 90 or 120 ns
Shaper type	CR-(RC) ⁴
Programmable signal polarity	Positive or negative
Linearity	±5% up to 150 fC
Detector capacitance	4-20 pF
ENC	<1000 e ⁻ @ 12 pF
Cross-talk	<1%
Number of bits	10
Sampling frequency	10-40 MHz
Readout frequency	max 80 MHz
Power consumption	<50 mW/channel
Area	<4 mm ² /channel

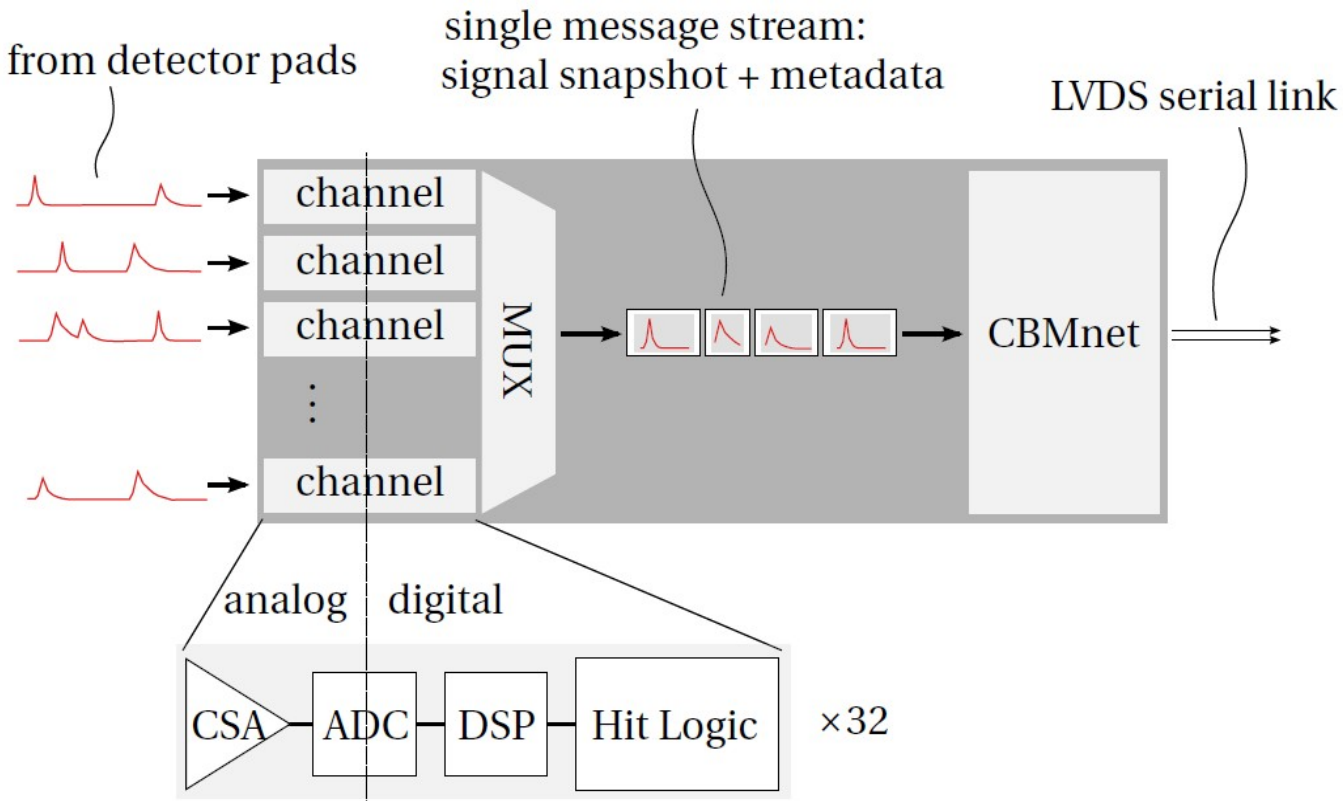
Front-end with semi-gaussian shaper



10-bit pipeline ADC
ADC consumes ~33 mW !!
FOM ~ 1.5pJ/conv.



SPADIC: Self-triggered Pulse Amplification and Digitization ASIC for TRD readout at CBM (FAIR)



CMOS UMC 180nm Front-end

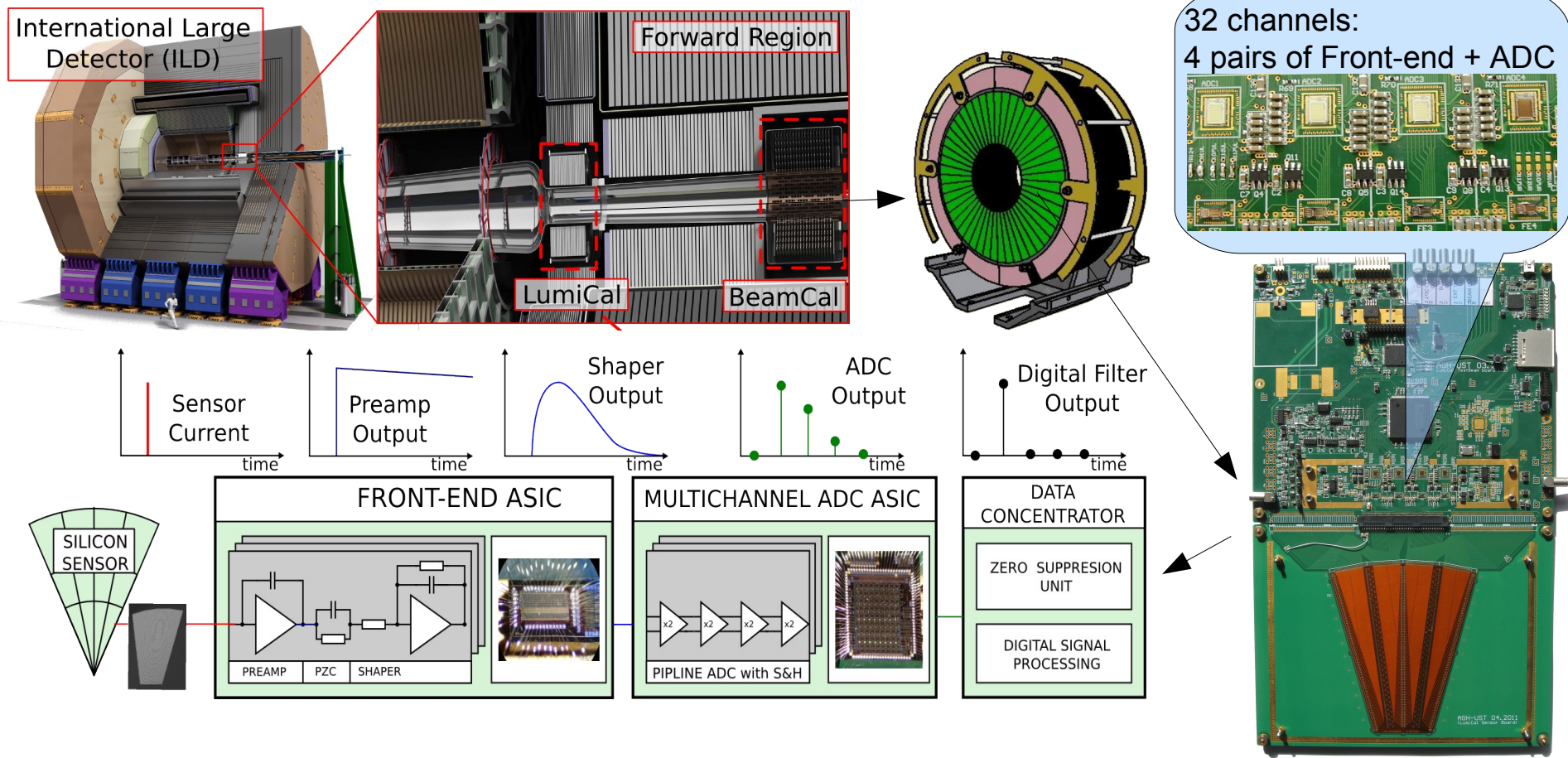
- Preamplifier
- Semi-gaussian shaper
- T_{peak} 80ns
- Power 4-8 mW
- ENC~800e@30pF

9-bit Pipeline ADC

- f_{sample} 25MHz
- ENOB ~8 bits
- Power cons. 4.8mW
- **FOM ~ 0.75 pJ/conv.**

Readout of LumiCal - Luminosity calorimeter for future International Linear Collider (ILC)

LumiCal detector will contain 30 layers of sandwich Si-W calorimeter ~200 000 channels

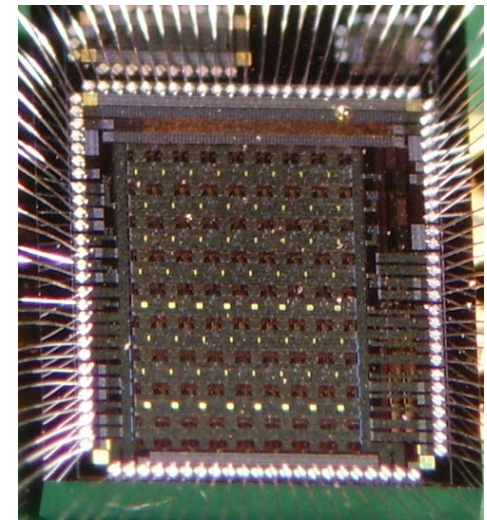
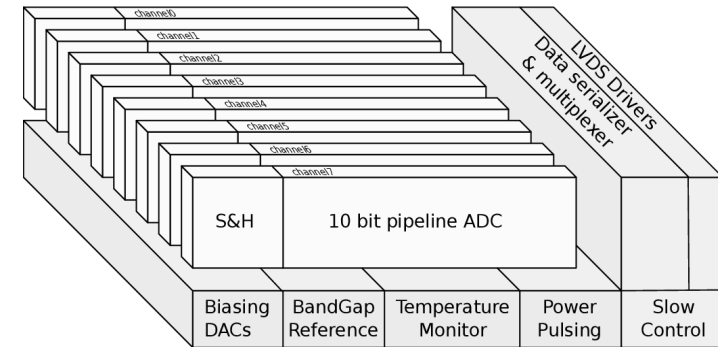


1st Prototypes of 8-channel front-end and ADC ASICs were designed and produced in AMS 0.35um CMOS. 32-channel readout module was built.

Multichannel digitizer ASIC for LumiCal readout

• Main features:

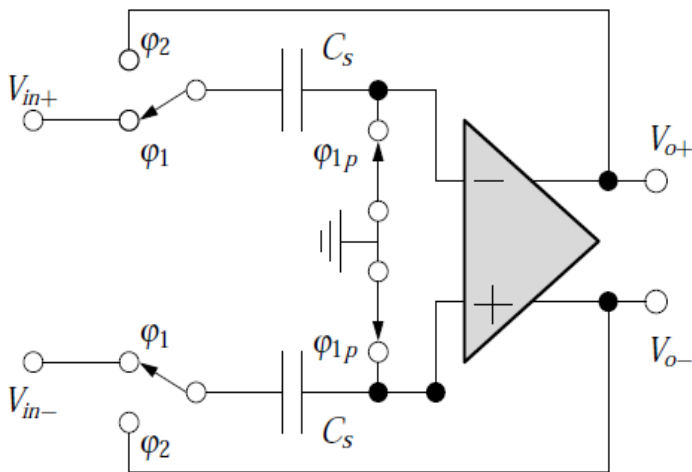
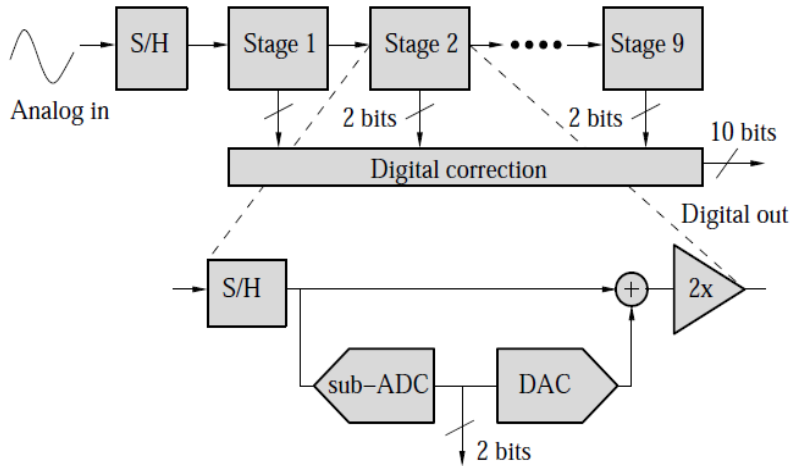
- 8 channels of 10-bit pipeline fully differential ADC
- Technology AMS 0.35um
- Layout with 200um ADC pitch
- Multimode digital multiplexer/serializer:
 - Test mode: single channel output (max fsmp ~ 50 Msps)
 - Parallel mode (~ 250 MHz): one data link per channel (max fsmp ~ 25 MSps)
 - Serial mode (~ 250 MHz): one data link per all channels (max fsmp ~ 3 MSps)
- High speed LVDS interface (~ 1 GHz)
- Power pulsing
- BandGap reference and Temperature sensor
- Various DACs
- Power consumption 1.2mW/channel/MHz
- ENOB ~ 9.7 , FOM ~ 1.4 pJ/conv.



2.6mm x 3.2mm

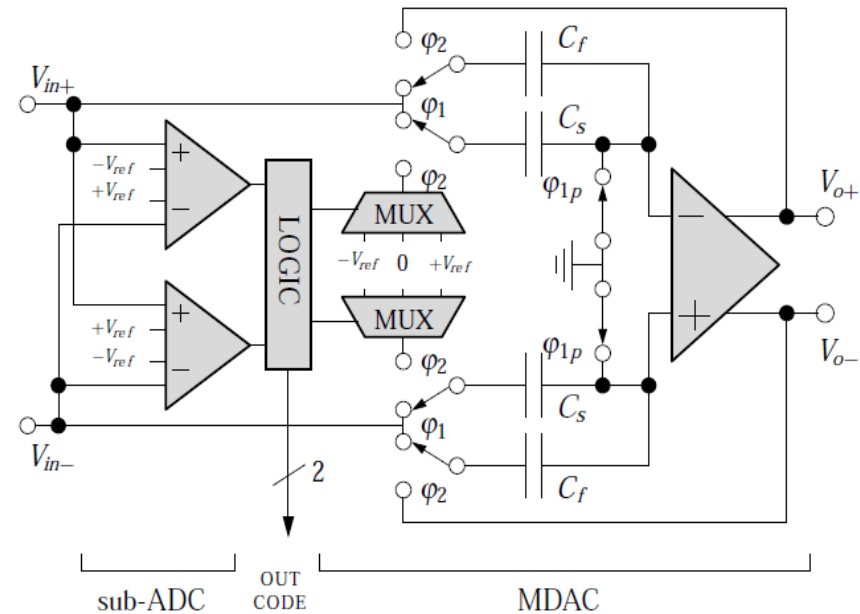
Multichannel digitizer ASIC

10-bit pipeline ADC



S/H stage

- High throughput - conversion rate = clock rate
- 1.5 bit per stage - redundancy reduces comparator requirements
- Fully differential architecture

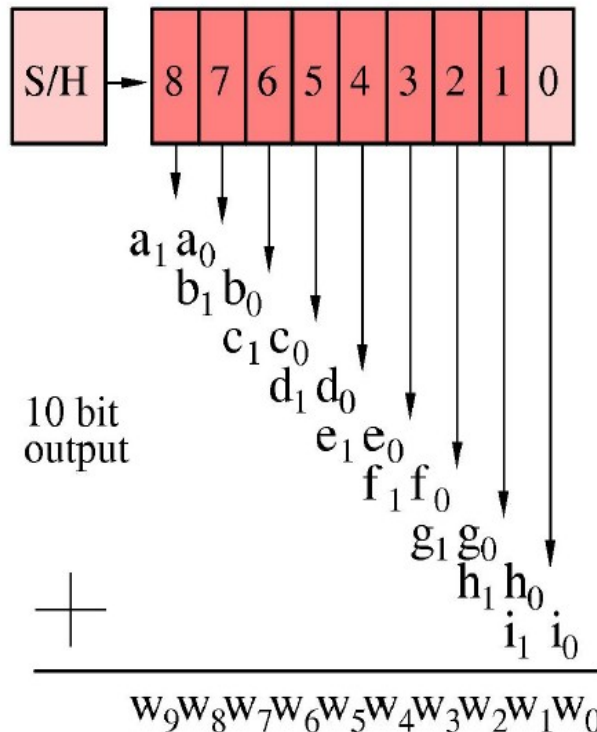


1.5 bit pipeline stage

Pipeline ADC – digital correction

- Digital part, including digital correction block is described in Verilog, synthesized automatically with RC Compiler (Cadence), and implemented using SoC Encounter (Cadence)

Digital correction

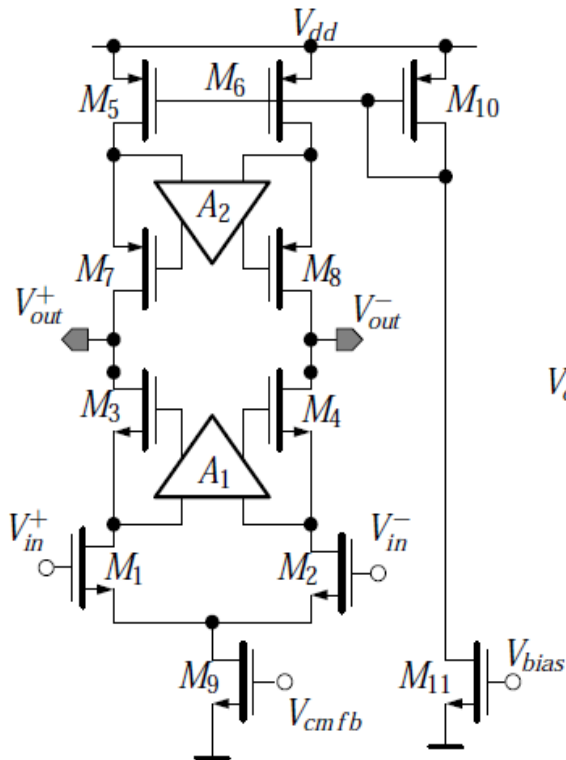


- Denote stage output as $s_i = \{0, 1, 2\}$
- Then digital correction is

$$w = \sum_{i=0}^8 2^i s_i$$

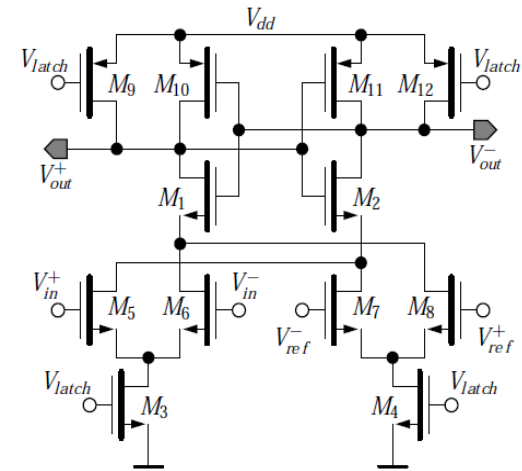
Pipeline ADC – analog blocks

- Fully differential amplifier+CMFB



High gain amplifier needed for precise
Multiplication by 2

- Dynamic latch comparator



Simple low precision
comparator good enough
(because of 1.5 bit per stage
redundancy)

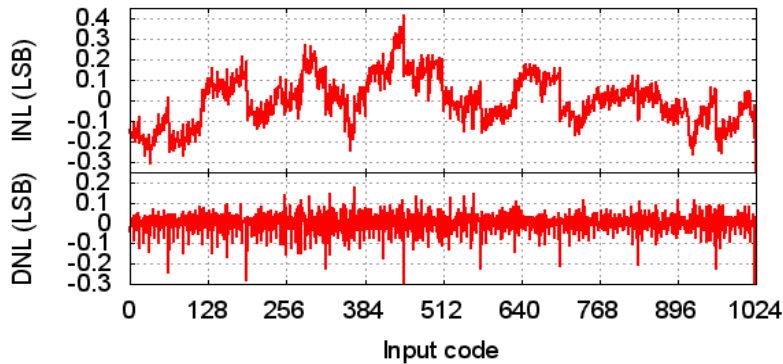


Multichannel digitizer ASIC Performance measurements

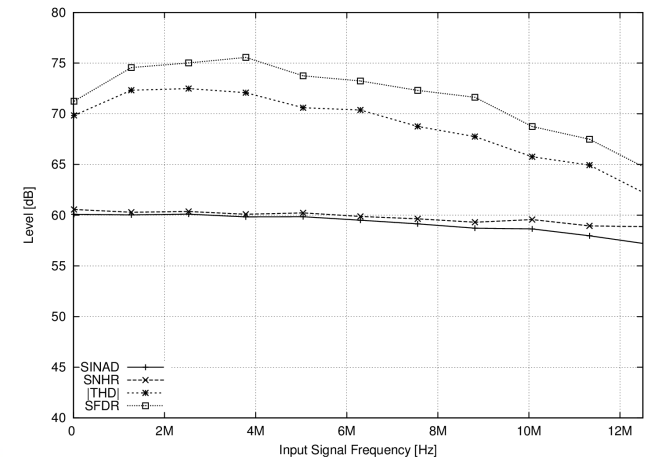
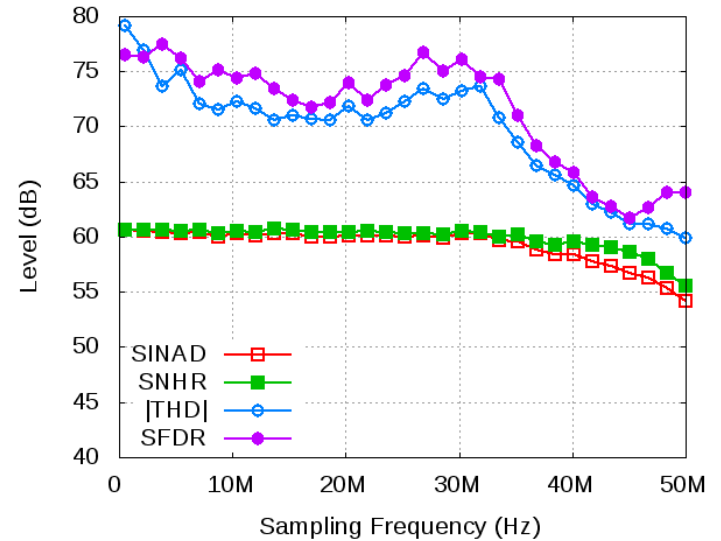
• Performance

- ENOB=9.7 up to 25 Ms/s (8 channels)
- INL<0.68, DNL<0.62
- Sampling rate up to ~25MS/s (multichannel) or up to ~50MS/s (single channel)
- Power scales linearly with sampling rate ~1.2mW/channel/MHz (without power pulsing)

Static measurements



Dynamic measurements



“Fast” Multichannel 10-bit pipeline ADCs

Commercial and research solutions

These ADCs have
 FOM ~ 1-2 pJ/conv.
 Means 1-2 orders
 of magnitude worse
 than the best
 published designs.

A lot can be done...

Parameter	Our work*	K. Kavani et al ESSCIRC 2002	AD9212 AnalogDevices	ADS5287 TexasInstruments	MAX1434 Maxim
Nr of channels	8	8	8	8	8
Architecture	10-bit pipeline	10-bit pipeline	10-bit pipeline	10-bit pipeline	10-bit pipeline
Serialization	Per channel & per chip	Per chip	Per channel	Per channel	Per channel
Technology	0.35 μ m CMOS	0.25 μ m CMOS	-	CMOS	BiCMOS
Supply	3.3 V	2.5 V	1.8 V	3.3/1.8 V (A/D)	1.8 V
Max. f_{sample}	25MS/s	20MS/s	65MS/s	65MS/s	50MS/s
Input range	2Vpp	-	2 Vpp	2 Vpp	1.4 Vpp
Power/channel	~1.2mW/MS/s plus I/O (<15%)	41mW@20MS/s	100mW@65MS/s 68mW@40MS/s	74mW@65MS/s 46mW@30MS/s	96mW@50MS/s
Area	8.2 mm ²	4mm ²	9x9mm ² (package)	9x9mm ² (package)	14x14mm ² (package)
INL	<0.68LSB	-	<0.5LSB	<1LSB	<1LSB
DNL	<0.62LSB	-	<0.4LSB	<0.55LSB	<0.5LSB
SINAD	~60.3dB	54.3dB	>=60dB	>=60.4dB	>=60dB
$T_{\text{power_ON}}$	<=10Tclk (~ μ s)	-	375 μ s	-	100ms

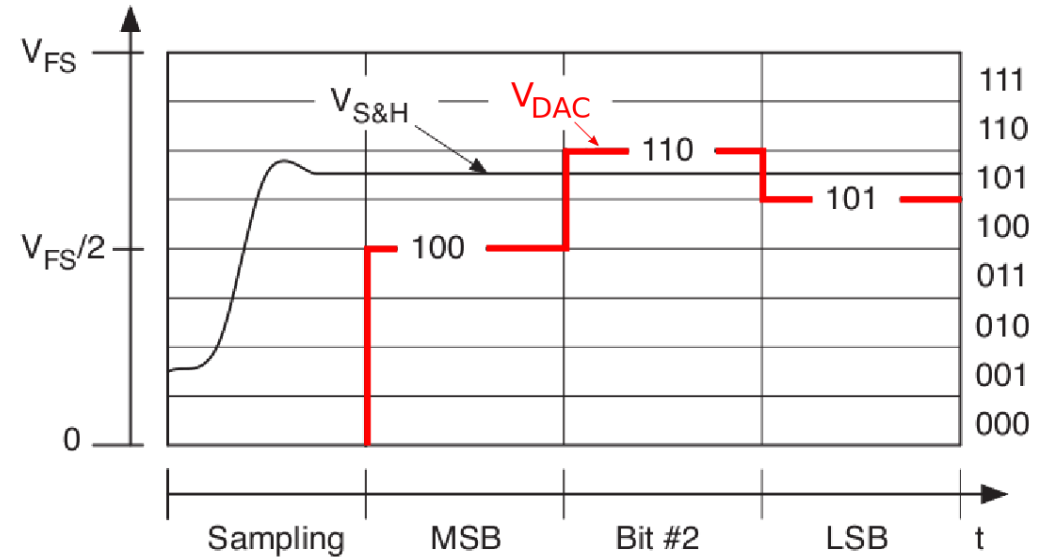
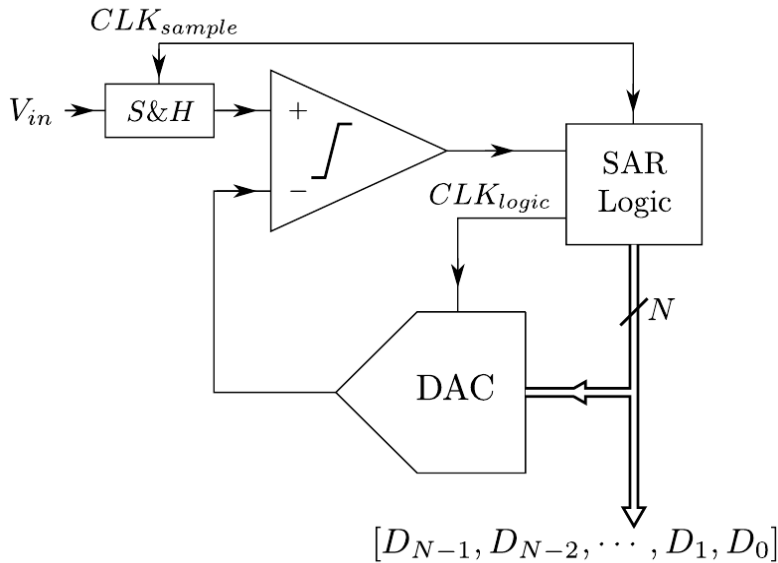
* M. Idzik, K. Swientek, T. Fiutowski, Sz. Kulis, D. Przyborowski “A 10-bit multichannel digitizer ASIC for detectors in particle physics experiments”, *IEEE Trans. Nucl. Sci.* v.59 p.294-302 2012

Part II: SAR ADC design and tests

- SAR ADC design
 - Fundamentals
 - DAC Switching energy
 - Other aspects - DAC capacitance, splitted DAC, asynchronous logic, dynamic comparator&logic, bootstrapped switch
- SALT project in IBM CMOS 130 nm
- LumiCal readout in IBM CMOS 130 nm
- Multichannel ADC aspects: PLL, sampling pulse, I/O SLVS, Single-to-Differential converter
- Summary

SAR architecture

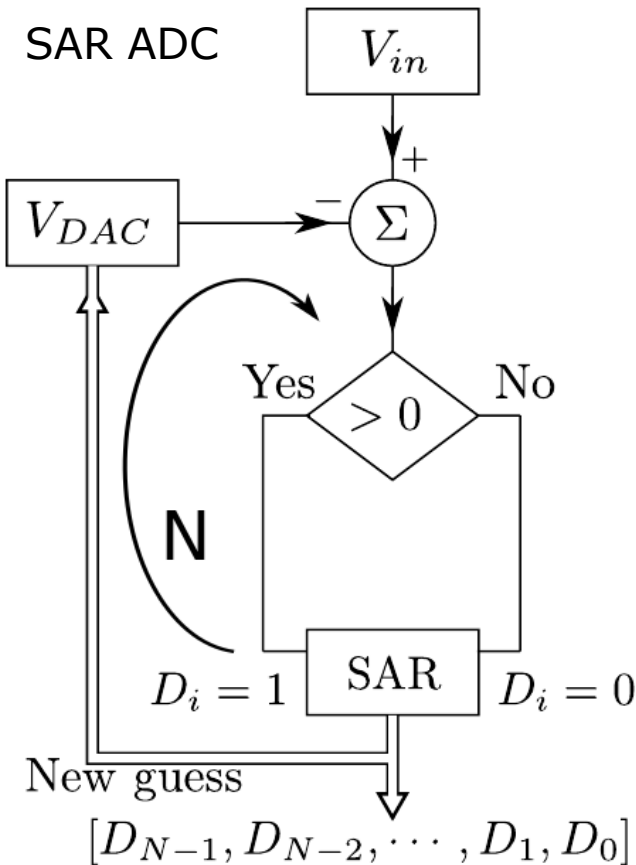
Fundamentals of operation



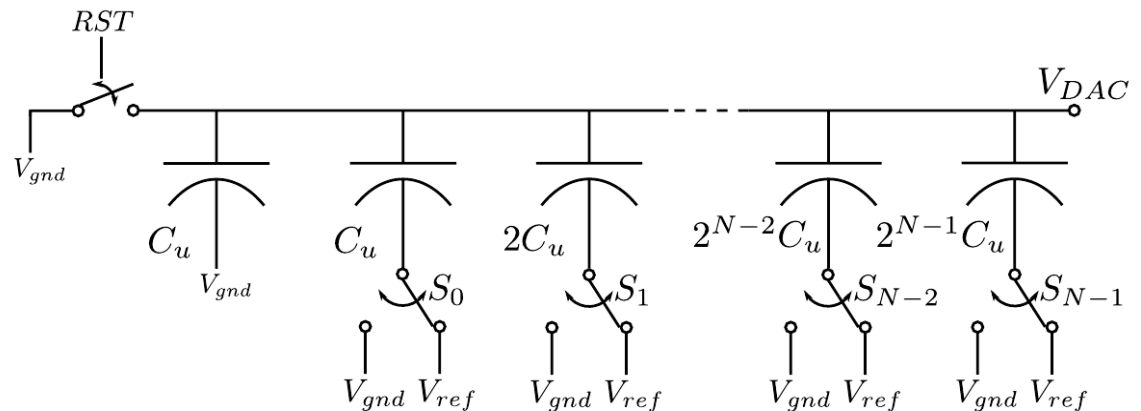
- Comparison between sampled input voltage and reference DAC output voltage
- Comparison result \rightarrow change reference DAC output voltage closer to input sample
- Each consecutive voltage change is half of the previous one
- Operation is repeated N times for N -bit ADC

SAR architecture

Advantages and disadvantages

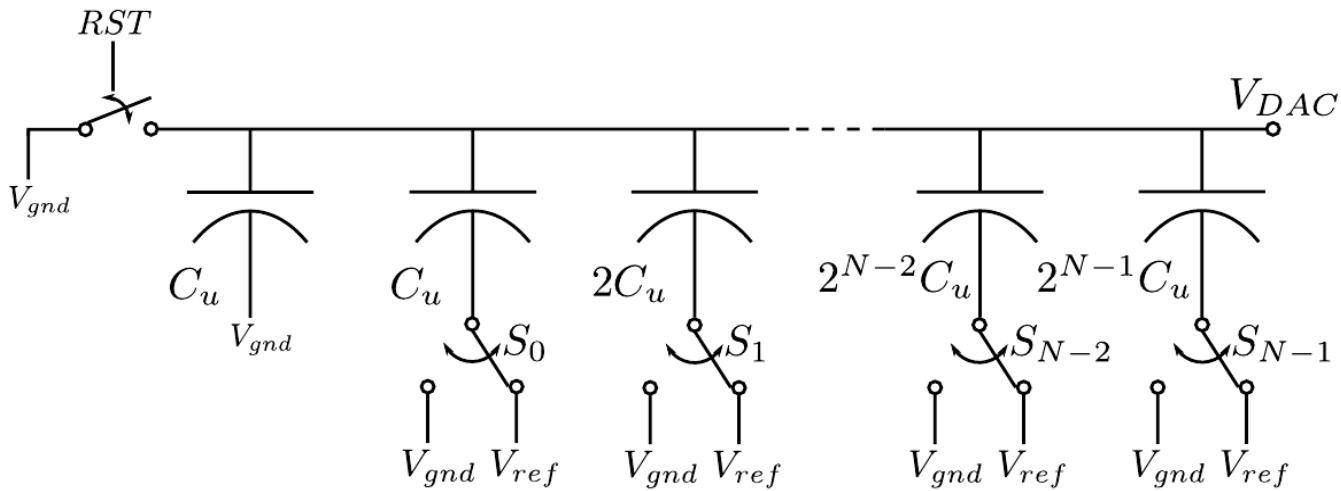


- + Power and area-efficient architecture – **same circuitry is used in loop N-times**
- + SAR ADC contains: single comparator, two DACs (differential) and SAR logic – **fits well to modern digital CMOS technologies**
- + DAC network is usually capacitive – **no static power, serves also as S/H circuit**



- Limited sampling rates – **but with modern CMOS technology ($\sim 100\text{nm}$) above 100MSps 10-bit ADCs are reported**

SAR architecture: Operation of charge scaling DAC



1) Reference voltage setting - charge scaling DAC:

1) Bottom side of MSB (S_{N-1}) capacitor switched to V_{ref} , all others to $V_{gnd} \rightarrow V_{DAC} = 1/2 V_{ref}$

2) Next switching depends on comparison result

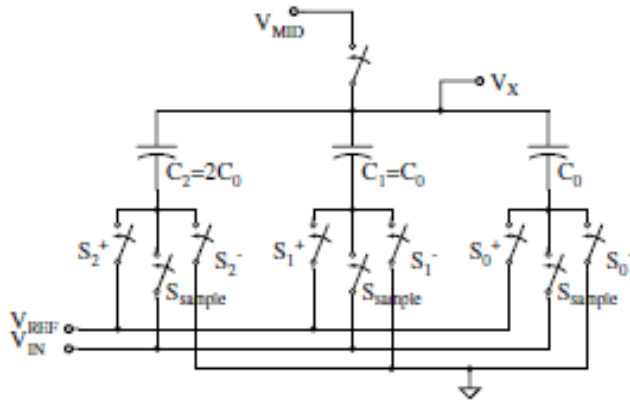
- $V_{DAC} = 3/4 V_{ref}$ if $V_{DAC} < V_{in}$
- $V_{DAC} = 1/4 V_{ref}$ if $V_{DAC} > V_{in}$

Part II: SAR ADC design and tests

- SAR ADC design
 - Fundamentals
 - **DAC Switching energy**
 - Other aspects - DAC capacitance, splitted DAC, asynchronous logic, dynamic comparator&logic, bootstrapped switch
- SALT project in IBM CMOS 130 nm
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Switching energy – principle

2-bit capacitor array example



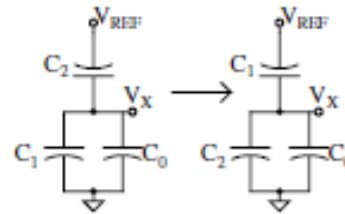
1. S_2 “up” transition: $E=C_0 V_{ref}^2$
- 2A. If $V_{in} > V_{ref}/2$ S_1 “up” transition: $E=C_0 V_{ref}^2/4$
- 2B. If $V_{in} < V_{ref}/2$ S_1 “down” transition:

Energy drawn from Vref:

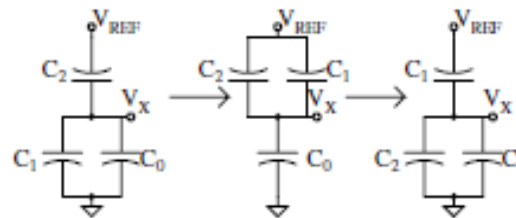
$$E = V_{ref} * \Delta Q$$

“up” transition – S_i short to V_{ref}

“down” transition - S_i short to gnd



Conventional switching:
 $E=5C_0 V_{ref}^2/4$



2 step switching:
 $E=3C_0 V_{ref}^2/4$

“down” transitions consume a lot of power...

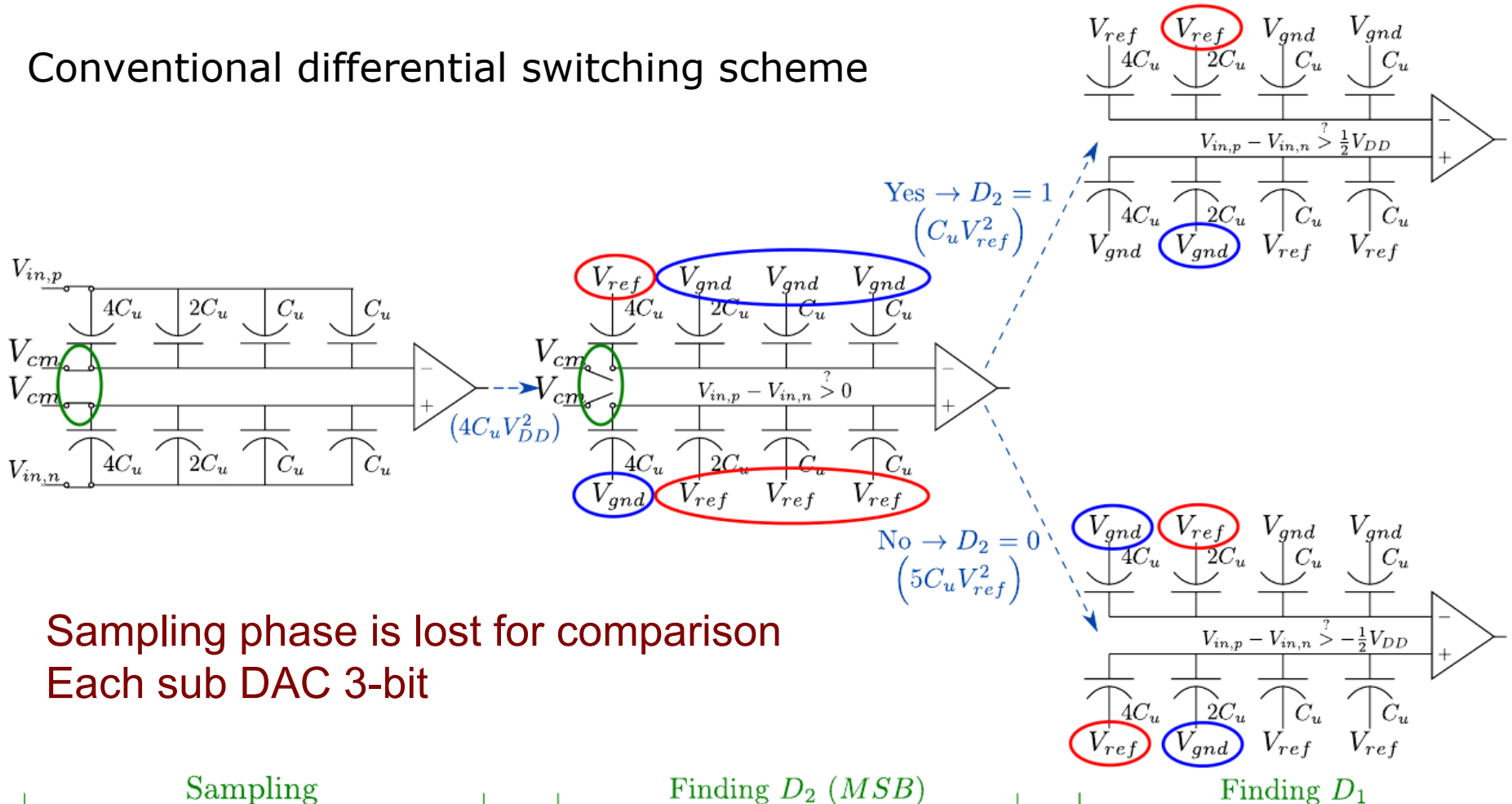
Switching scheme can be optimized to save power in “down” transitions !

Conventional DAC in SAR ADC

Switching scheme and energy consumption

3-bit SAR ADC example

Conventional differential switching scheme



Sampling phase is lost for comparison
Each sub DAC 3-bit

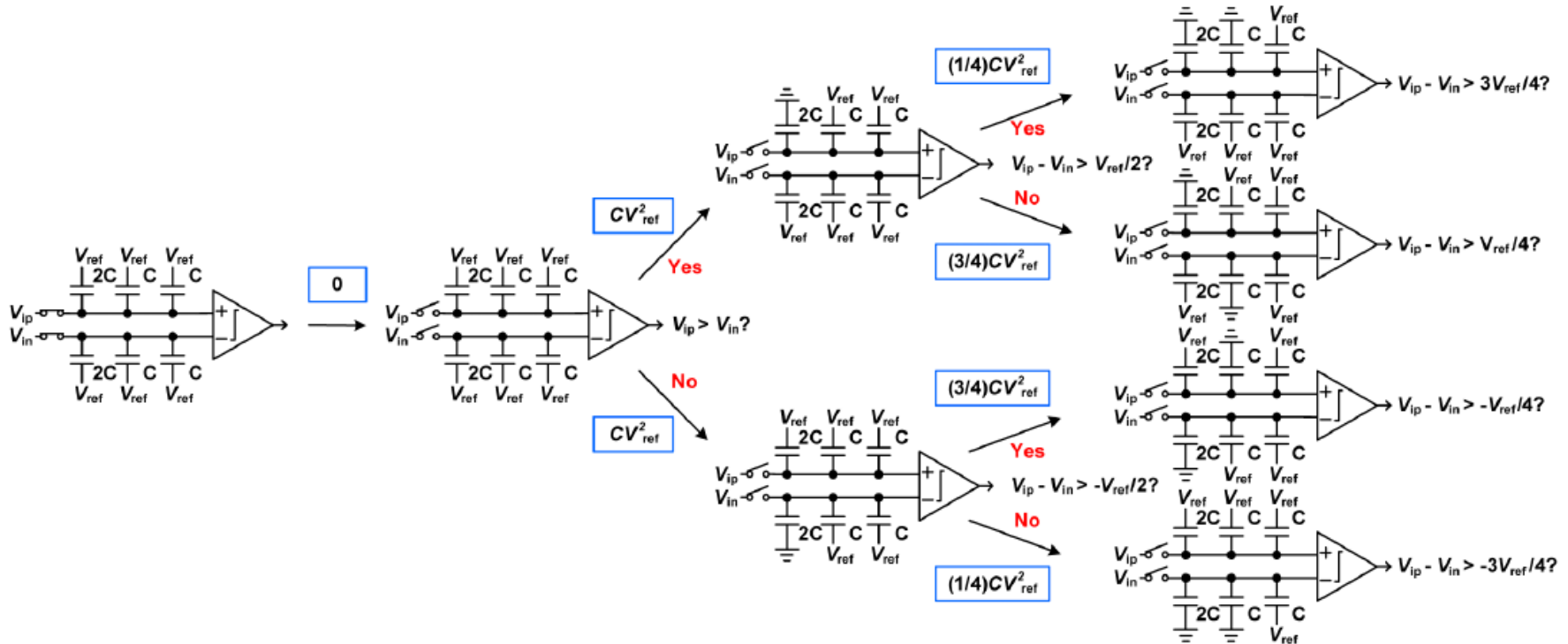
Sampling

Finding D_2 (MSB)

Finding D_1

Switching energy – more efficient configurations

Set and down 3-bit SAR ADC example

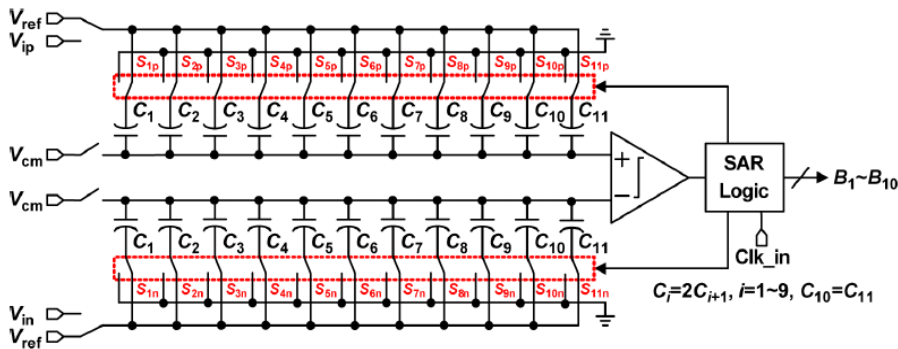


- 1st comparison after sampling ! (before any switching in DAC)
- Each sub DAC 2-bit !
- Switching energy ~81% less than conventional SAR ADC

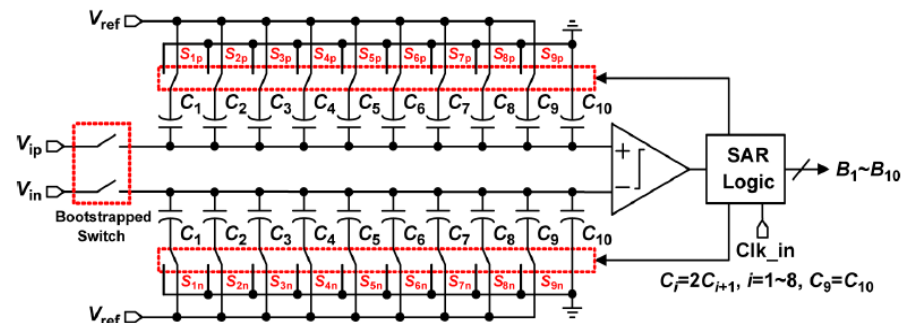
Switching energy – more efficient configurations

Set and down vs conventional

Conventional 10-bit SAR

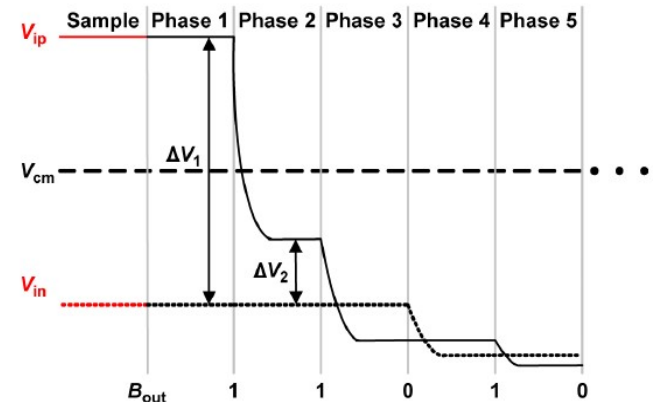


Set and down 10-bit SAR



Set and down SAR ADC:

- pair of MSB capacitors less
- V_{in} sampled on top plate
- 1st comparison done before any switching

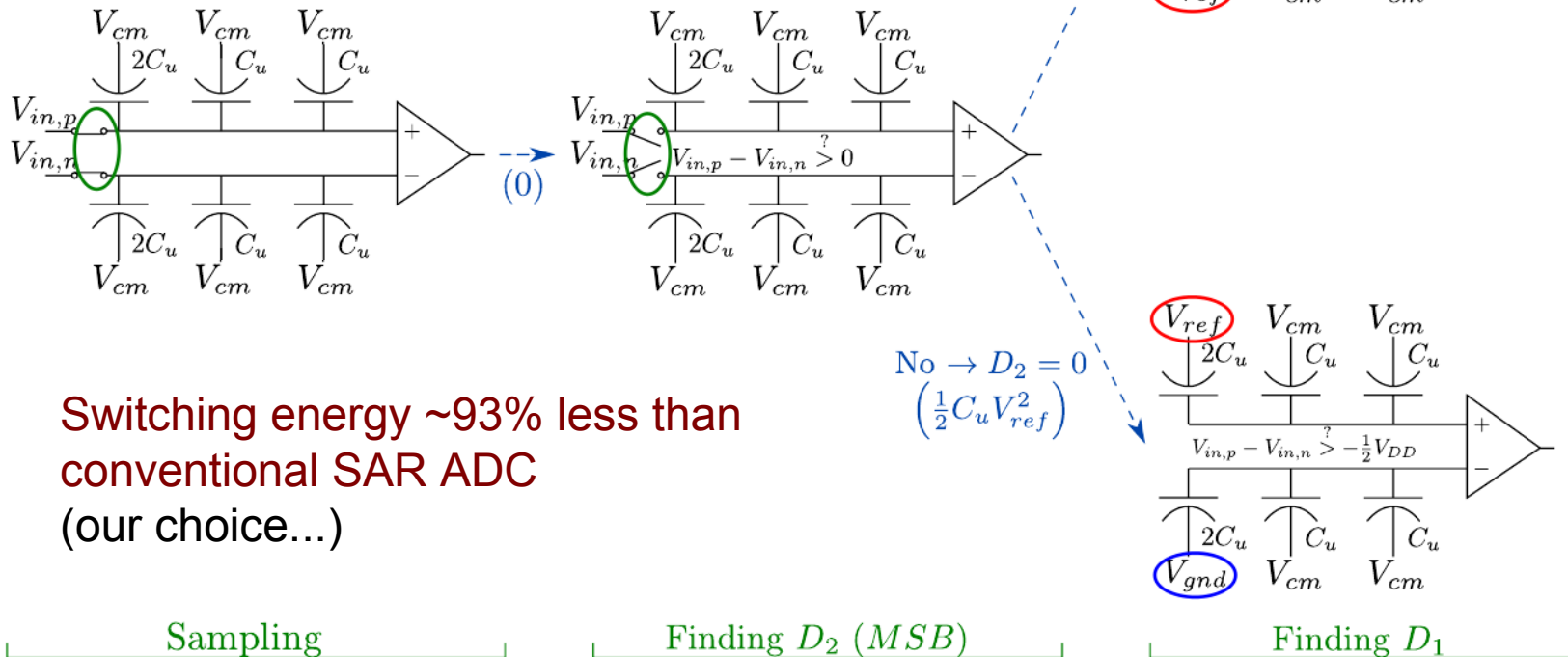


Variable common mode...

DAC in SAR ADC

Merged Capacitor Switching (MCS) scheme

- + First comparison done before any switching – **(N-1) capacitors needed**
- + Much more energy efficient than conventional scheme



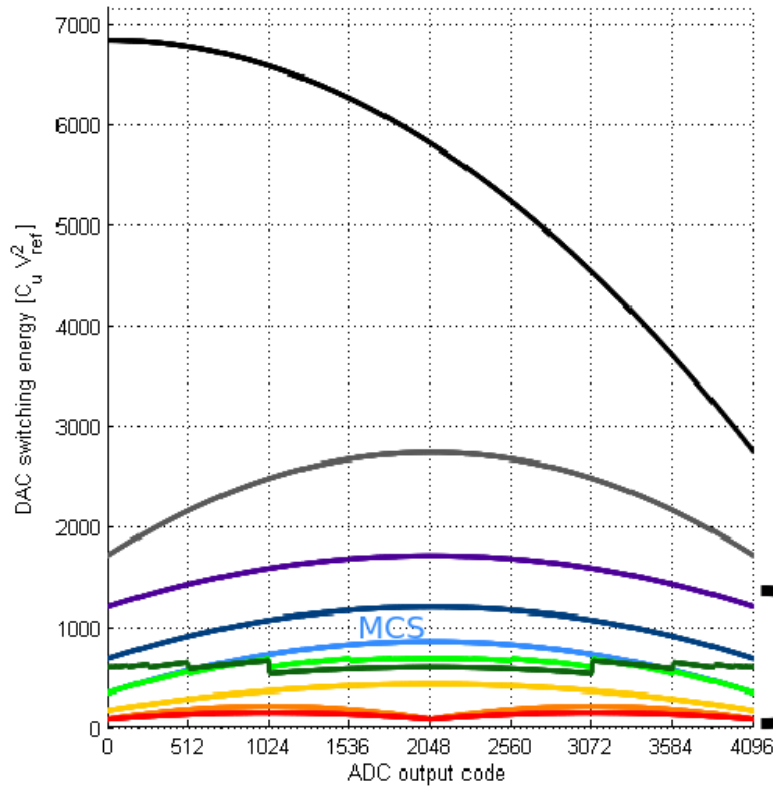
Switching energy ~93% less than conventional SAR ADC (our choice...)

DAC switching energy in SAR ADC

Various SAR configurations

- With CMOS technology scaling digital power consumption is decreasing rapidly - so minimizing analog power (DAC, comparator) is of main interest
- Huge progress has been obtained in the last ~10 years in optimizing capacitive DAC configurations and their switching schemes
- Various DAC switching configurations were proposed
 - **Conventional (100% power consumption)**
 - 2 step switching (~10% power saving)
 - Charge sharing (~24% power saving)
 - Split capacitor (~37% power saving)
 - Energy saving (~56% power saving)
 - Set and down (~81% power saving)
 - Vcm-based (~87% power saving)
 - **Merge Capacitor Switching (MCS) (~93% power saving)**
 - During the last year some new were proposed (up to ~98% power saving)

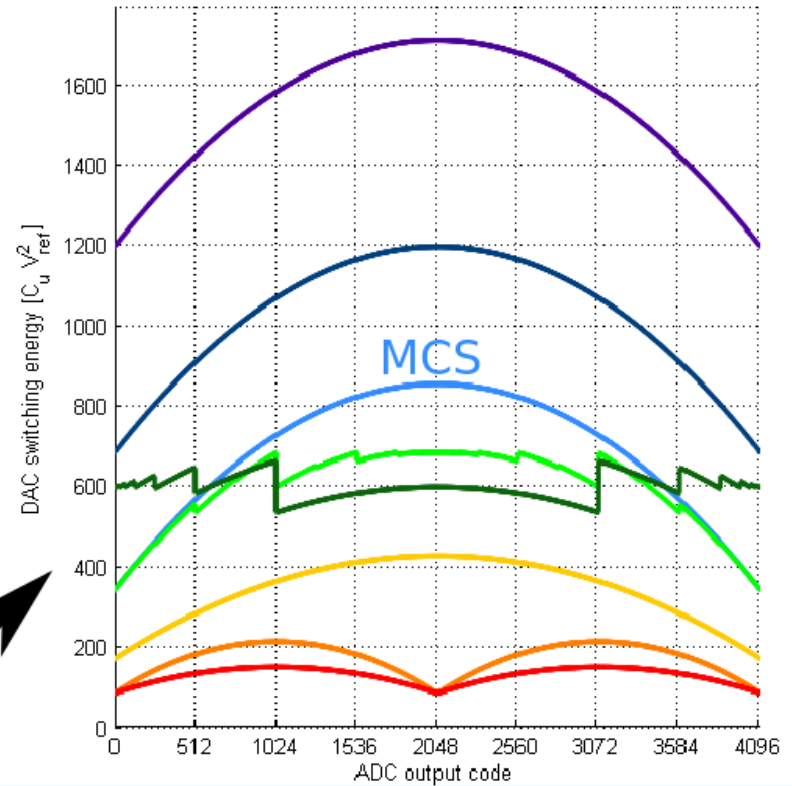
DAC switching energy in SAR ADC Comparison of various configurations...



- classical ($E_{avg} = 5459.3[C_u V_{ref}^2]$)
- energy saving ($E_{avg} = 2388.3[C_u V_{ref}^2]$)
- switchback ($E_{avg} = 1535.5[C_u V_{ref}^2]$)

- monotonic ($E_{avg} = 1023.5[C_u V_{ref}^2]$)
- MCS ($E_{avg} = 682.2[C_u V_{ref}^2]$)

Chosen scheme



- imp. switchback ($E_{avg} = 597.3[C_u V_{ref}^2]$)
- EMCS ($E_{avg} = 596.8[C_u V_{ref}^2]$)
- AMCS ($E_{avg} = 341.1[C_u V_{ref}^2]$)
- trilevel ($E_{avg} = 170.4[C_u V_{ref}^2]$)
- V_{CM} -based monotonic ($E_{avg} = 127.9[C_u V_{ref}^2]$)

Newly reported / variable common mode

Part II: SAR ADC design and tests

- SAR ADC design
 - Fundamentals
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 - **Other aspects - DAC capacitance, splitted DAC, asynchronous logic, dynamic comparator&logic, bootstrapped switch**
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DAC in SAR ADC

Capacitors noise area and matching

Noise

- Thermal switch noise of sampling circuit – kT/C

$$\frac{kT}{C} < \frac{\sigma^2}{12}, \sigma = \frac{V_{ref}}{2^N}$$

$$C > 12kT \left(\frac{2^N}{V_{ref}} \right)^2$$

- For $V_{ref}=1$ V:

N=6 bits	$C > 0.2$ fF
N=8 bits	$C > 3.3$ fF
N=10 bits	$C > 52.0$ fF
N=12 bits	$C > 830.0$ fF

Thermal noise is negligible for low/medium resolution

Area

Capacitance density in CMOS 130nm:

- VNCAP M1-M2 ~ 0.4 fF/ μm^2
- MIMCAP ~ 2 fF/ μm^2

Matching

Mismatch (%) at 3σ :

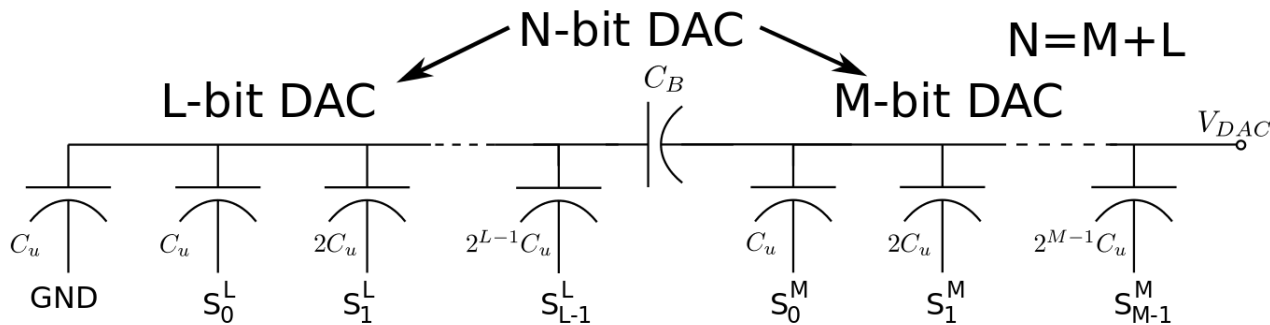
- VNCAP $10 \times 20 \mu\text{m}^2$ (~ 80 fF): $\sim 5\%$
- MIMCAP $6 \times 7 \mu\text{m}^2$ (~ 80 fF): $\sim 0.7\%$
- MOM – no model exist, matching unknown...

For considered technology MIMCAP has higher density and better matching, but a problem of C_{min} appears...

DAC in SAR ADC

Splitted DAC configuration

Example for 10-bit SAR ADC



- N-bit DAC splitted into two DACs connected via series unit capacitor

- C_u – minimal unit capacitance ensuring 3 σ matching within 0.5LSB
Assume technology limit $C_u = 30\text{fF}$

$$C_u = \frac{9}{2\sqrt{2}} 2^{2L} (2^M - 1) K_\sigma^2 K_C$$

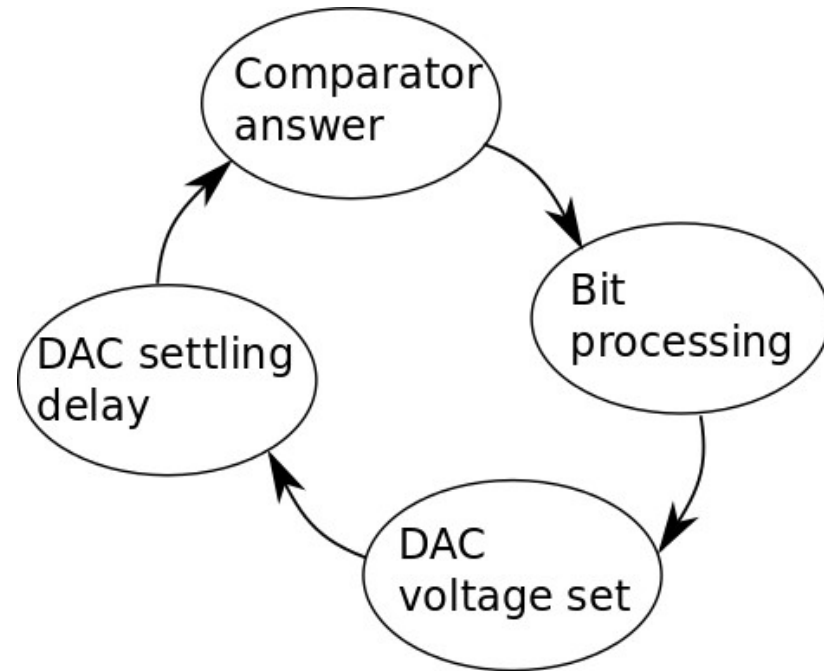
$$K_\sigma = 4.12 \frac{\%}{\mu m} \quad K_C = 2.05 \mu m$$

M	L	C_u [fF]	C_{DAC} [pF]	No. of C_u	\sim Area [μm^2]
9	0	5.66 \rightarrow 30	15.33	512	7079
8	1	11.29 \rightarrow 30	7.65	257	3553
7	2	22.5 \rightarrow 30	3.81	131	1811
6	3	44.64	2.81	71	1461
5	4	87.87	2.72	47	1903
4	5	170.07	2.55	47	3684
3	6	317.47	2.22	71	10388
2	7	544.24	1.63	131	32857
1	8	725.65	0.73	257	85947

Design of SAR ADC

Asynchronous logic – no fast clock distribution

- To operate at 40MS/s 10-bit ADC has to convert single bit in approximately 2ns
- Each bit conversion require at least two clock cycles – generation and distribution of 1GHz clock is needed for synchronous operation
- Asynchronous logic → data flow releases actions in sequence



- + No fast clock distribution needed – a lot of power saved
- + Single slope of sampling signal starts the conversion → ADC can operate in **asynchronous mode**

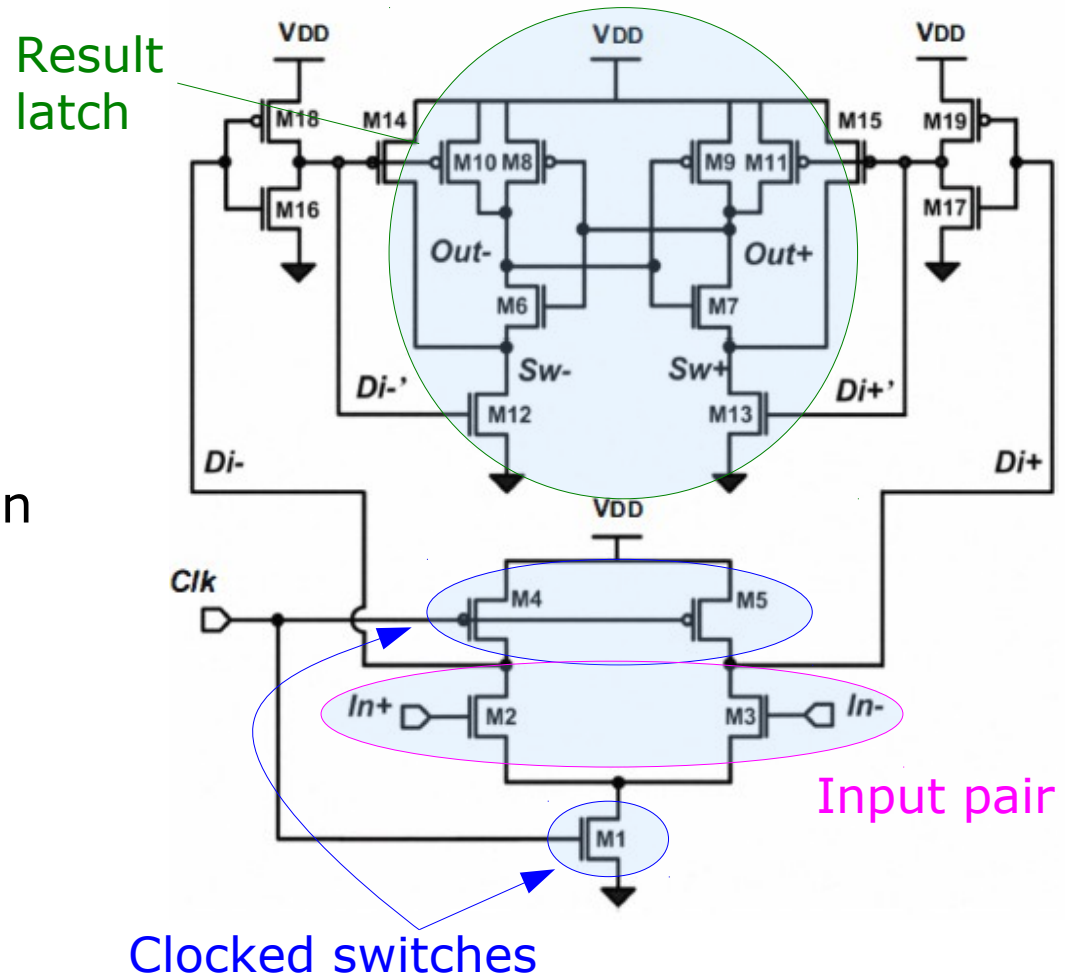
Design of SAR ADC Dynamic comparator

Dynamic comparator

- Comparison performed on rising edge of clock signal
- Reset (low clock level) needed before next comparison

Pros and cons:

- + No direct path current
- + Low power consumption
- Dead time needed for reset



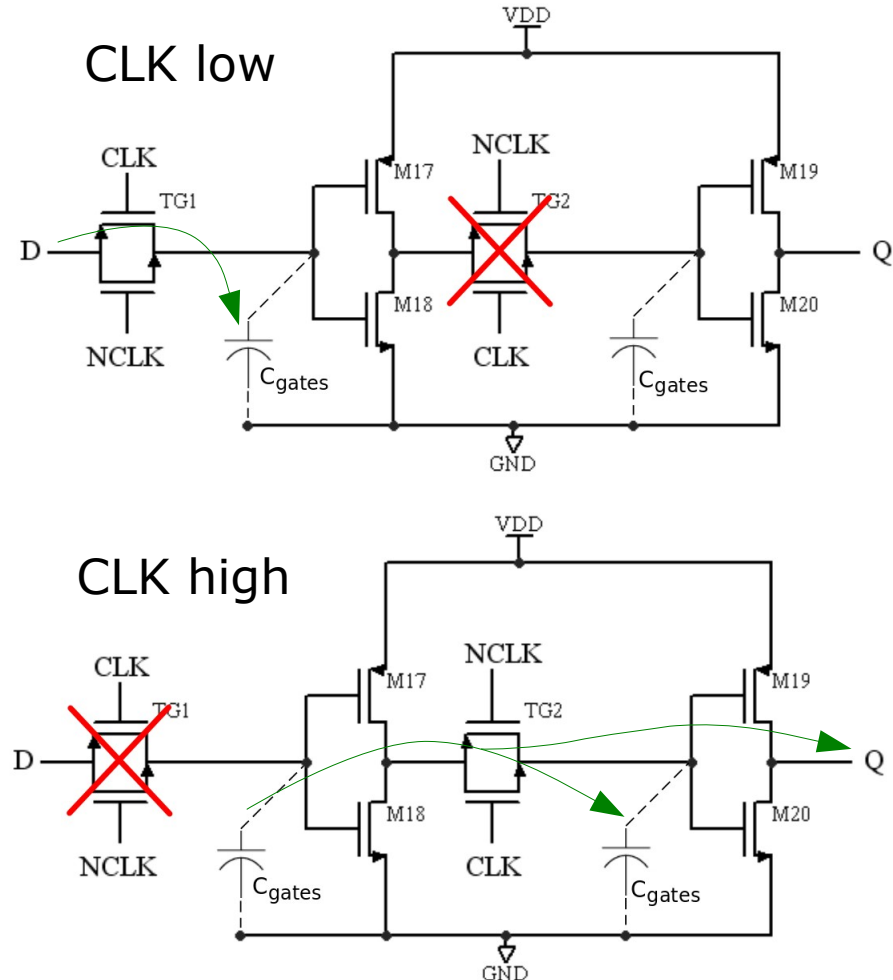
Design of SAR ADC

Dynamic logic – idea of operation

Dynamic D-type flip-flop:

- Bit (voltage level) stored on inverter gate capacitance
- + Very fast - only two small transistor gates need to be recharged on each clock slope
- Clock needs to run continuously (or static reset is needed)
- Manual layout

Flip-flop architecture	Signal propagation time [ps]	Power consumption [μ W/clock cycle]
Static	155	2.62
Dynamic	50	2.58

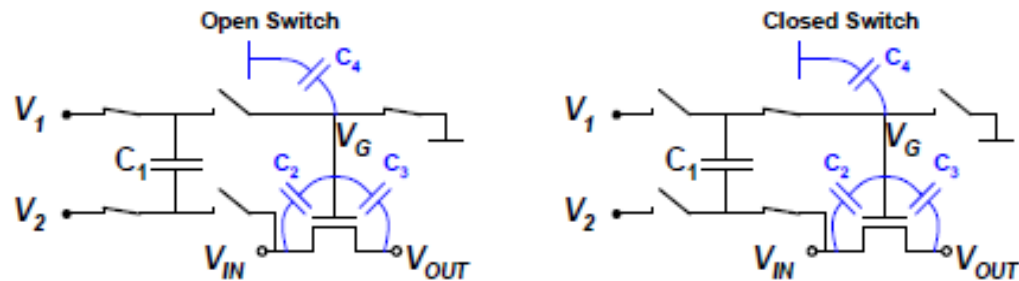


Dynamic flip-flop is 3 times faster

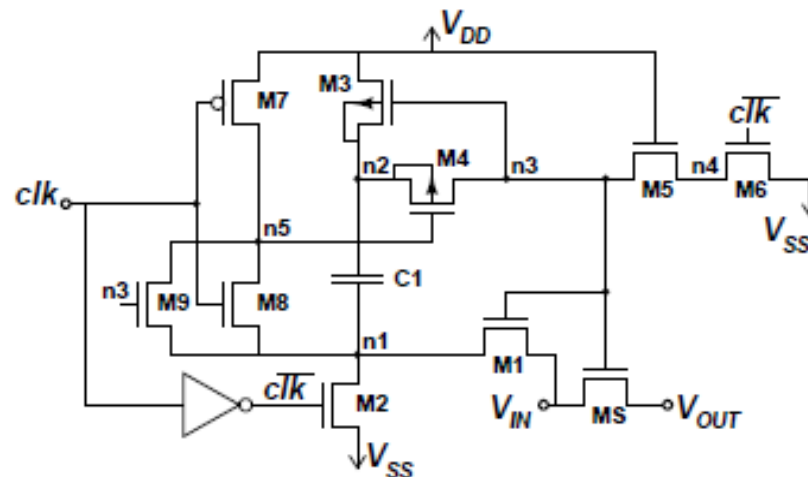
Design of SAR ADC Bootstrapped S/H switch

How to minimize signal distortion during sampling phase ?

Idea



Implementation



Part II: SAR ADC design and tests

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- **SALT project in IBM CMOS 130 nm**
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LHCb Tracker System Upgrade



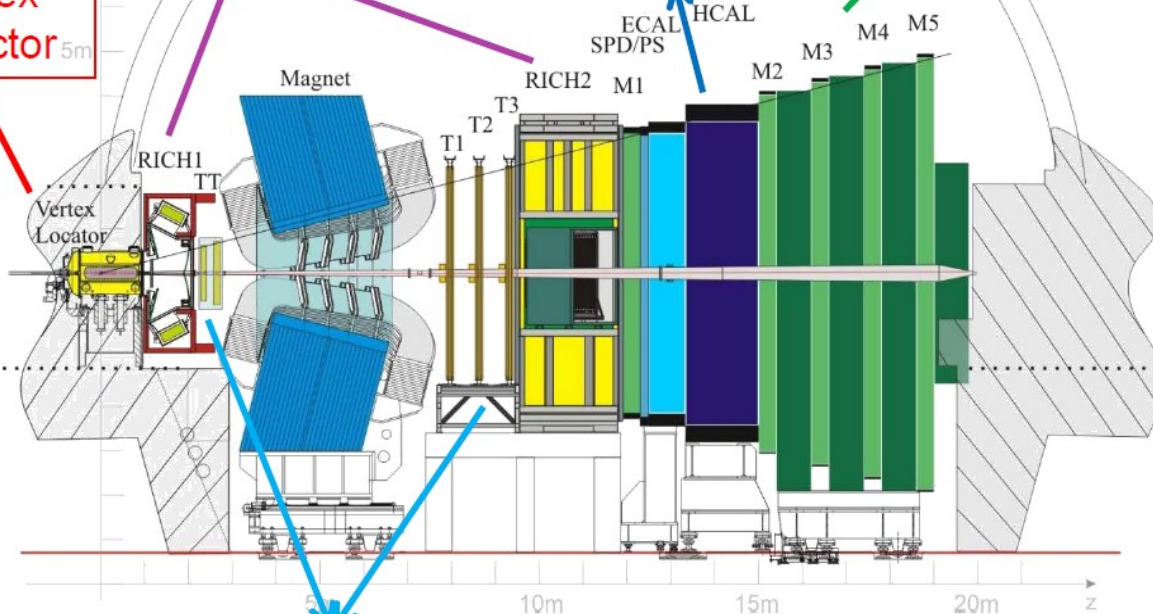
Particle ID
Replace
HPDs +
electronics

Upgraded LHCb Detector

Calorimeters
Reduce PMT gain
+ new electronics

Muon
new electronics

New
Vertex
Detector 5m

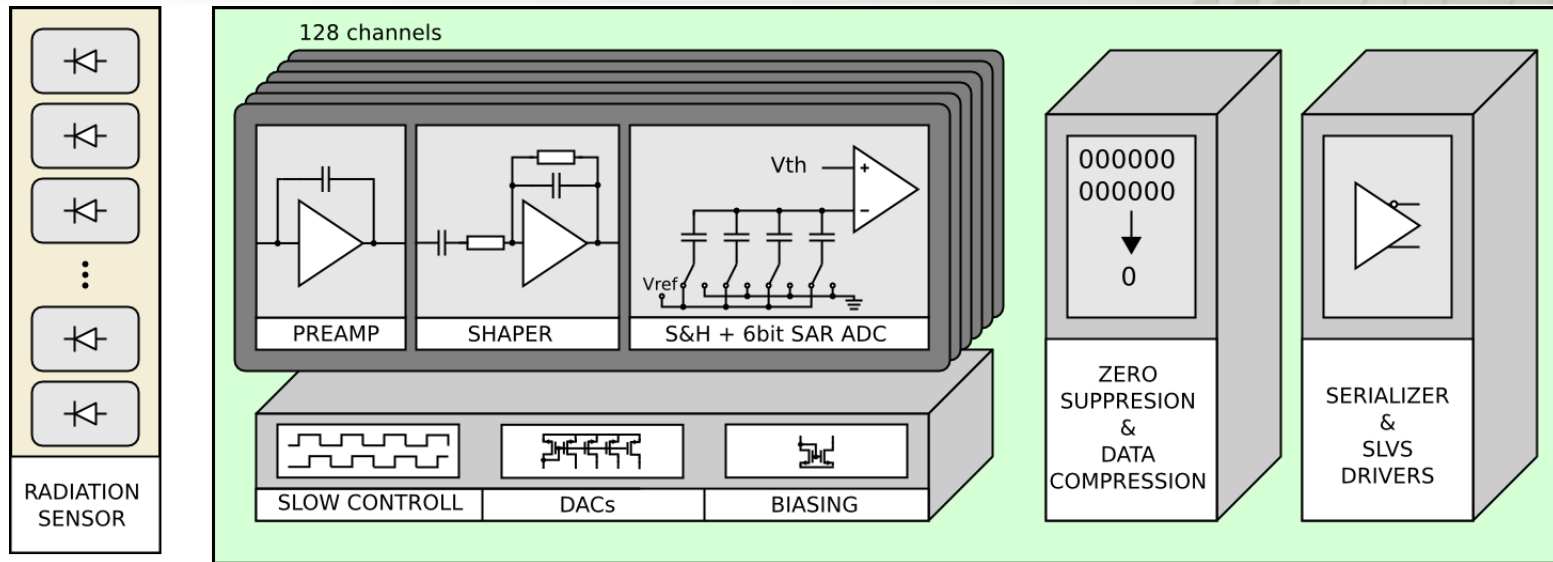


New Tracking stations

→ See Poster Session and
backup slides for details

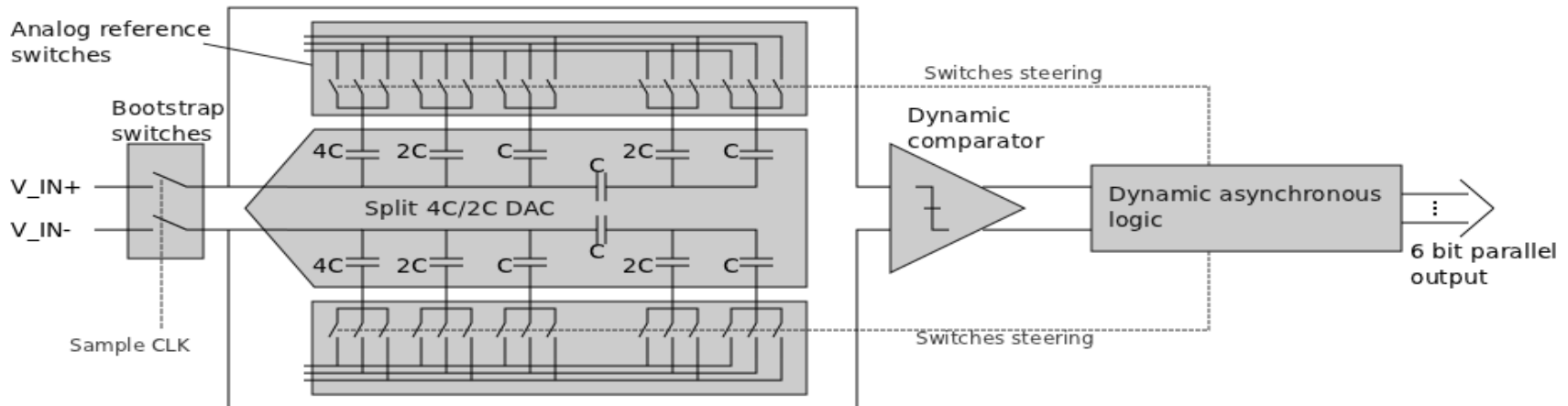
- To increase trigger rate from 1MHz to 40MHz new readout electronics needed in LHCb Tracking System
- Silicon Upstream Tracker (old TT) will need ~0.5 million readout channels

SALT- readout ASIC for LHCb silicon strips



- Complex System on Chip (SoC) ASIC
 - 128 channels
 - Preamplifier-shaper, 6-bit ADC, zero supp., serialization, fast data transmission
 - Pitch $\sim 40\mu\text{m}$
- CMOS IBM 130 nm technology

6-bit SAR ADC Architecture & Design considerations



Architecture of 6-bit ADC

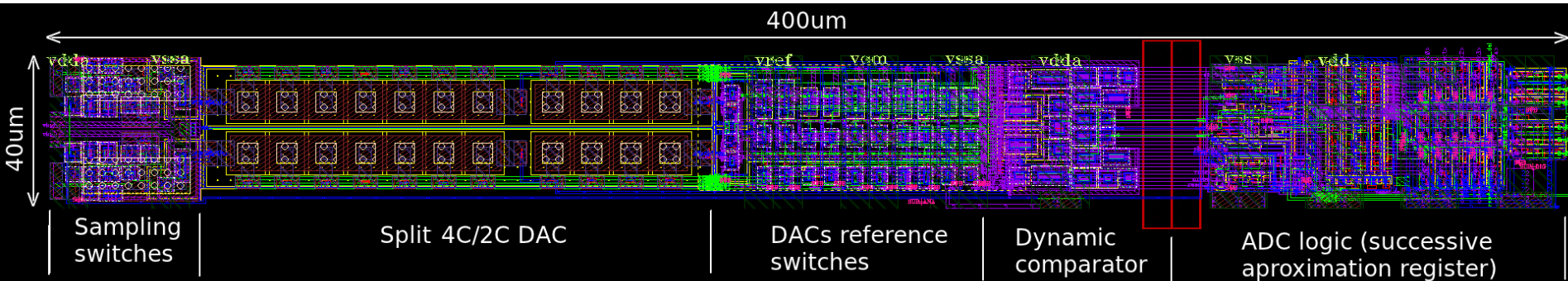
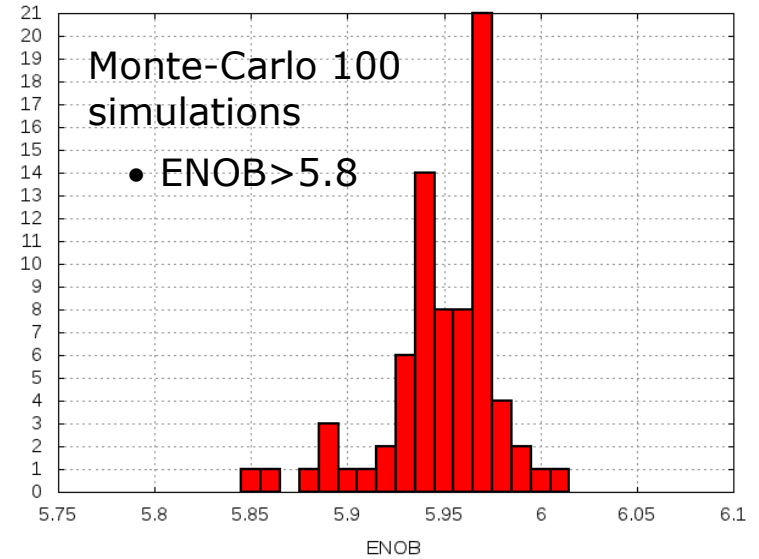
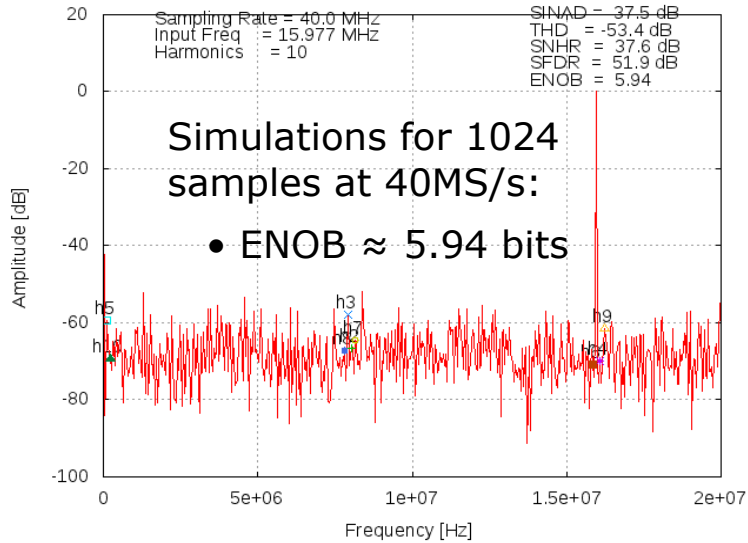
- Differential segmented/split DAC with MCS switching scheme – **ultra low power**
- Dynamic comparator – **no static power consumption, power pulsing for free**
- Asynchronous logic – no clock tree – **power saving, allows asynchronous sampling**
- Dynamic SAR logic – **much faster than conventional static logic**

Design consideration:

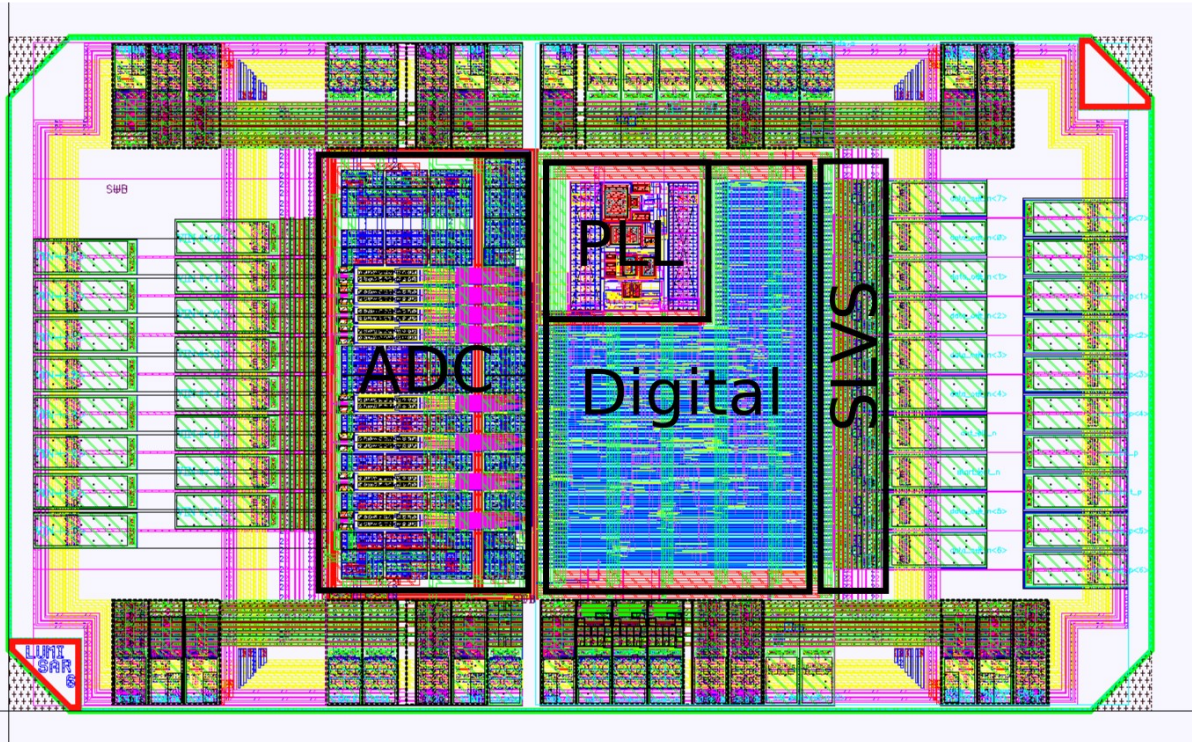
- Variable sampling frequency (up to ~ 90 MS/s) and power consumption
- Power consumption ~ 0.3 mW at 40 MS/s
- 40 μ m pitch, ready for multichannel integration

6-bit SAR ADC

Post-layout simulations



6-bit SAR ADC Prototype ASIC integration



2340um x 1380um

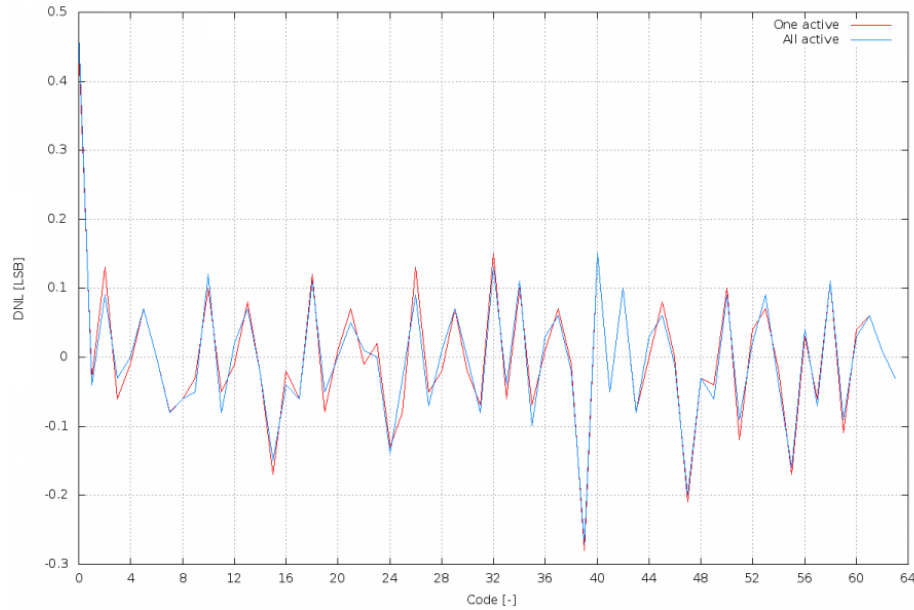
- ADC prototype contains:
- 8 channels of 6-bit SAR ADC in 40um pitch
 - Multiplexing&Serialization circuitry
 - PLL prototype (discussed later...)
 - SLVS I/O circuitry (discussed later...)
 - Staggered pads

Prototypes were fabricated in 2012. Development of FPGA based test setup has taken long time. First part of measurements has been completed in October 2013

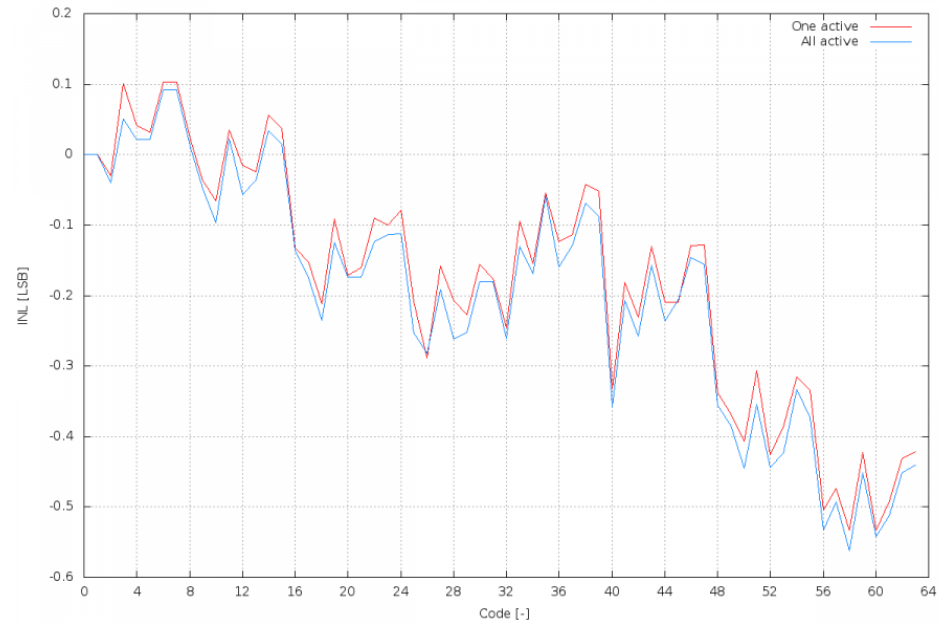
6-bit SAR ADC

Static tests – linearity

DNL@50MHz



INL@50MHz

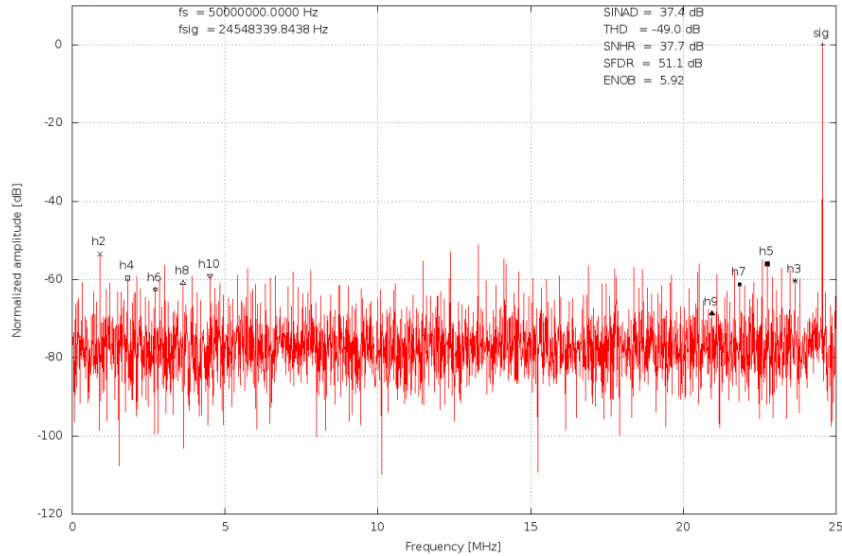


First measurements show that ADC is working very well. At 50MHz sampling frequency good linearity INL, DNL < 0.5 is seen.

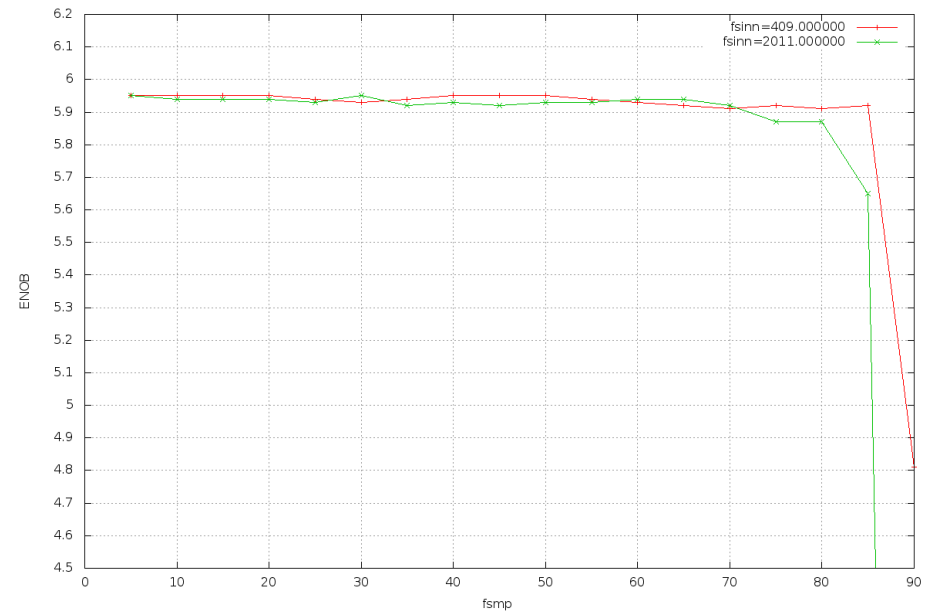
6-bit SAR ADC

Dynamic tests – ENOB effective resolution

Example Fourier spectra @50MHz sampling



Scan vs sampling frequency

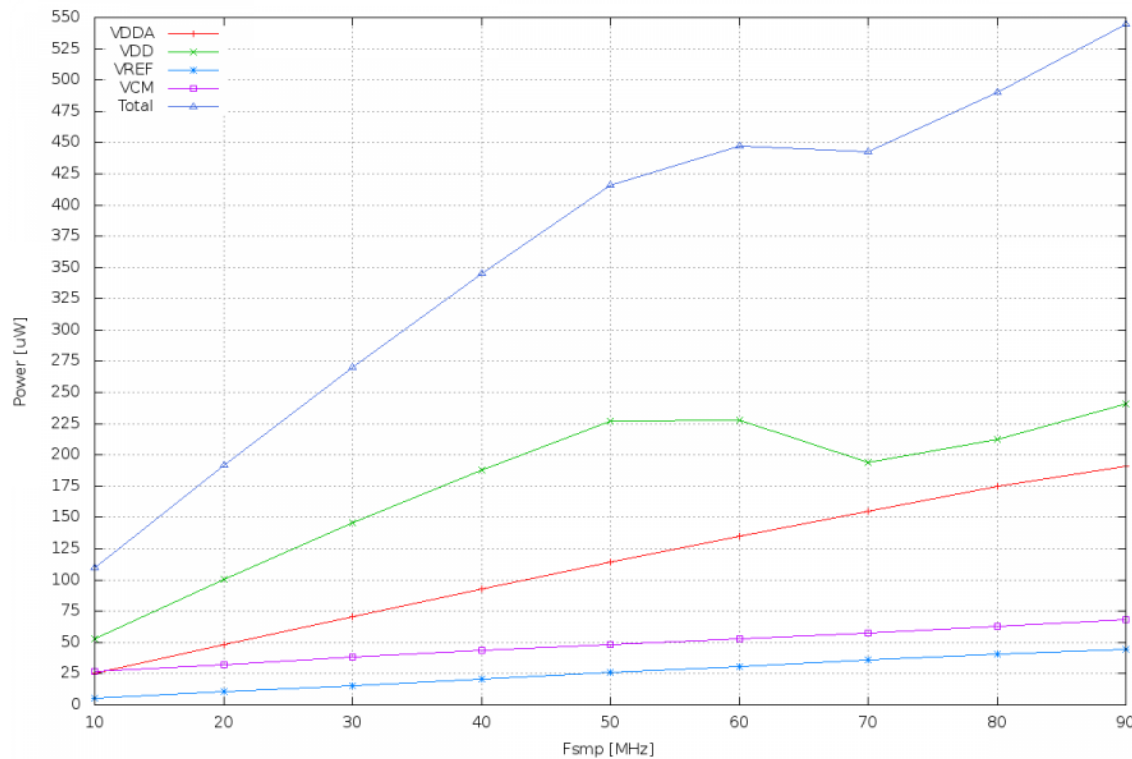


Measurements show very good dynamic behaviour. The measured ENOB is between 5.7 – 5.9 bits. The ADC works well for sampling frequencies beyond 80 MHz.

6-bit SAR - test results

Power consumption

Example power measurements vs sampling frequency



**The 6-bit ADC
sampling at 40MHz
consumes much less
than the front-end !**

FOM ~ 150 fJ/conv

At 40 MHz sampling the total power consumption is around 350uW.

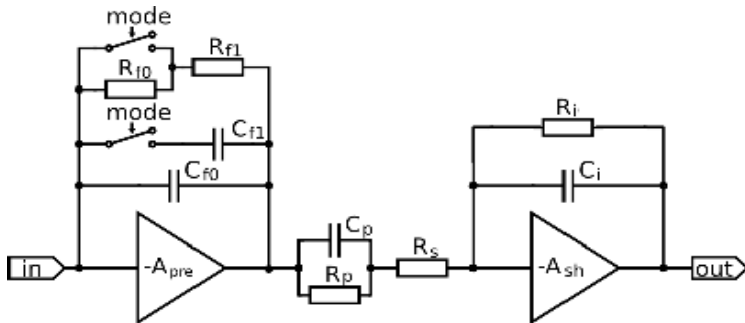
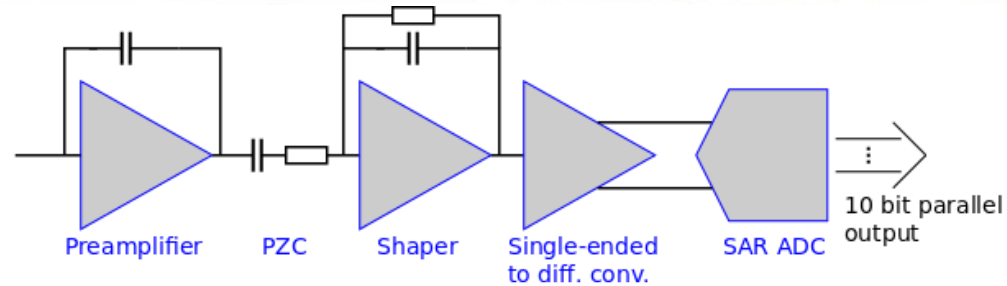
Part II: SAR ADC design and tests

- SAR ADC design
 - Fundamentals
 - DAC Switching energy
 - Other aspects - DAC capacitance, splitted DAC, asynchronous logic, dynamic comparator&logic, bootstrapped switch
- SALT project in IBM CMOS 130 nm
- **LumiCal readout in IBM CMOS 130 nm**
- Multichannel ADC aspects: PLL, sampling pulse, I/O SLVS, Single-to-Differential converter
- Summary

New readout electronics for luminosity calorimeter in IBM CMOS 130 nm

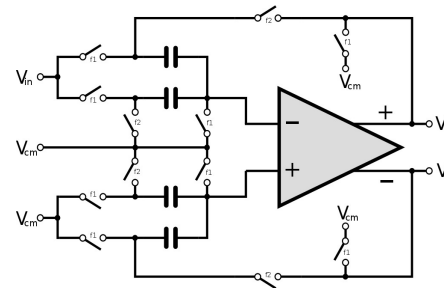
Design and technology comparison

New readout in 130 nm has very similar architecture to existing one in 0.35um but should consume much less power and be radiation resistant



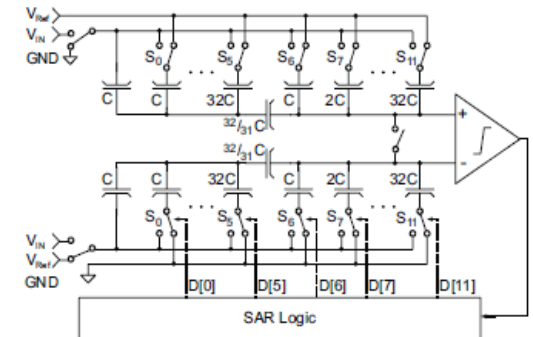
Front-end specs:

- $C_{det} \approx 5 \div 50 \text{ pF}$
- 1st order shaper ($T_{peak} \approx 50 \text{ ns}$)
- Variable gain, two modes:
 - calibration: MIP sensitivity
 - physics: Q_{in} up to $\sim 6 \text{ pC}$
- Power pulsing
- Peak power cons. $\sim 1.5 \text{ mW/channel}$ (in AMS 0.35um it was $\sim 9 \text{ mW}$)



Single-to-Diff specs:

- Max freq. $> 40 \text{ MHz}$
- Power pulsing
- Peak power $\sim 0.5 \text{ mW}$

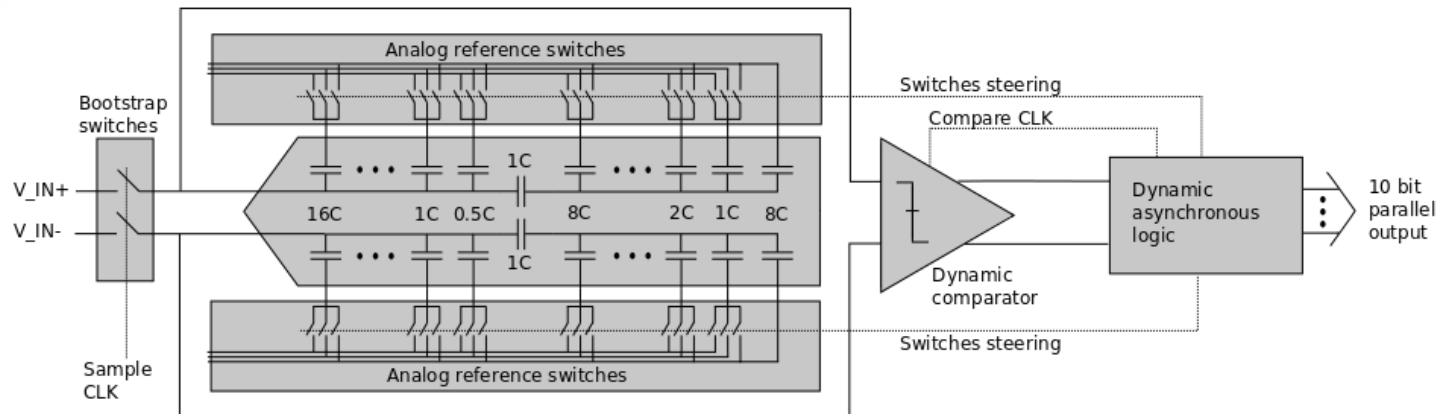


ADC specs:

- 10-bit resolution
- Architecture: SAR ADC
- Max frequency $> 40 \text{ MHz}$
- Power pulsing
- Peak power $\sim 1 \text{ mW @40MHz}$ (in AMS 0.35um it would be $> 40 \text{ mW}$)

Design of SAR ADC

Chosen architecture of 10-bit SAR ADC



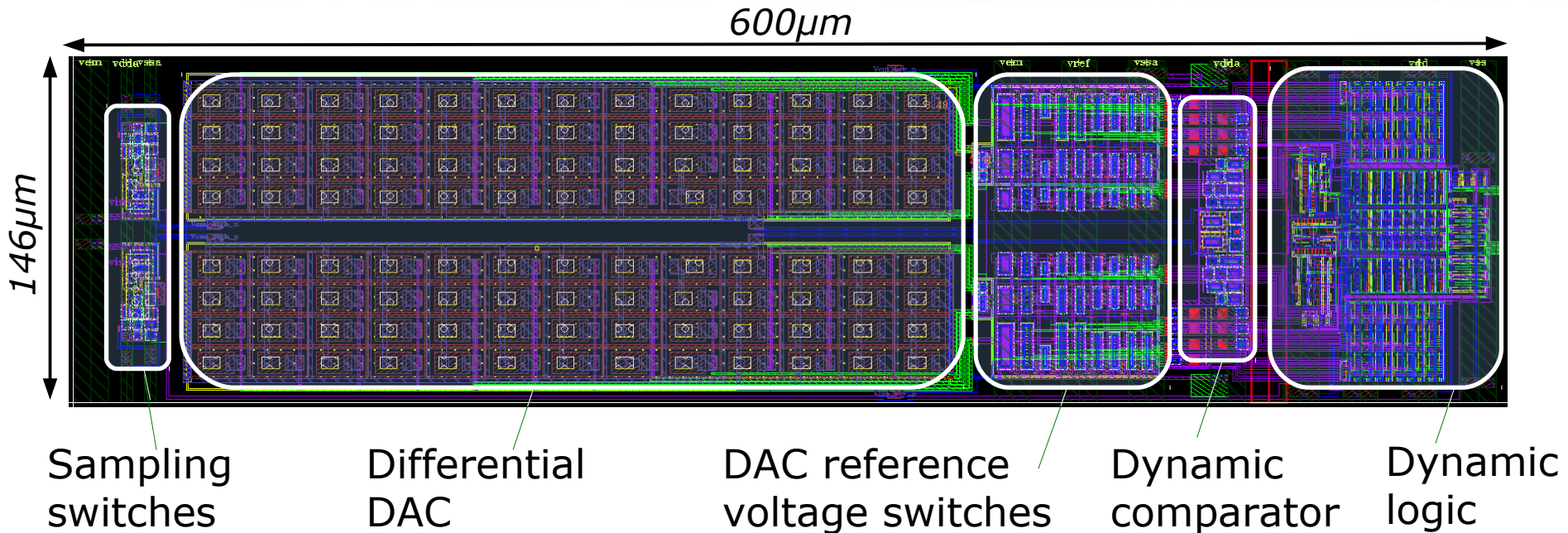
Architecture of 10-bit ADC

- Differential segmented/split DAC with MCS switching scheme – **ultra low power**
- Dynamic comparator – **no static power consumption, power pulsing for free**
- Asynchronous logic – no clock tree – **power saving, allows asynchronous sampling**
- Dynamic SAR logic – **much faster than conventional static logic**
- Bootstrapped sampling switch – **improves linearity**

Design consideration:

- Variable sampling frequency (up to ~ 50 MS/s) and power consumption
- Power consumption ~ 1 mW at 40 MS/s
- 146 μm pitch, ready for multichannel integration

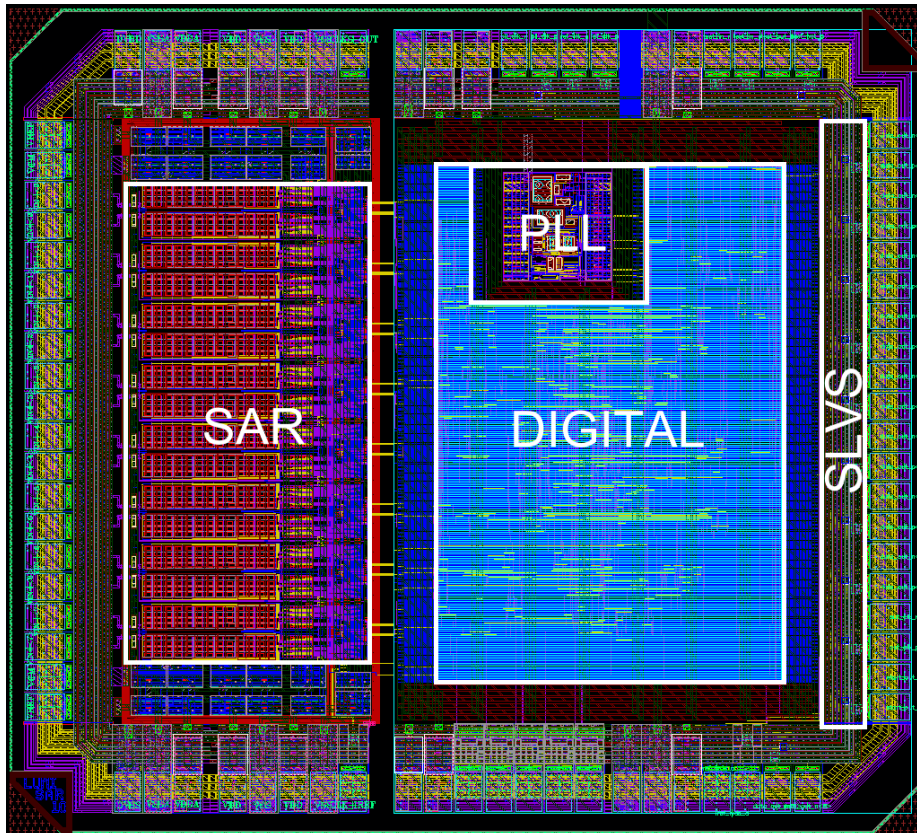
Design of 10-bit SAR in IBM 130nm



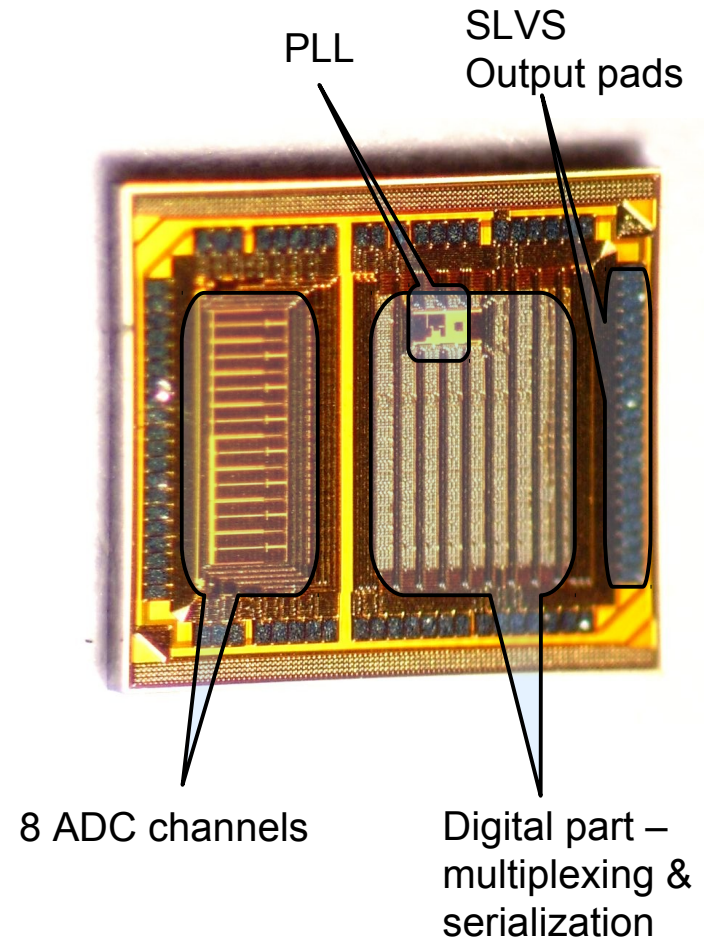
Main features of ADC in IBM 130 nm

- Simulated ENOB \approx 9.5-9.7 bits
- Maximum sampling rate \sim 50 MS/s
- Power consumption \approx 1-1.4mW @ 40 MS/s
- No dummy capacitors in DAC network!

8 channel 10-bit SAR ADC in IBM 130 nm



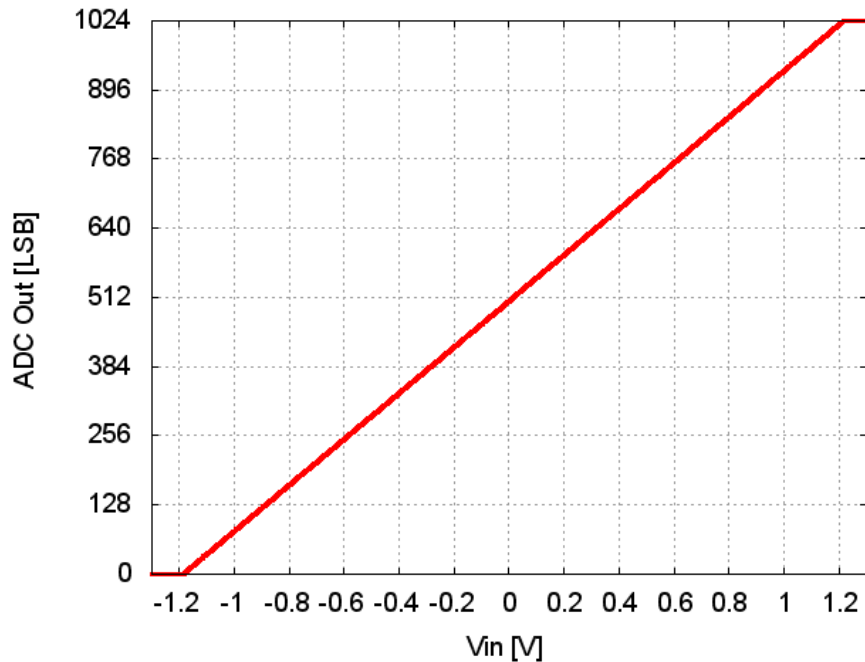
2200um x 2000um



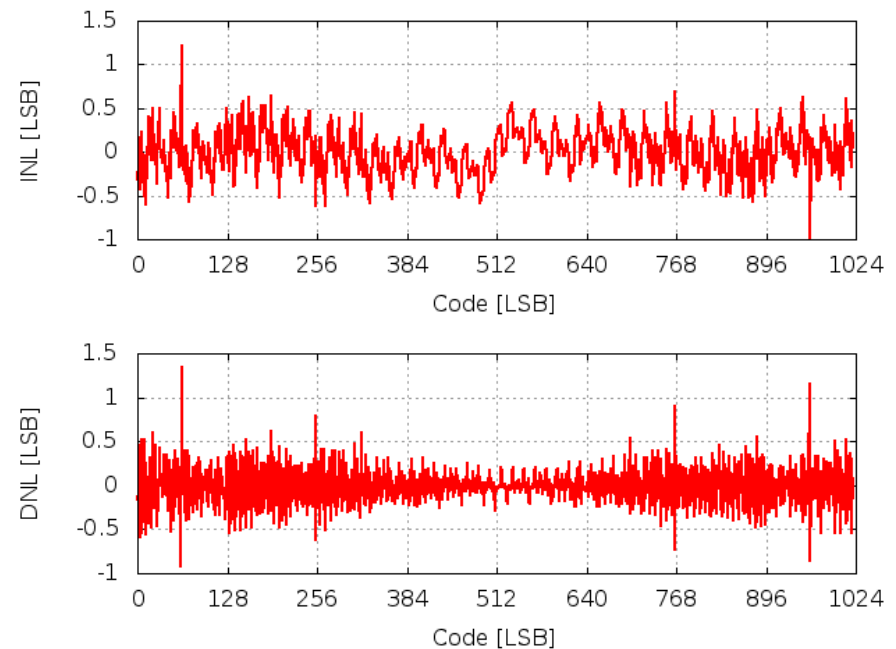
Measurements results

10-bit SAR ADC - Static measurements

Transfer function



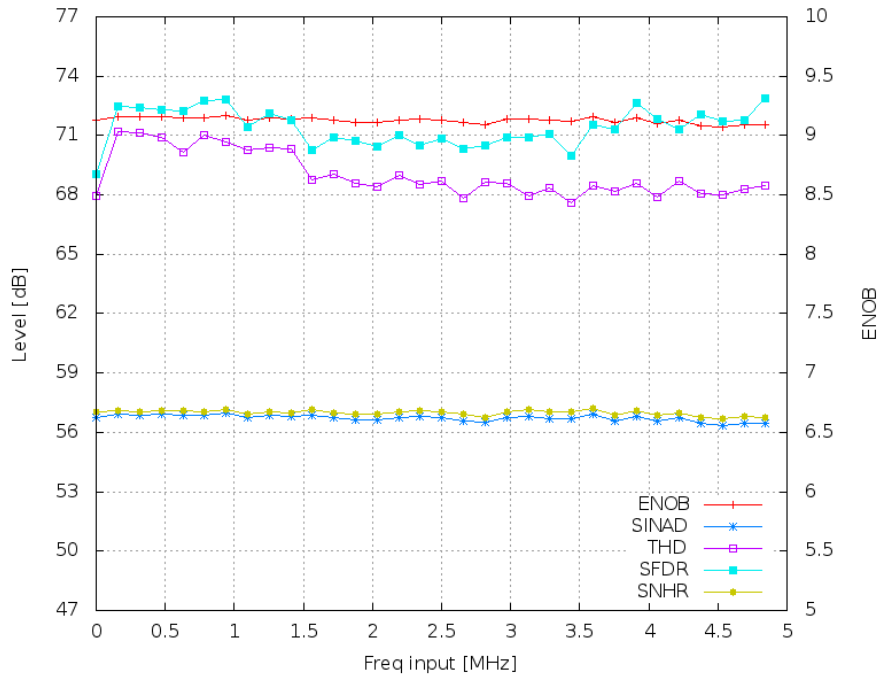
INL/DNL measurements



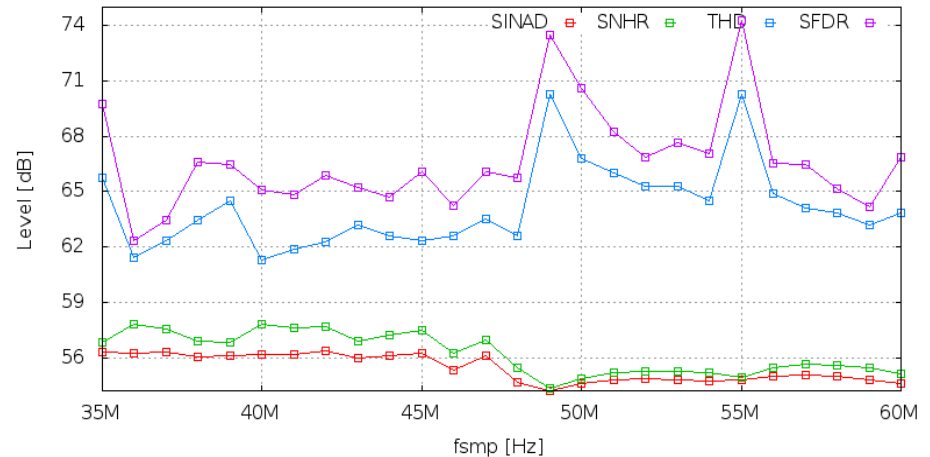
- ADC is alive and works in the whole input signal range
- There are some codes with worse linearity (some improvements in DAC layout are needed)

Measurements results: Dynamic measurements

Dynamic measurements @10MHz

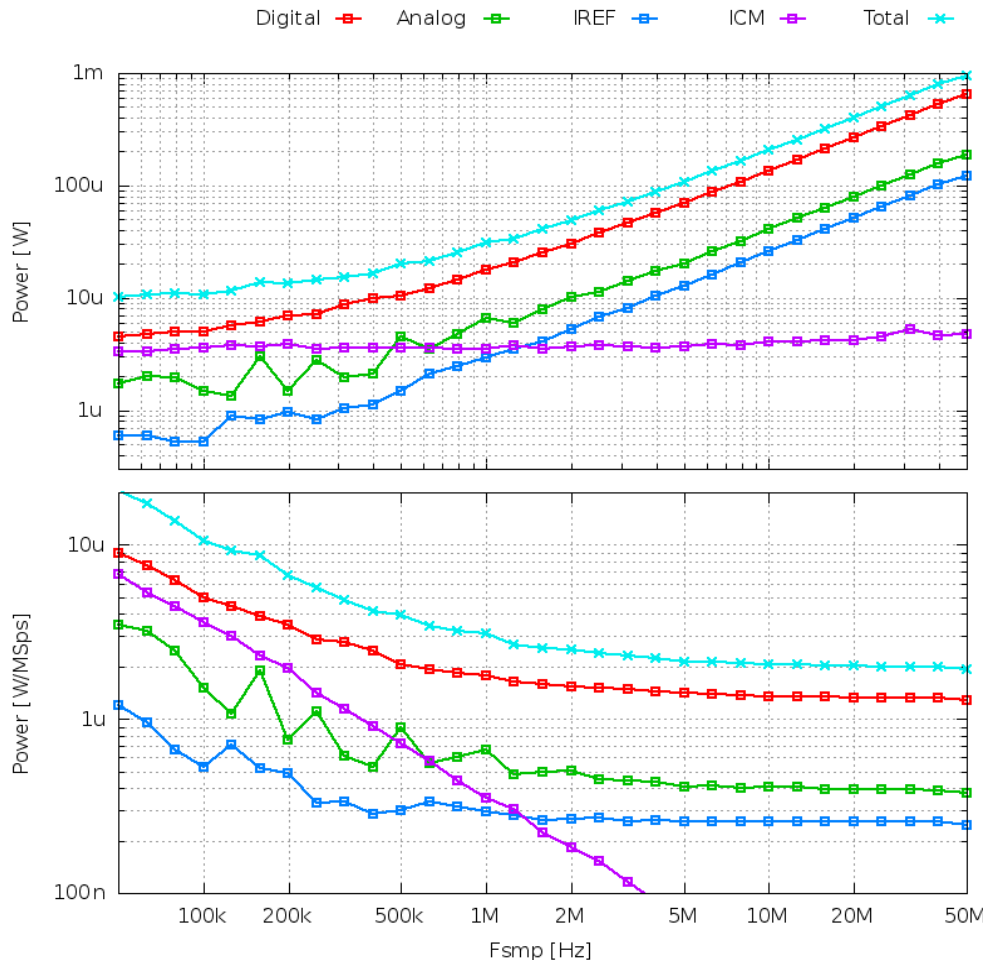


ENOB ~ 9.2 up to Nyquist input frequency for $f_{\text{sample}} \sim 20\text{MHz}$



ADC works for f_{sample} up to about 60MHz, but above 20 MHz ENOB start to decrease. Problem with jitter found..., will be fixed in next submission.

Measurements results of 10-bit SAR ADC Power consumption



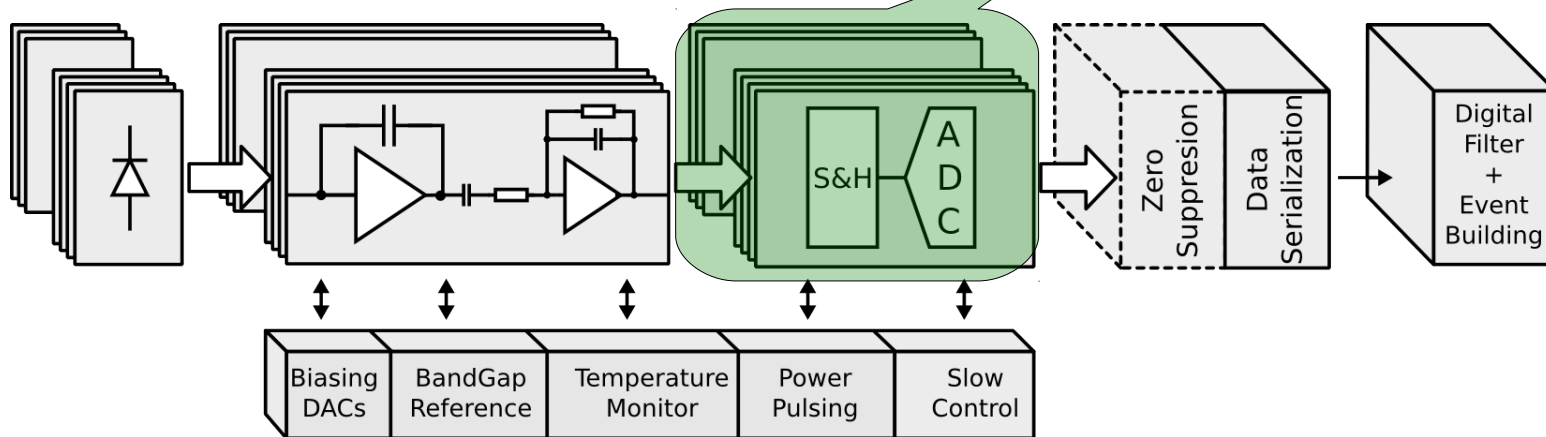
- Power consumption \sim **1 mW** per channel at 40 MS/s (**40 times less than pipeline ADC in AMS 0.35 μ m**)
- 10-bit ADC sampling at 40MHz consumes less than the front-end !
- FOM \sim 50fJ/conv.

Part II: SAR ADC design and tests

- SAR ADC design
 - Fundamentals
 - DAC Switching energy
 - Other aspects - DAC capacitance, splitted DAC, asynchronous logic, dynamic comparator&logic, bootstrapped switch
- SALT project in IBM CMOS 130 nm
- LumiCal readout in IBM CMOS 130 nm
- **Multichannel ADC aspects: PLL, sampling pulse, I/O SLVS, Single-to-Differential converter**
- Summary

Multichannel ADC aspects

Main challenge – ADC power consumption!

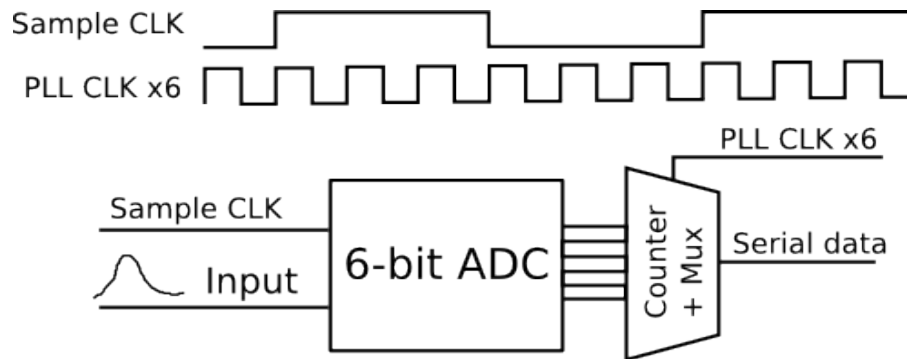


Multichannel readout with ADC conversion becomes real SoC (System on Chip) and needs peripheral circuits:

- PLL/DLL for data multiplexing&serialization, DACs , Slow control eg. SPI or I2C, voltage reference (bandgap), temperature sensor (PTAT), I/O circuits like LVDS/SLVS, DSP, etc...

Multichannel ADC aspects

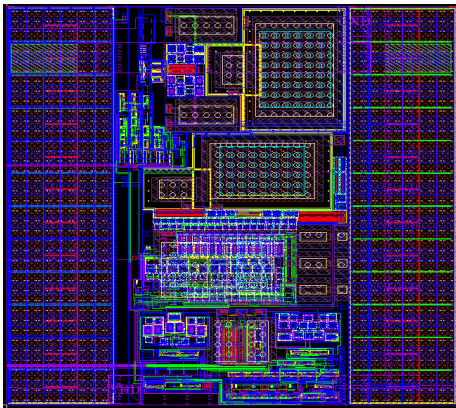
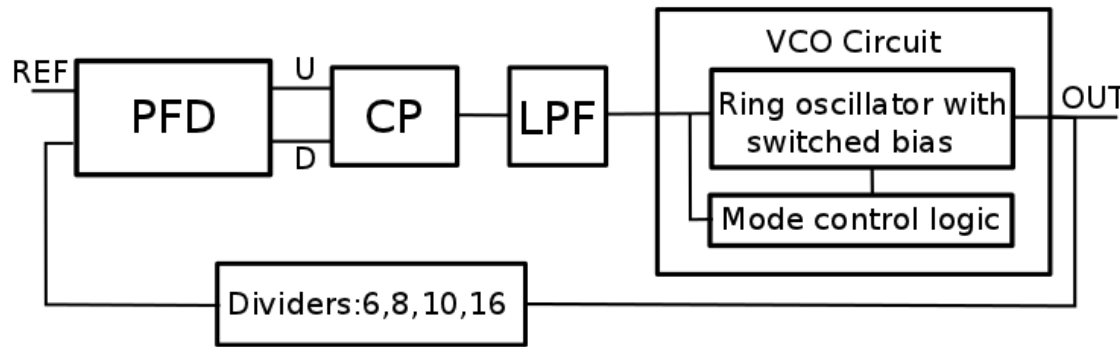
Phase-Locked Loop (PLL) - key block for high speed clock generation and data serialization



Example PLL needed to multiply sampling CLK frequency by 6

- Flexible PLL needed for data serialization in future readouts
 - different division factors needed for 6(10)-bit ADCs and maybe also for different numbers of ADC channels
 - variable frequency PLL needed for different sampling rate ADC
- Low power consumption is default requirement

Multichannel ADC aspects PLL design in IBM 130 nm



300 x 300 μm

PLL features:

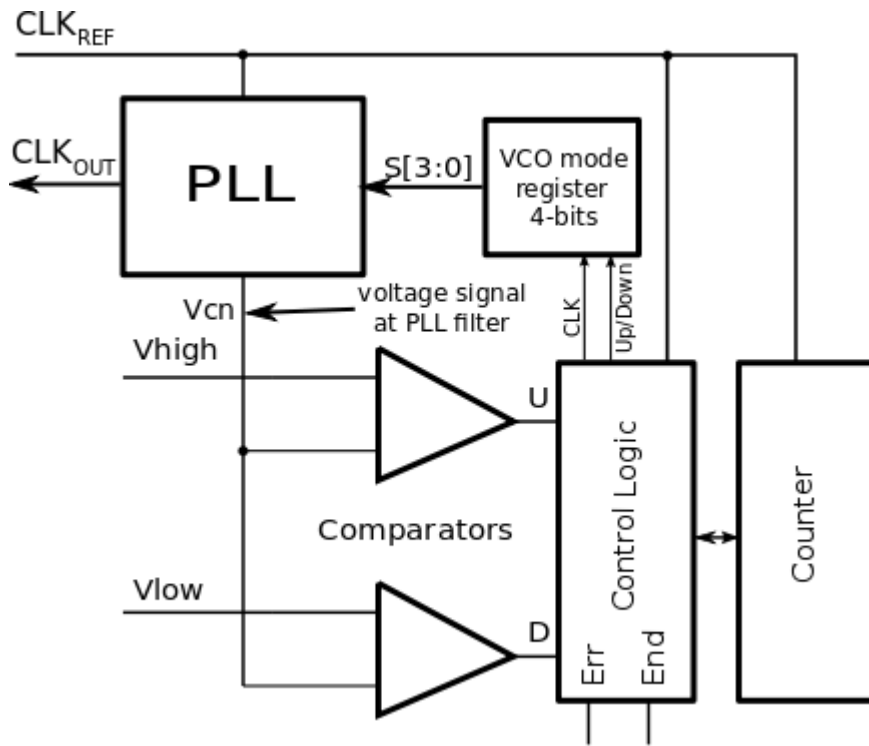
- General purpose PLL block
- Very wide output frequency range (10MHz - 3.5GHz)
- 16 VCO modes - Automatically (or manually) changed
- Jitter 15-70 ps (to be improved...)
- Power consumption $\sim 0.6\text{mW}@1\text{GHz}$
- Different loop division factors: 6,8,10 and 16



AGH

Multichannel ADC aspects PLL design in IBM 130 nm

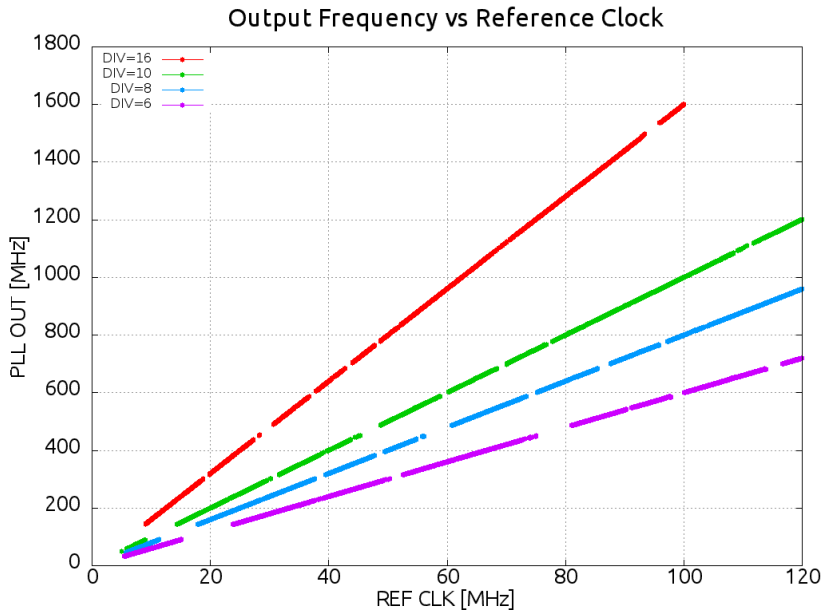
PLL - principle of automatic VCO mode change



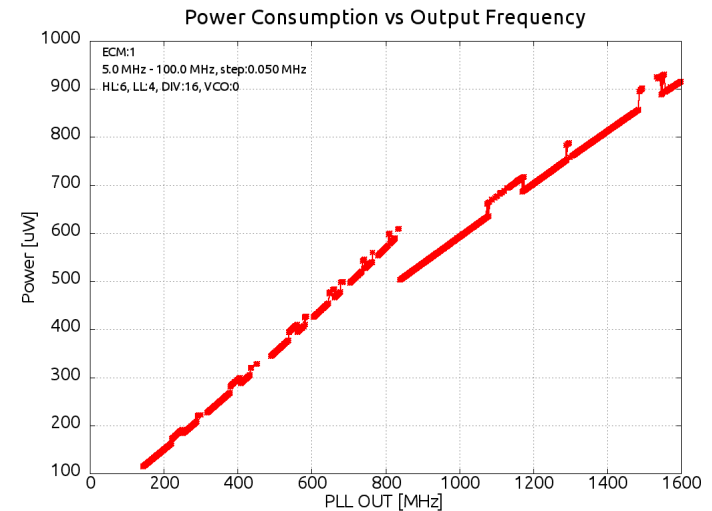
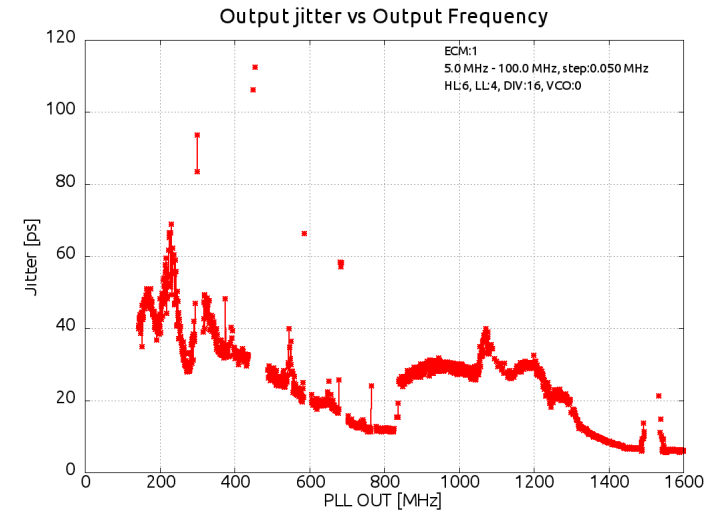
- Comparators check whether a voltage signal at the PLL filter (V_{cn}) is greater than V_{high} or lower than V_{low} .
 - If $V_{cn} > V_{high}$ (VCO too slow) for certain period (measured by counter) control logic switches the mode register to faster mode (up).
 - If $V_{cn} < V_{low}$ (VCO too fast) VCO mode register is switched to slower mode (down).
 - When V_{cn} voltage stays between V_{high} and V_{low} the mode is not changed.

Multichannel ADC aspects

Performance of PLL prototype in IBM 130 nm

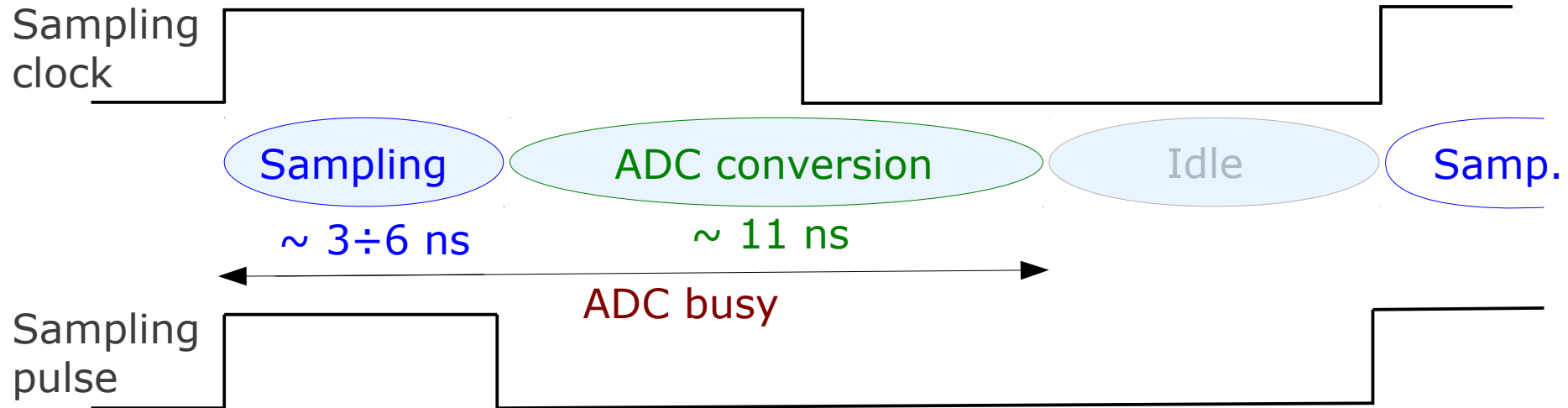


- Measurements confirm proper circuit operation in frequency range 20MHz-1.6GHz
- All four division factors work properly
- Automatic mode change positively verified
- Power consumption scales linearly with PLL clock frequency (two rings → two curves)



Multichannel ADC aspects

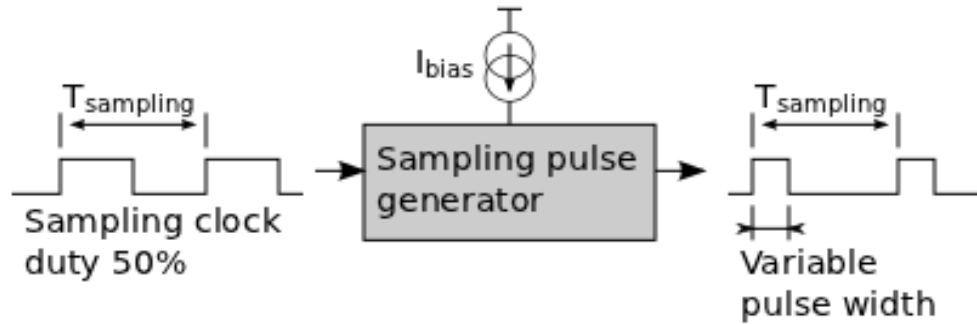
Generation of sampling pulse



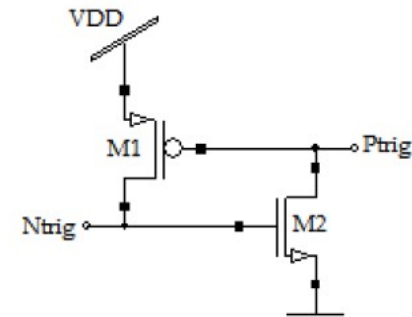
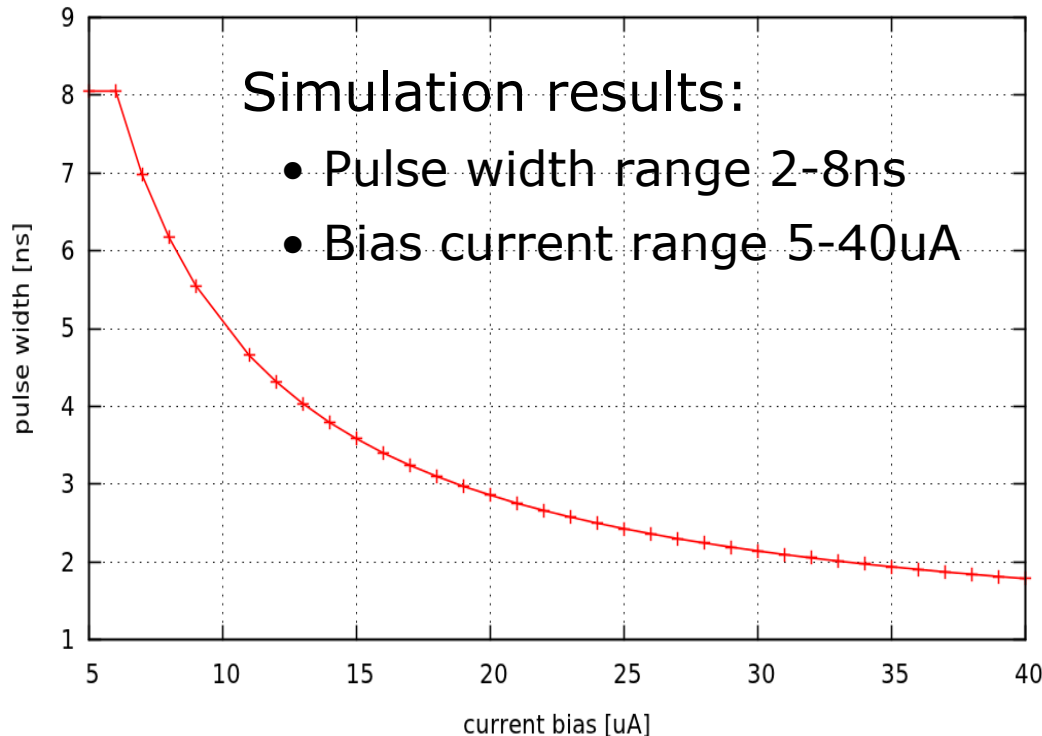
- ADC works with 50% duty cycle sample clock
- Input signal sampling time should be tuned:
 - If too short - decrease resolution
 - If too long - lowers maximum sampling frequency
- Current steered width pulse generator providing sample timing designed

Multichannel ADC aspects

Design of sampling pulse generator



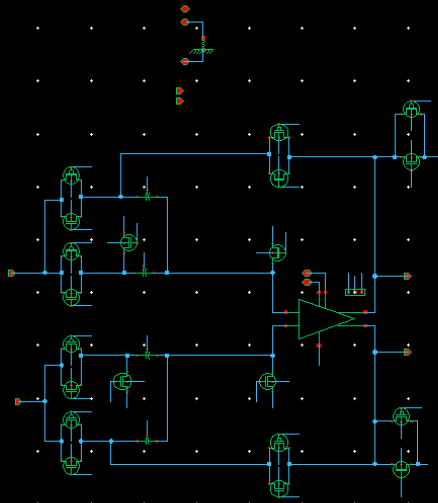
Generator of sampling pulse converts 50% duty external sampling clock into internal variable width pulse (controlled by I_{bias})



Pulse generator design is based on MOS thyristor delay circuit.

Multichannel ADC aspects

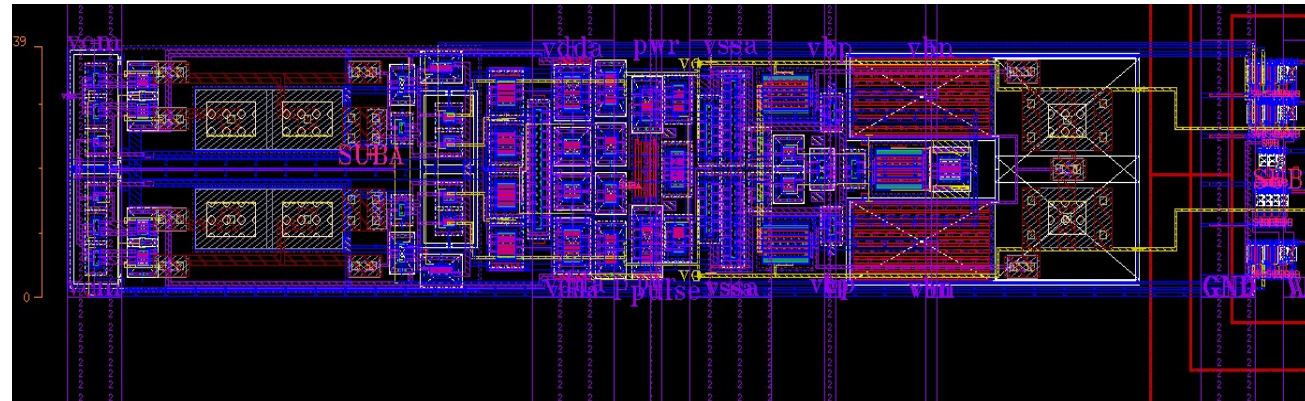
Design of Single-to-Differential converter in IBM 130 nm



Typically front-end electronics has single-ended output. In such case a Single-to-Differential converter is needed.

Main features of Single-to-Differential converter:

- Architecture: differential switched-capacitor amplifier
- Recycled folded cascode as amplifying stage
- Gain = 2
- Simulated power consumption ~0.25mW for 6-bit ADC and ~0.5mW for 10-bit ADC



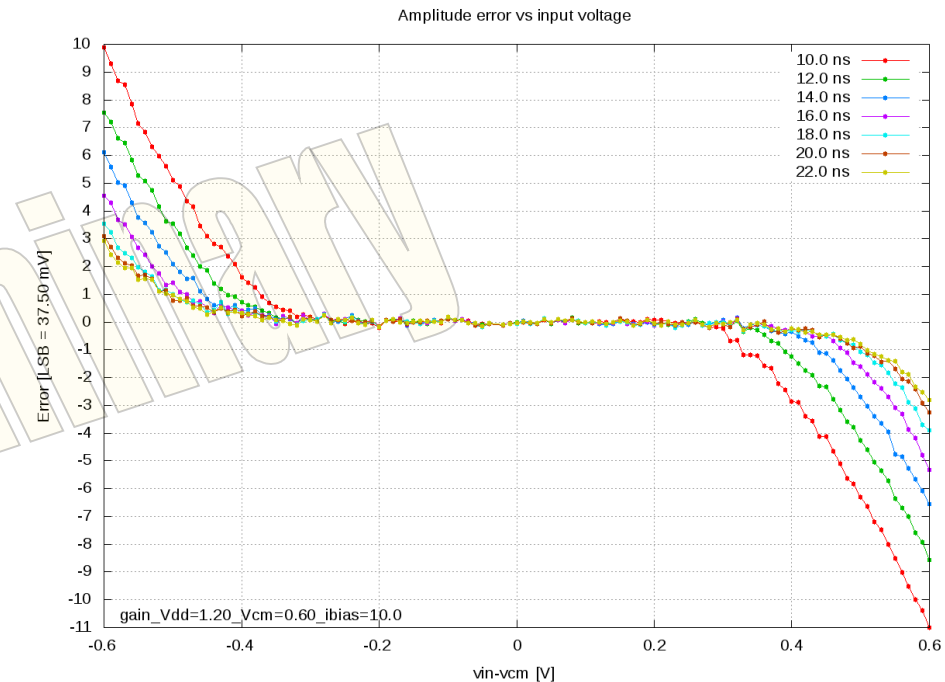
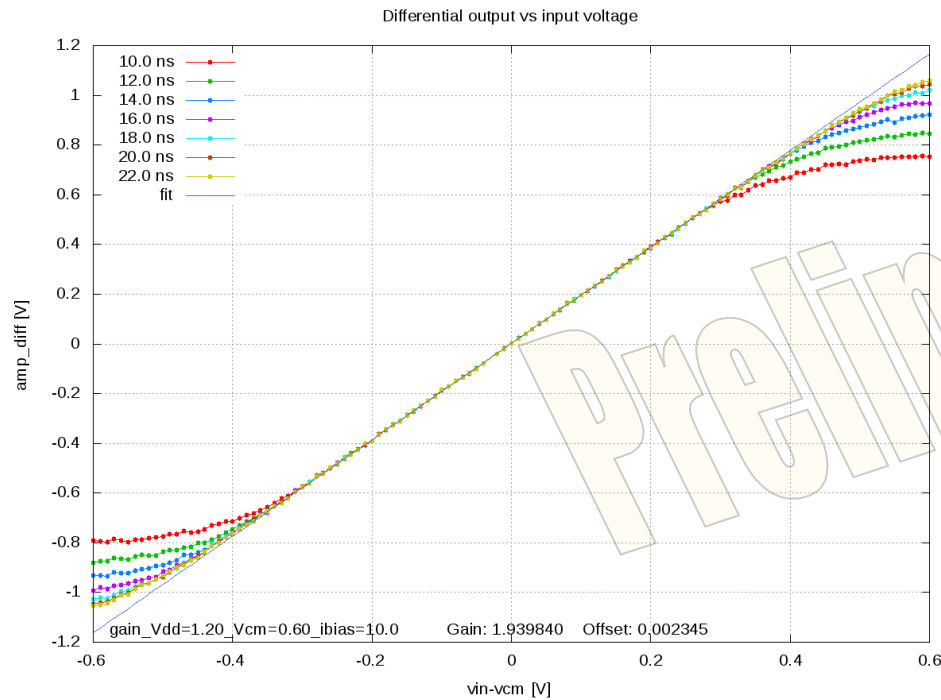
Multichannel ADC aspects

Single-to-Differential converter for 6-bit ADC

Preliminary measurements

Transfer curve of S-to-Diff converter for different sampling times

Error of S-toDiff transfer curve in LSB for different sampling times

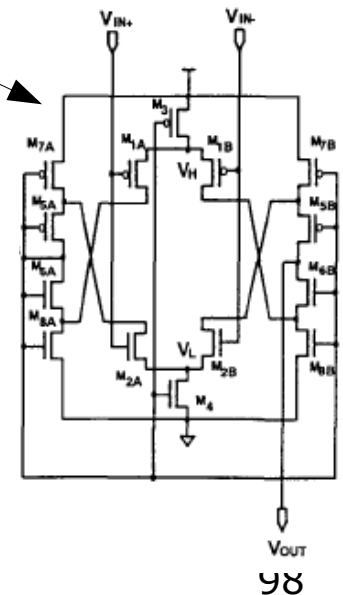
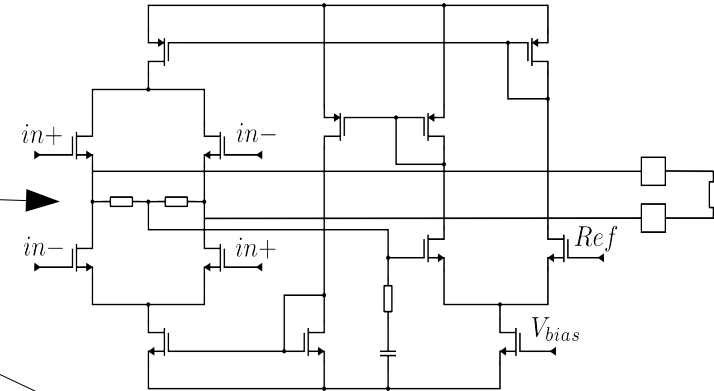


Good linearity is kept for more than half of input signal range

Multichannel ADC aspects

Design of SLVS interface

- Specifications:
 - Architecture
 - Driver – based on Boni paper
 - Receiver – based on self-biased amplifier (Bazes paper)
 - Technology – IBM 130 nm
 - Maximum frequency $\sim 1\text{GHz}$
 - Pitch matched to pads. Driver/receiver integrated with 2 pads (146 μm pitch)

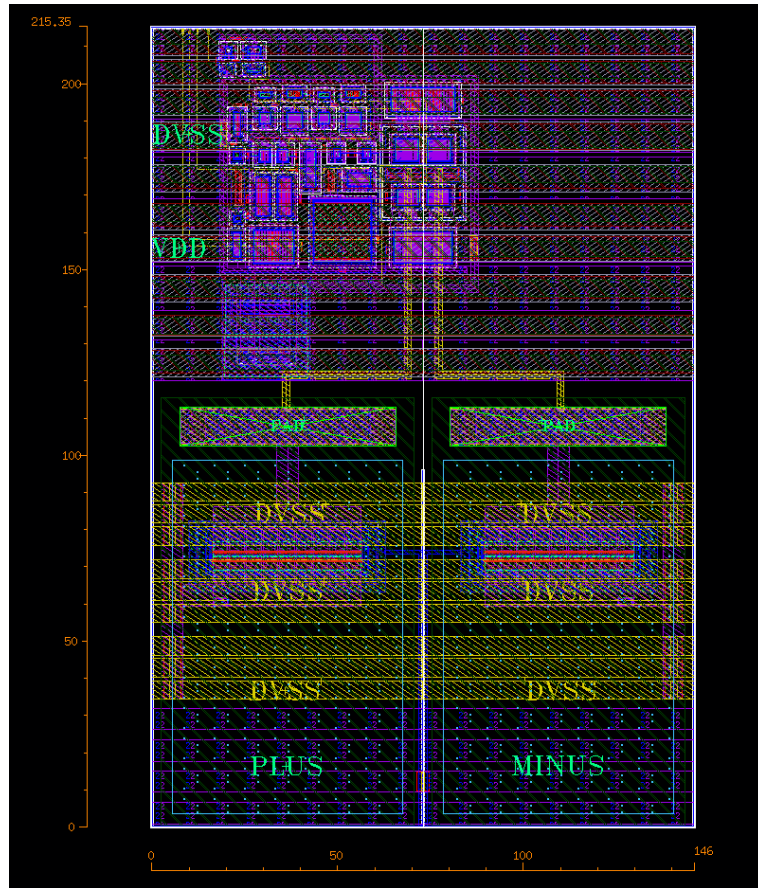


A. Boni, A. Pierazzi, D. Vecchi, LVDS I/O Interface for Gb/s-per-Pin Operation in 0.35 μm CMOS, IEEE J. Solid-State Circuits, vol. 36, no. 4, pp. 706–711, April 2001

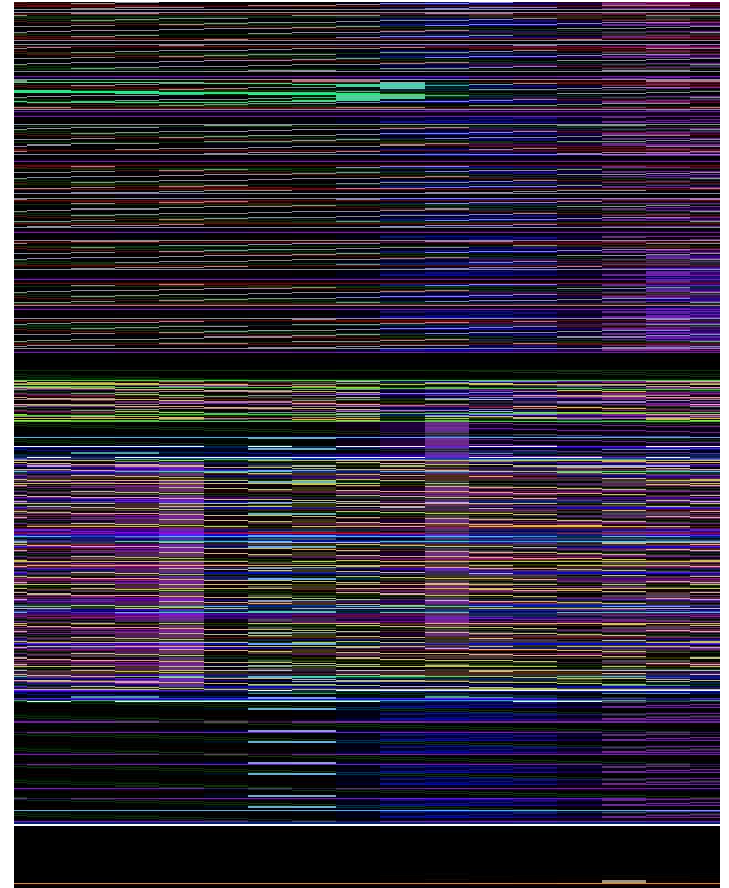
M. Bazes, Two Novel Fully Complementary Self-Biased CMOS Differential Amplifiers, IEEE J. Solid-State Circuits, vol. 26, no. 2, pp. 165–168, February 1991.

Multichannel ADC aspects SLVS interface as differential I/O pads

Driver



Receiver



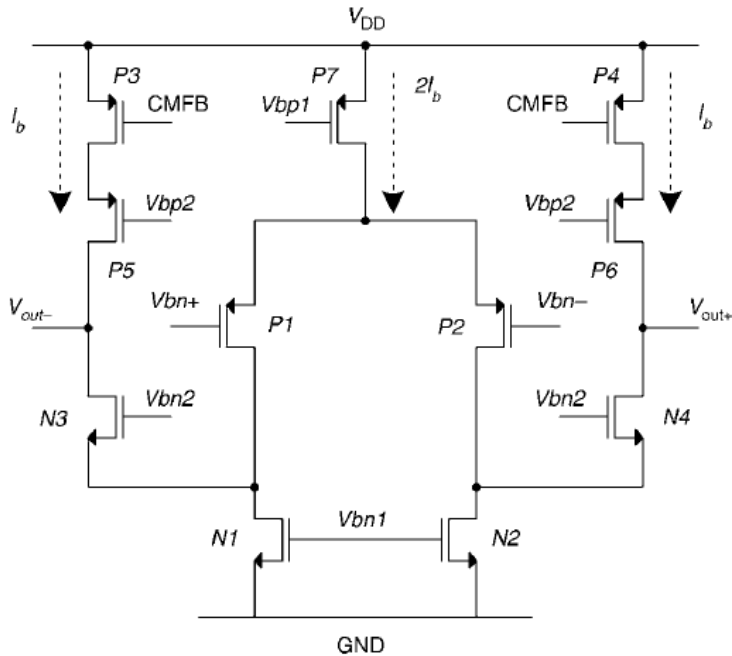
Functionality verified during ADC and PLL test up to ~1.5 GHz.
Dedicated quantitative tests not yet done (waiting in line...)

Summary

- Potential of deep-submicron CMOS technologies, together with recent developments in ADC architectures – SAR in particular, allow to build multichannel front-end ASICs comprising ADC in each channel, without penalty on power consumption
 - Modern ADC can consume significantly less power than preamp&shaper circuitry
- Multichannel readout ASIC with ADC becomes complex Systems on Chip (comprise hundreds of channels, front-end, ADC, DSP, PLL, DLL, serializer/deserializer, digital interfaces, etc...)
 - Various ADC aspects (e.g. reference voltage design) were not covered in this presentation...

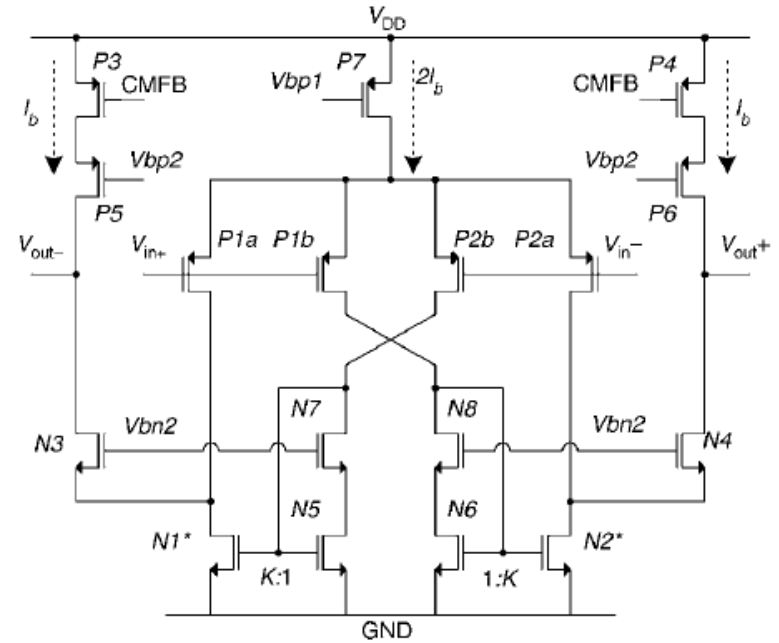
Thank you for attention

Sampling amplifier issues



Conventional folded cascode (FC)

$$Gm_{FC} = gm_{P1}, SR_{FC} = 2I_b / C_L$$



Recycling folded cascode (RFC)

$$Gm_{RFC} = gm_{P1} (1+K), SR_{RFC} = 2KI_b / C_L$$

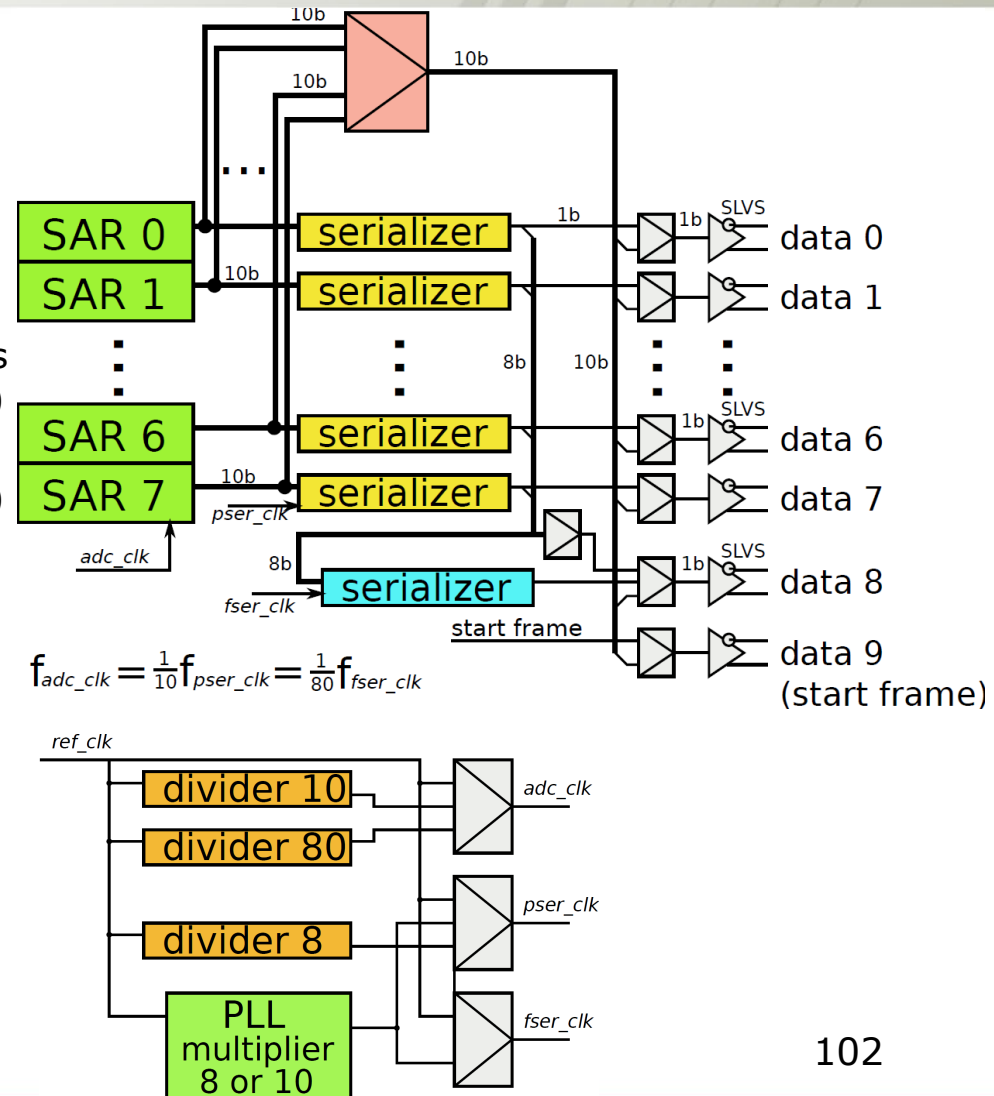
In 130nm a gain of few hundred may be achieved. For 10-bit accuracy a second stage or a gain boosting is needed

Design of SAR multichannel ADC

Specifications & implementation issues:

- 8 channels of 10-bit (6-bit) SAR ADC
- Technology IBM 130 nm
- Layout with 146um (40um) ADC pitch
- Multimode digital multiplexer/serializer:
 - Serial mode: one data link per all channels (external clk division or PLL clk generation)
 - Parallel mode: one data link per channel (external clk division or PLL clk generation)
 - Test mode: single channel output (max fsmp ~50 Msp/s)

- PLL for data serialization
- High speed SLVS interface (~1GHz)
- Power pulsing
- Generation of short sampling pulse
- Bootstrapped S/H switches
- Voltage reference not yet addressed...
- SingleEnded-to-Differential converter ??



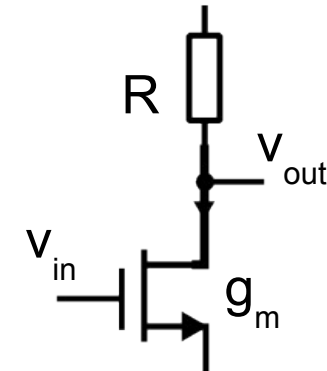
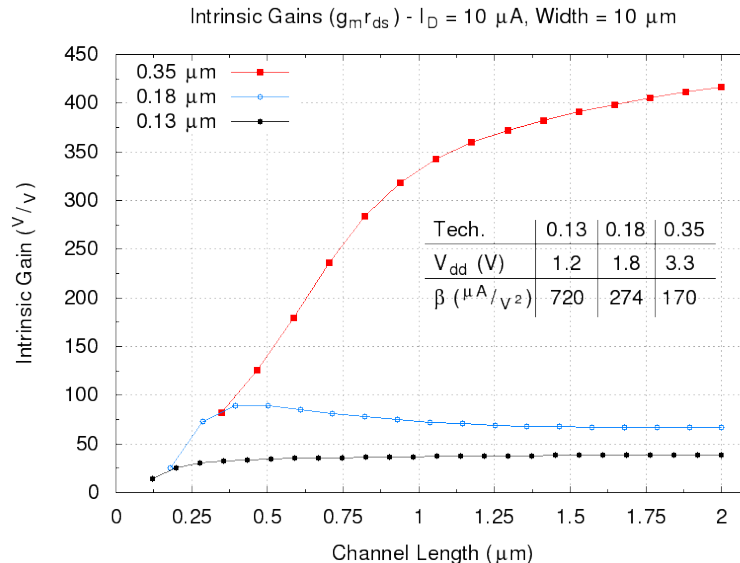
Design in deep sub-micron CMOS

Comparison of CMOS generations

Technology nodes used in HEP: 350nm – 250nm – 180nm – 130nm - 65nm
 LHC FAIR SLHC/LC

Modern CMOS processes offer: higher speed, lower power, smaller area, better radiation hardness,

Intrinsic gain
Of NMOS



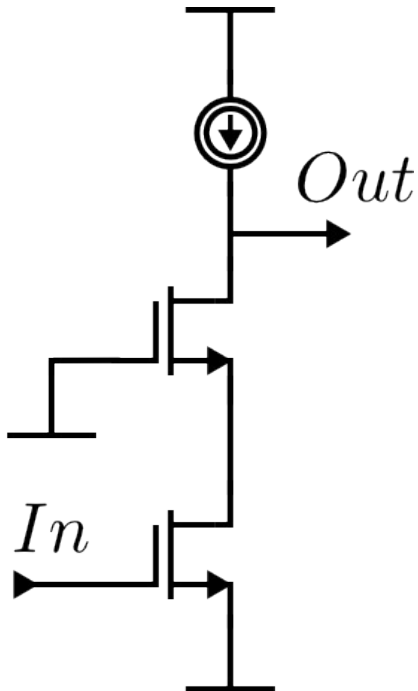
but also lower gain..., and hundreds of design rules

Design in deep sub-micron CMOS has become much more difficult !103

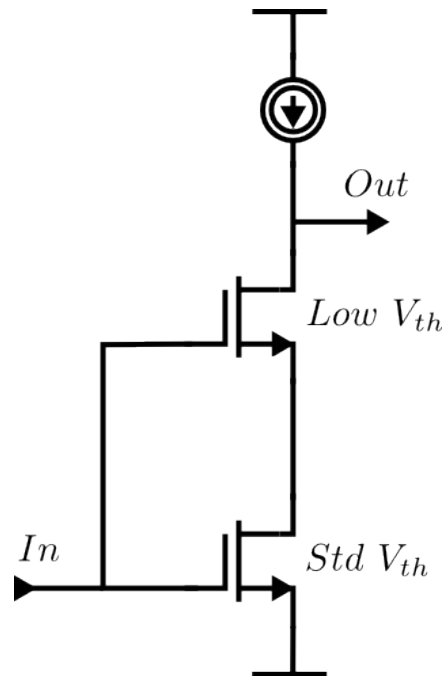
Main front-end block: Amplifier

Amplifier design in deep sub-micron CMOS

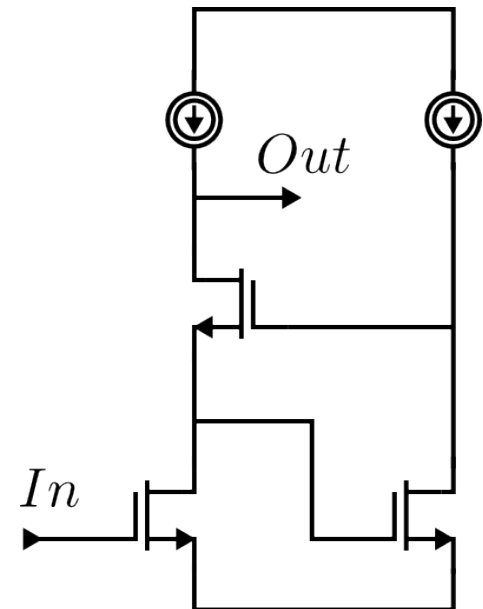
Cascode amplifier



Self-Cascode



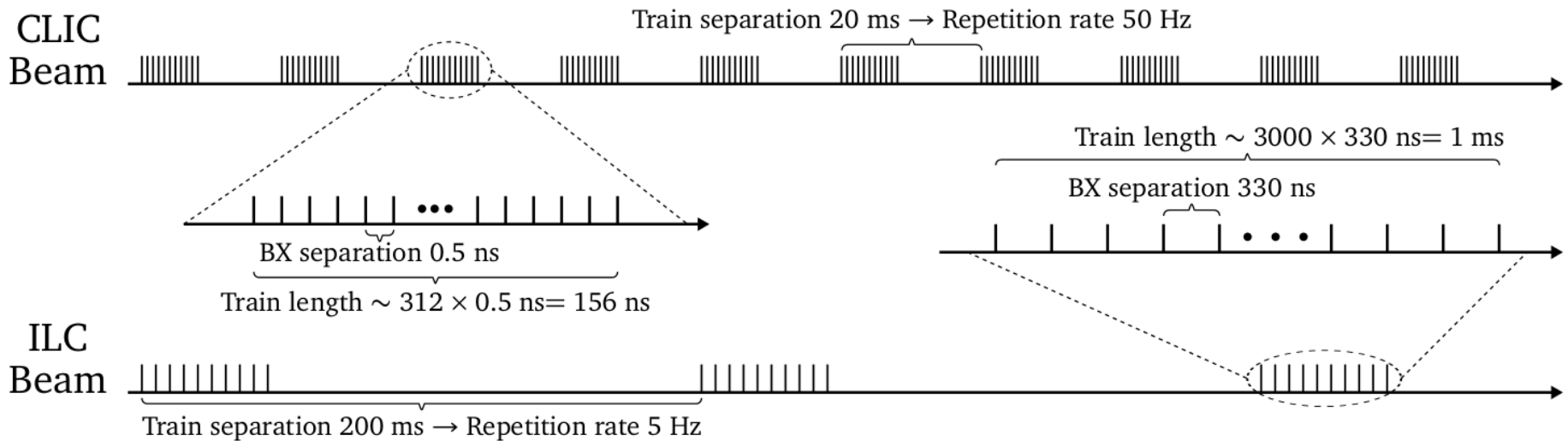
Regulated cascode (gain boosting)



Low intrinsic gain and small power supply voltage make amplifier design difficult. It is a challenge to obtain gain > 1000 in 130 nm CMOS !

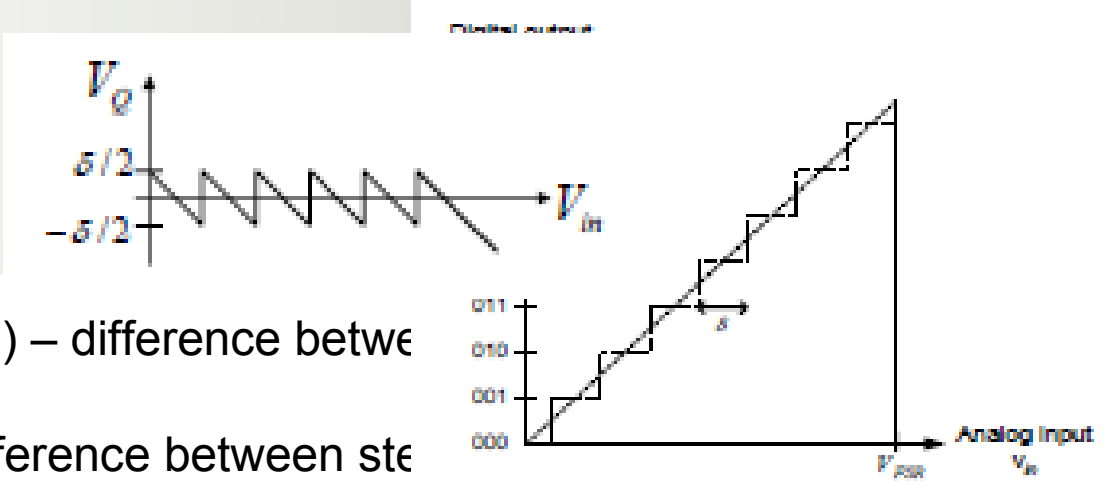
Readout electronics for future linear colliders

Power pulsing needed for huge power savings



- Very low duty cycle ($\ll 1\%$).
- The average power consumption can be dramatically reduced by turning the power off between the trains.
- Readout electronics should allow fast power switching.

Real ADC Static errors



Differential Non-Linearity (DNL) – difference between step widths

Integral Non-Linearity (INL) difference between step widths and a best fit line

Missing Codes – excessive DNL leads to missed codes in ADC

Non-Monotonicity – excessive DNL leads to non-monotonic behavior in ADC

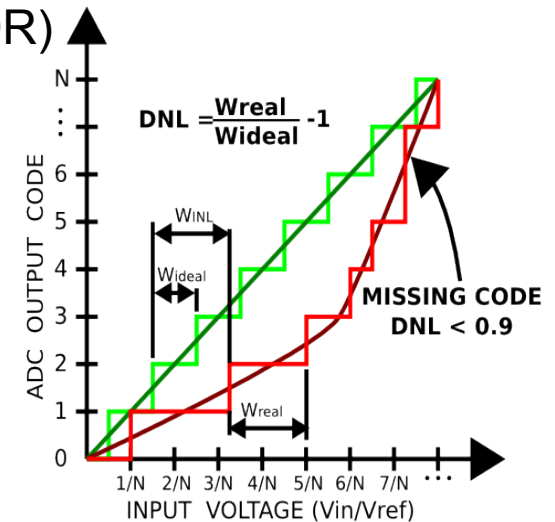
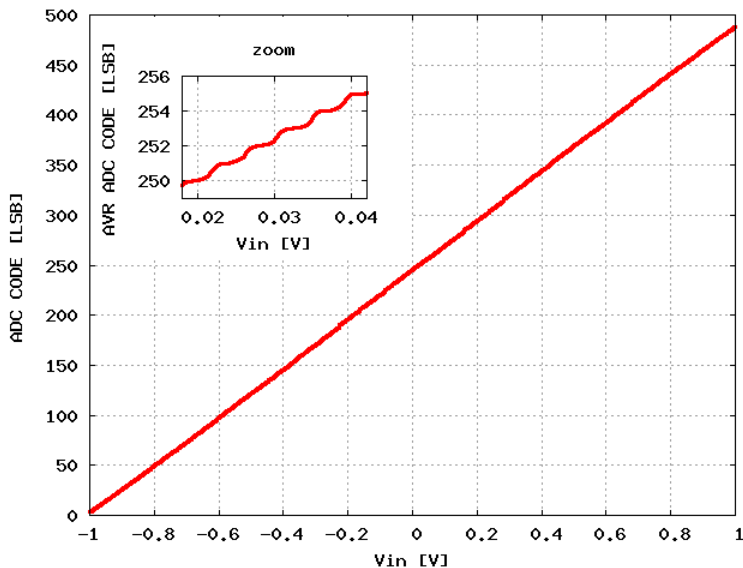
Offset error

Gain error

Signal-to-Noise and Distortion (SINAD)

Spurious Free Dynamic Range (SFDR)

— IDEAL TRANSFER FUNCTION
— REAL TRANSFER FUNCTION





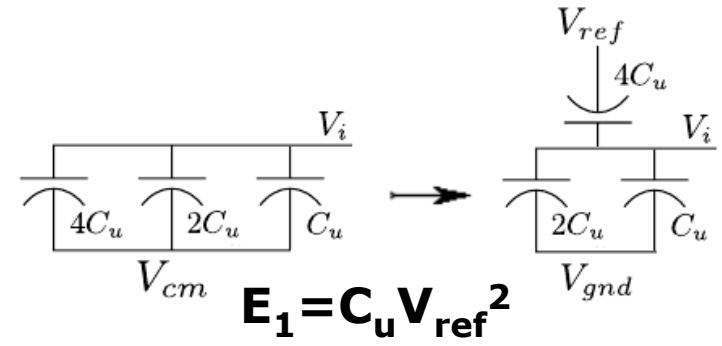
AGH

Key aspects of DAC in SAR ADC

DAC switching energy:

Principle 2-bit capacitor array example

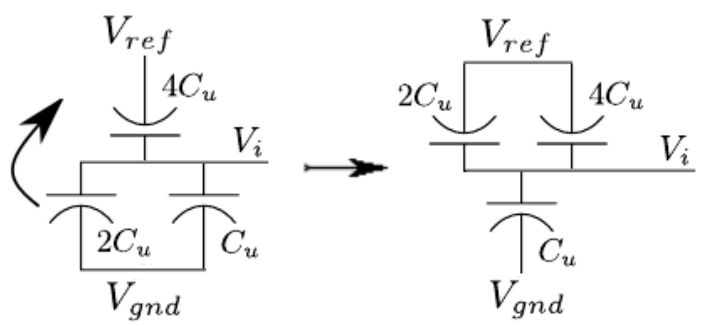
- Energy drawn from V_{ref} : $E = V_{ref} \circ \Delta Q$
- a) **up** transitions - nC_u short to V_{ref}
- b) **down** transitions - nC_u short to V_{gnd}



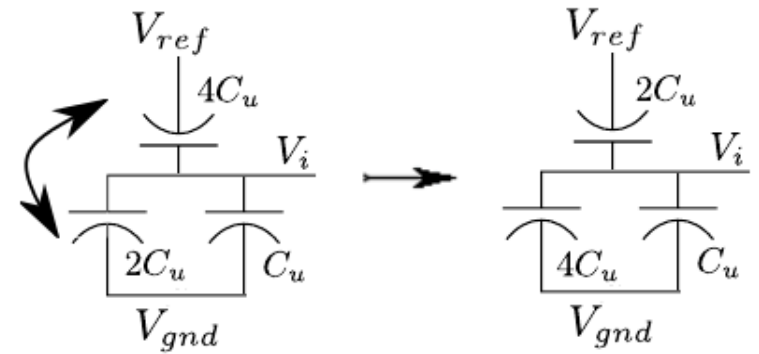
1) $4C_u$ goes **up**, $2C_u$ and C_u goes **down**:

2a) If $V_{in} > \frac{1}{2}V_{ref}$ then only $2C_u$ goes **up**:

2b) otherwise $2C_u$ goes **up** and $4C_u$ goes **down**:



$$E_{2up} = \frac{1}{4} C_u V_{ref}^2$$

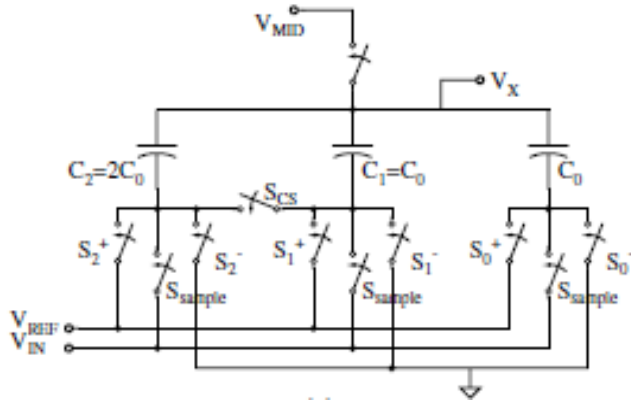


$$E_{2down} = 5 \circ \frac{1}{4} C_u V_{ref}^2 = 5 \circ E_{2up}$$

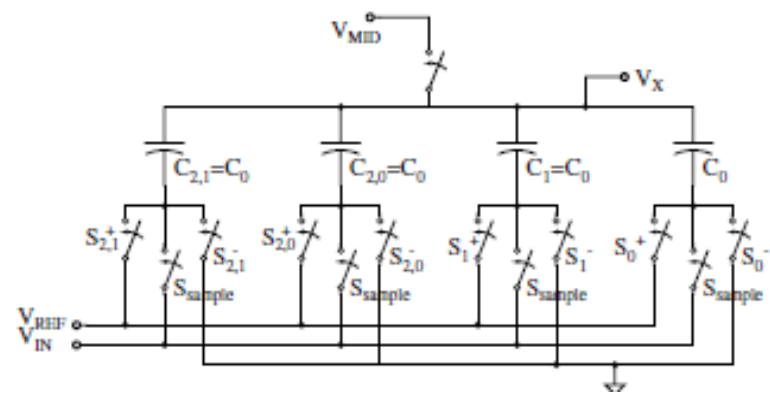
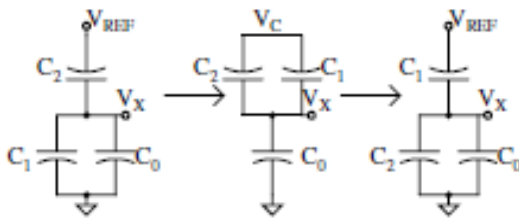
down transitions consume much power...

Switching energy – principle 2-bit capacitor array example...

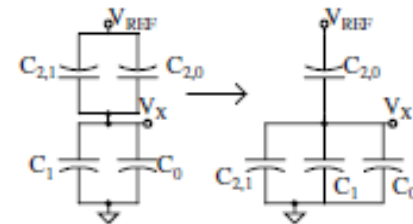
There are other ways to perform “down” transitions:



Charge sharing: $E = 7C_0 V_{ref}^2 / 12$



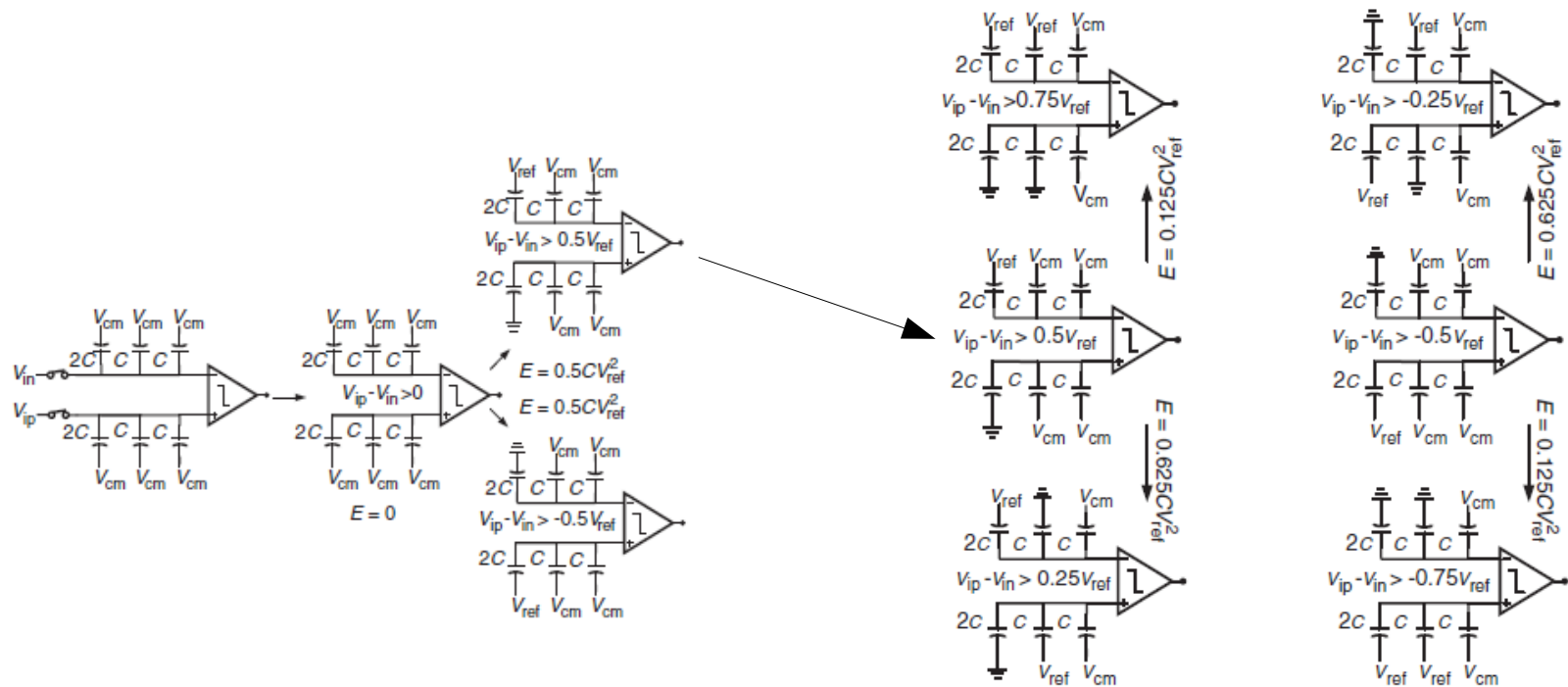
Split capacitor: $E = C_0 V_{ref}^2 / 4$



Switching scheme may be optimized to save power in “down” transitions!

Switching energy – more efficient configurations

Merge Capacitor Switching (MCS) SAR ADC



Switching energy ~93% less than conventional SAR ADC

Such switching scheme is used in our present design